

# Experimental characterization of cyclic behaviour of pure lead: temperature sensitivity and strain-rate effects

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## Abstract

Proton beam pulses with an energy of 20 GeV/c collide with a pure-lead based target installed in the neutron Time-Of-Flight facility (n\_TOF) at the European Laboratory for Particle Physics (CERN). The interaction between the proton beam and lead produces neutrons via *spallation* mechanism and results in a rapid temperature increase and propagation of stress waves. To evaluate the material response in such challenging conditions, a reliable thermo-mechanical characterization is necessary for the calibration of an appropriate constitutive model for pure lead that is valid under cyclic plasticity and high temperature. In this work, the experimental bases for the development of such constitutive material description are laid. Starting with metallurgical characterization, the typical grain size of the material was initially investigated as well as any variations in the metallurgical features. The grains appeared to have an equivalent size ranging from 2 to 6  $\mu\text{m}$ . Then, static tensile tests were conducted at room temperature and different strain-rates from  $10^{-1}$  to  $10^{-4}$   $\text{s}^{-1}$ . The obtained results were crucial for optimizing the specimen geometry and test setup for the subsequent cyclic tests. Tension-compression cyclic tests were performed at different strain amplitudes from 0.1 to 1.5%, and at three different temperatures (room temperature, 90°C and 150°C). The strain amplitudes were controlled by an extensometer and the strain field evolution during the test was recorded by means of 2D DIC.

## Keywords

Pure lead; creep; cyclic deformation; Time-Of-Flight facility target.

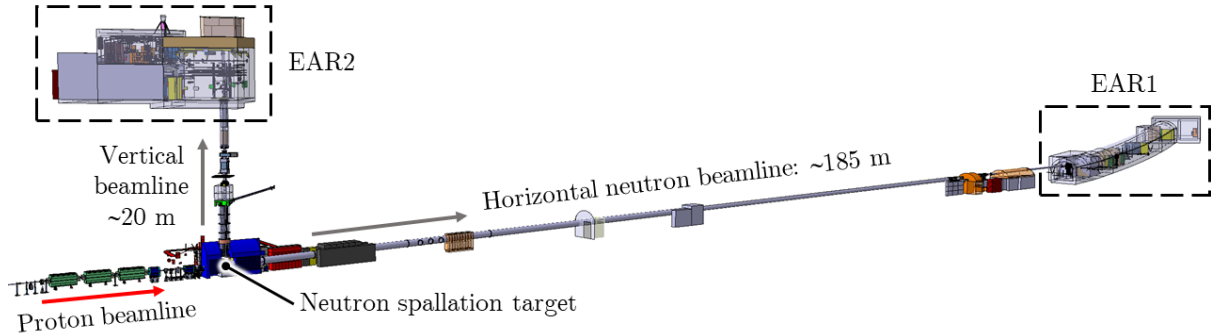
## 1. Introduction

The characterization of cyclic behaviour of pure lead presented in this paper has been carried out to better understand the thermo-mechanical behaviour of the neutron spallation target installed in the neutron Time-Of-Flight facility (n\_TOF) at the European Laboratory for Particle Physics (CERN). The n\_TOF facility is a neutron source capable of providing high-intensity neutron pulses for neutron cross-section measurements based on the time-of-flight method (Gunsing et al. 2017). An overview of the facility is shown in Fig. 1 (Esposito, Calviani et al. 2021). Proton beam pulses with an energy of 20 GeV/c are extracted from the Proton Synchrotron accelerator ring at CERN and collide with a pure-lead based target. The interaction between beam and target produces neutrons via *spallation* mechanism

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39 (Colonna, Gusing, and Käppeler 2018). On average, each proton produces 300 neutrons (Mingrone  
40 2016). The neutrons travel toward two experimental areas where samples and detectors for neutron-  
41 induced reaction measurements are installed. The measurements performed at n\_TOF are important for  
42 a wide range of applications in nuclear physics, nuclear technology, astrophysics, and medicine  
43 (Chiaveri et al. 2020).



45 *Fig. 1: Overview of the n\_TOF facility at CERN. A 20-GeV/c proton beam impacts a pure-lead target providing*  
46 *neutrons via spallation mechanism to the two experimental areas EAR1 and EAR2 (Esposito, Calviani et al. 2021).*

47 The definition of a reliable design for the neutron spallation target requires a good understanding and a  
48 reliable characterization of its thermo-mechanical response when impacted by proton beam. Each  
49 proton pulse can have up to  $10^{13}$  protons at 20 GeV/c and impacts the target with a minimum period of  
50 1.2 s. During the interaction, about half of the energy of a single proton pulse (up to 32 kJ) dissipates  
51 in form of heat in the target in only 25 ns. This provokes, inside the pure-lead target, a rapid temperature  
52 increase and consequent thermal expansion that leads to violent dynamic phenomena with propagation  
53 of stress waves. The temperature spike is followed by fast thermal diffusion and rapid cooling. The  
54 high-purity lead in the target works in the elastic-plastic regime when subjected to the stress field due  
55 to the evolution of thermal gradients and propagation of stress waves. The choice of high purity lead  
56 (>99.98%) as spallation material is dictated by physics requirements related to the neutron production.  
57 The periodic character of the proton beam impacts, the thermal cycles, and the passage of stress waves  
58 induce a cyclic loading on pure lead in the elastic-plastic regime. The evolution of temperature and  
59 stress in the target can be estimated by Finite Element Model (FEM) simulations, for which an  
60 appropriate constitutive model of pure lead valid in cyclic plasticity conditions is required. To define a  
61 reliable constitutive model, experimental stress-strain curves under cyclic loading are needed. However,  
62 cyclic stress-strain curves of pure lead for different values of strain-range amplitude, temperature, and  
63 strain-rate are not available in the literature.

64 Pure lead has a melting point of 600 K, which means that diffusional mechanisms are active even at  
65 room temperature. The material is therefore prone to recrystallization phenomena already at moderate  
66 temperatures and will permanently deform due to creep mechanisms when subjected to shear stress  
67 during application. The good formability, the resistance of lead to external agents, and its high density,  
68 have made this the material of choice for specific applications in various fields born, or highly  
69 developed, in the last century. Lead is in fact broadly used as water barrier for subsea high voltage  
70 power cables, as solder material in the electronics industry, and as radiation (photon) shielding in the  
71 nuclear and medical industries.

72 The study of the phenomenon of creep is of utmost importance to enable an accurate description and  
73 prediction of the mechanical response of this material to monotonic and cyclic external loads and of the  
74 consequent damage mechanisms. The term creep refers to the permanent, time-dependent deformation  
75 of a metal that occurs when sufficient temperature and stress are present. Depending on the temperature

76 and stress (or strain rate) levels, the phenomenon might be dominated by diffusion or dislocation glide  
77 and climb. Under cyclic loading, the weakening of grain boundaries and the increased amount of plastic  
78 deformation may reduce the number of loading cycles required to initiate damage, which generally  
79 occurs at the grain boundaries for elevated temperatures, and then propagates at faster rate than in the  
80 absence of creep. To assess the structural integrity of components under creep deformation and damage,  
81 it is therefore necessary to account for the impact of this phenomenon with opportune modelling tools  
82 (Kassner 2015; Takahashi 2009; Viespoli and Berto 2019; Wu, Yang, and Zhao 2020).

83 In addition, the creep response impacts the apparent elastic modulus of the material and the flow stress  
84 reached to impose a certain strain rate (Lall et al. 2016; Motalab et al. 2012; Pang et al. 1998).

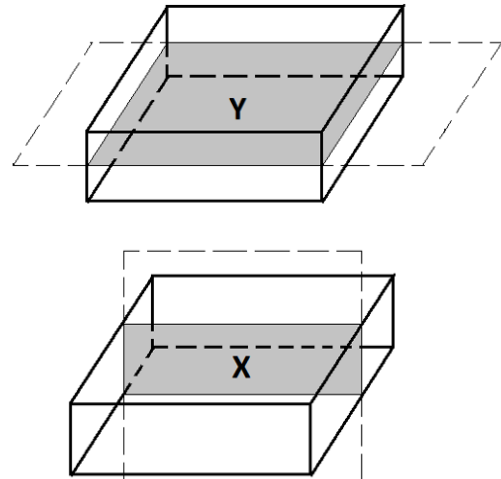
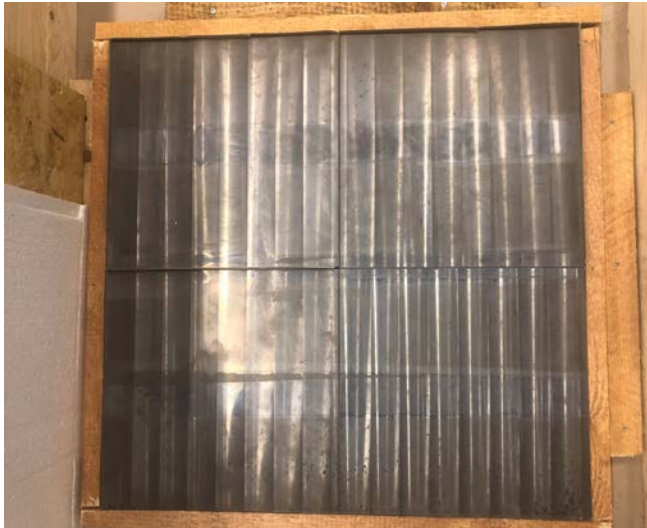
85 It is known that grain size affects the response of a polycrystalline metal lattice in presence of diffusional  
86 creep, with bigger grains reducing the detrimental effect of grain boundaries with respect to creep  
87 induced damage (Kassner and Pérez-Prado 2000; Mohamed and Langdon 1974).

88 The strength of lead-based alloys has been investigated in the cable industry to estimate the lifetime of  
89 the lead sheathing necessary to ensure electrical insulation from water impregnation; characterizing the  
90 behaviour of lead alloys under both monotonic and cyclic loads is critical for this purpose. However,  
91 being these studies strongly tied to a specific field/application, the available research on the subject in  
92 terms of alloys investigated, experimental procedures, and characterization techniques is limited and  
93 largely outdated, dating back several decades (Anelli, Donazzi, and Lawson 1988; Dollins and Betzer  
94 1956; Feltham 1956; Harvard 1972; Linul et al. 2017; Moore and Alleman 1932; Sahota and Riddington  
95 2000). In recent years, however, with the growing need for interconnection of national electrical grids,  
96 renewed interest in the energy sector has led to the development of new studies focusing on the  
97 mechanical response of lead accounting for factors such as microstructure, production defects, and  
98 loading type. These studies encompass investigations performed at the microstructural, macrostructural,  
99 and full-component levels (Johanson et al. 2018, 2019; Moreno et al. 2021; Viespoli, Johanson, Alvaro,  
100 Nyhus, and Berto 2019; Viespoli, Johanson, Alvaro, Nyhus, Sommacal, et al. 2019; Viespoli et al. 2019;  
101 Viespoli et al. 2020, 2021; Wan et al. 2020).

## 102 **2. Materials and methods**

### 103 **2.1. Materials**

104 The material investigated in this study is high-purity lead (purity level >99.99%) provided by Metall-  
105 Technik Halsbrücke GmbH & Co. (MTH) in the form of four cast blocks of 300 mm × 300 mm × 50mm  
106 each (see Fig. 2). Based on the authors' previous experience with lead alloys (Johanson et al. 2018,  
107 2019; Moreno et al. 2021; Viespoli, Johanson, Alvaro, Nyhus, and Berto 2019; Viespoli, Johanson,  
108 Alvaro, Nyhus, Sommacal, et al. 2019; Viespoli et al. 2019; Viespoli et al. 2020, 2021; Wan et al. 2020),  
109 and due to the low melting temperature and yield point of lead, its microstructure is prone to changes  
110 even under small loads and moderate temperature variations. This, in turn, may affect both the material  
111 monotonic and cyclic response. To evaluate the suitability of the material preparation and machining  
112 procedure, metallurgical investigation trials were performed both on as-received and heat-treated  
113 (150°C for 2 hours) specimens.

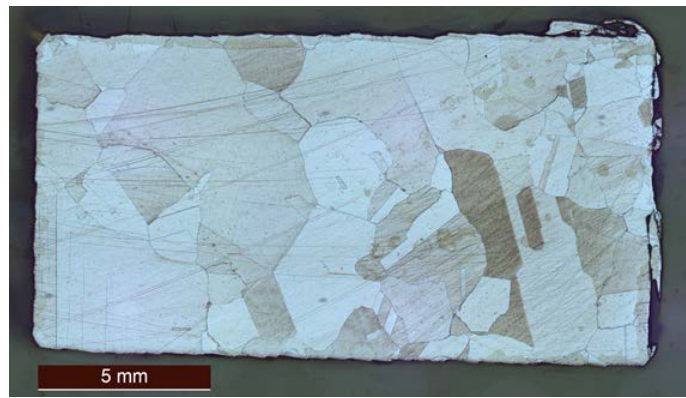


114 Fig. 2: Left: as-received cast blocks of pure lead; right: schematics indicating the planes of reference for the  
 115 microstructural characterization.

116 Fig. 3 presents the results of these trials: the as-received specimen featured bigger grains than those  
 117 observed on the heat treated one, as expected due to the activation of the recrystallization process  
 118 induced by the heat treatment. This indicates that the preparation procedure was suitable for revealing  
 119 the real metallurgical structure of lead. Additionally, the lack of grain size variation along the  
 120 specimen's edges suggests that also the machining of the specimens via Electron Discharge Machining  
 121 (EDM) does not significantly affect the microstructure.



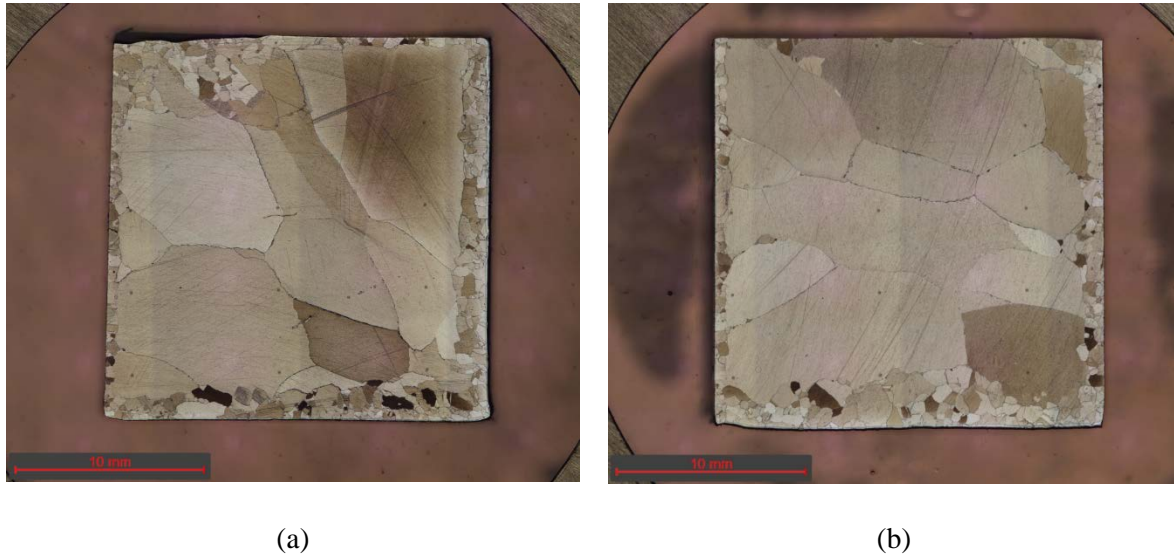
(a)



(b)

122 Fig. 3: Results of metallurgical investigation trials performed on: a) as-received specimen; b) heat-treated  
 123 specimen.

124 Once the suitability of the specimen preparation and machining procedure was confirmed, the cast  
 125 blocks of pure lead were examined in different orientations and positions, as shown in Fig. 2. The  
 126 macrographs resulting from examining the as-received block in the two different orientations shown in  
 127 Fig. 2 (from top of the block and side of the block) are reported in Fig. 4. No significant difference in  
 128 grain size or morphology can be observed with respect to the orientations. However, the edges of the  
 129 two specimens revealed smaller grains, likely due to the conditions the material was exposed to during  
 130 transportation and storage.



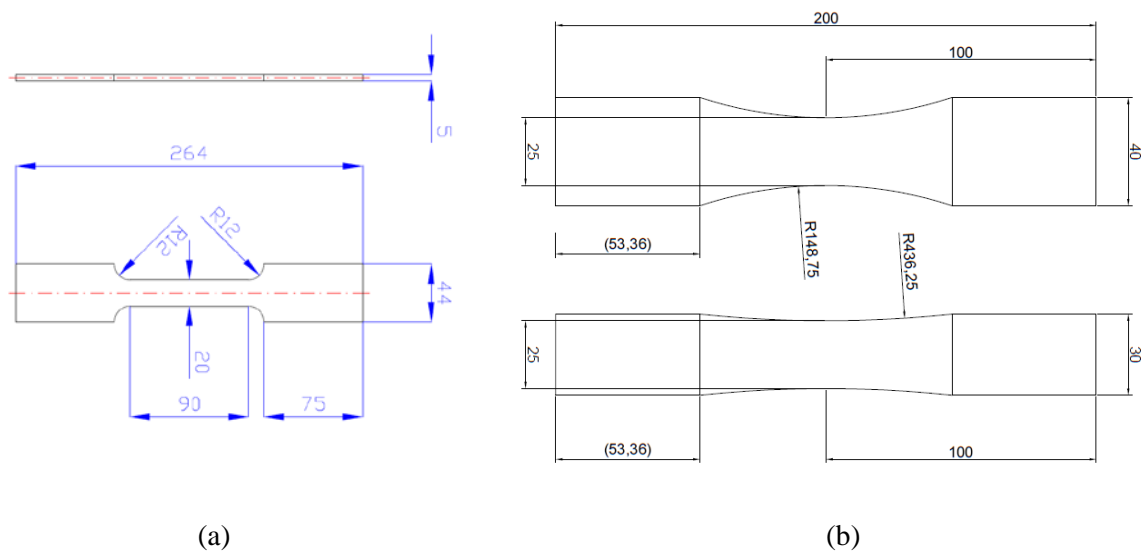
131 Fig. 4: Metallurgy of as-received cast blocks of pure lead performed on: a) orientation X; b) orientation Y (refer  
 132 to Fig. 2).

133 **2.2. Mechanical testing**

134 Even though the main goal of the experimental campaign is to characterize the material's cyclic  
 135 behaviour under different temperature and strain rate conditions, a first round of monotonic tensile  
 136 testing was conducted to gain valuable insights regarding suitable dimensions for the test specimen  
 137 design.

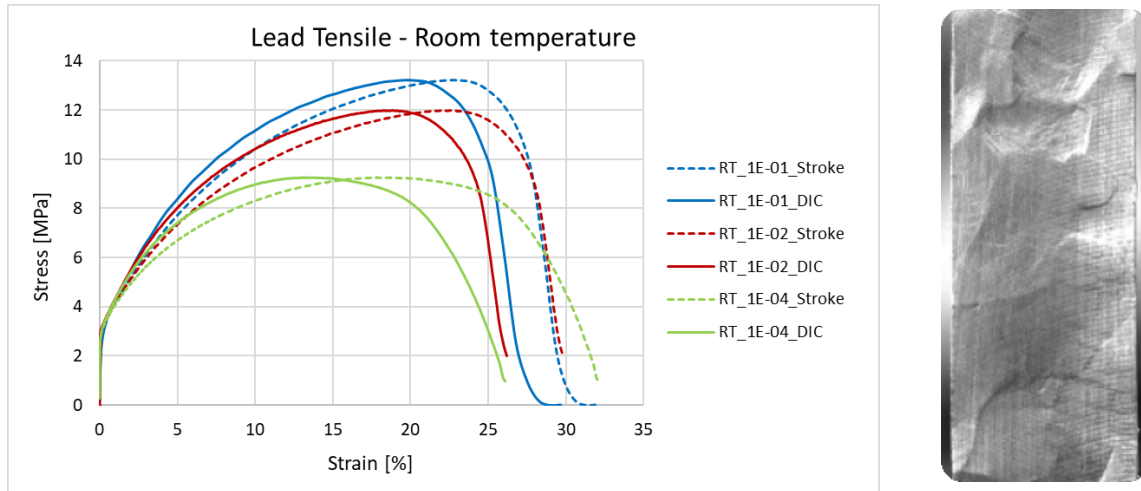
138 *Monotonic tensile testing*

139 Since no standards or common practice are available in literature regarding mechanical testing of pure  
 140 lead, a first exploratory round of static tensile tests was performed using the geometry shown in Fig.  
 141 5(a) to determine the best setup parameters. The tests were conducted at room temperature (20°C) under  
 142 displacement control and the strain-rate was varied from  $10^{-1}$  to  $10^{-4}$  s $^{-1}$ .



143 Fig. 5: Specimen geometries used for mechanical testing (dimensions in mm): (a) thin specimen according to NS-  
 144 EN-ISO 6892-1:2016 and (b) square section specimen adopted for cyclic testing.

145 The displacement was also measured by DIC (Digital Image Correlation) and compared with the  
146 machine's stroke output (see Fig. 6). Based on the results of the metallurgical characterization, which  
147 showed a grain size ranging from 2 to 5 mm and the observation of the "orange peeling effect" from the  
148 tensile testing performed on the specimen shown in Fig. 5(a), it was deemed necessary to use a new  
149 specimen geometry to ensure the validity of the results. Fig. 5(b) shows the design and the relevant  
150 dimensions of the specimen used for the cyclic testing of the material.



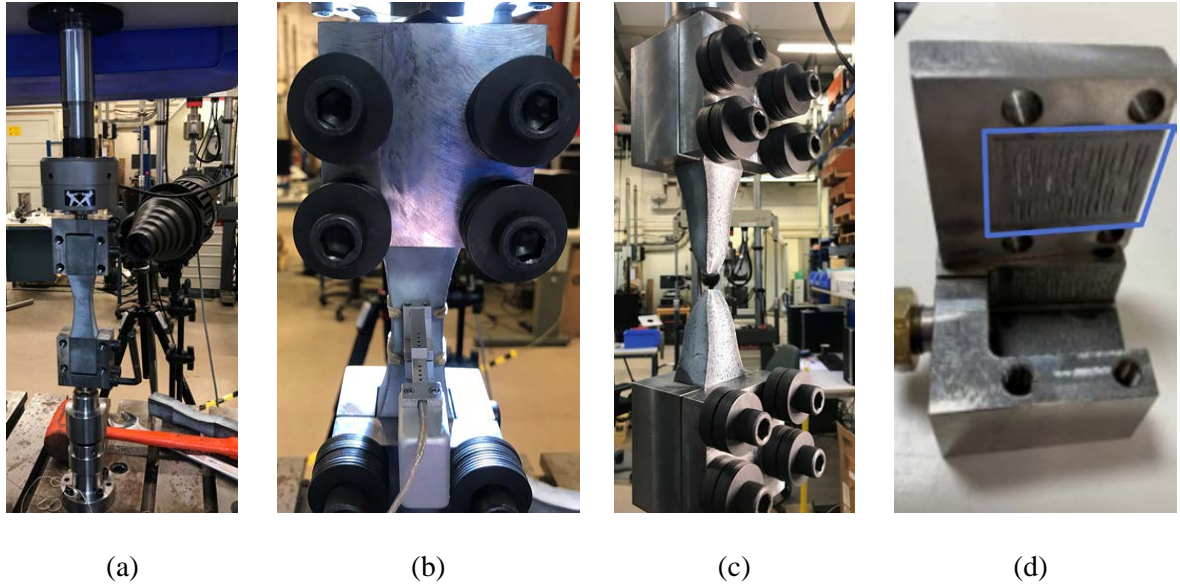
151 *Fig. 6: Stress-strain curves of pure lead at room temperature and different strain rates obtained by measuring*  
152 *both machine stroke and DIC. "Orange peel" effect due to the grain "protrusion" from the specimen surface is*  
153 *also clearly visible on the longitudinal view of the specimen.*

#### 154 *Cyclic testing*

155 All the mechanical cyclic tests were performed in a 25-kN servo-hydraulic test machine from Dartec  
156 under strain control by using a 25-mm MTS extensometer attached directly to the specimen's surface.  
157 Cyclic mechanical testing of pure lead presents peculiar challenges, particularly when it comes to  
158 gripping: due to its low melting temperature, high ductility and creep tendency, the material is strongly  
159 prone to slip when gripped and such behaviour is accentuated as the testing temperature increases. To  
160 address this, special grips were designed for the cyclic testing. The grips were equipped with four M12  
161 bolts per side, and a set of Belleville washers was compressed by each bolt to ensure constant gripping  
162 load even in case of a significant amount of material relaxation. In addition, grooves oriented  
163 perpendicular to the loading direction were dug on the inner grip surface to increase friction between  
164 the grips' inner surface and the specimen gripping area. Test set-up, including pictures of the grips, are  
165 shown in Fig. 7.

166 The extensometer provided real-time feedback to the test machine so that a constant strain rate could  
167 be maintained and the target value for a given maximum strain amplitude could be reliably reached.  
168 Additionally, the sine wave frequency was automatically adjusted by the machine based on the  
169 extensometer recording to maintain the target strain rate for different imposed strain ranges.  
170 Furthermore, an in-house DIC system with a 5 MPixel Prosilica camera was used to obtain second  
171 feedback on the strain development, both in the gauge between the extensometer knives and at other  
172 possible locations of interest on the specimens' surface.





173 *Fig. 7: (a) Overview of test set-up, including DIC camera; (b) and (c) close-up on the specimen with extensometer*  
 174 *and on the gripping system and specimen after failure; (d) picture showing grooves engraved inside the grips for*  
 175 *an improved gripping.*

176 Cyclic testing was performed at various fixed maximum strain amplitudes imposed in both an increasing  
 177 and decreasing stepwise sequence and for three different temperatures, as summarized in Table 1. Thirty  
 178 cycles were imposed for each  $\Delta\varepsilon$  level. Additionally, a final relaxation stage was implemented for tests  
 179 2, 3, 4, 5, 1T, 2T, 3T and 4T.

180 *Table 1. Test matrix for cyclic tests*

Test ID	1	2	3	4	5	6	1T	2T	3T	4T
Strain-rate [ $s^{-1}$ ]	$10^{-2}$	$10^{-3}$	$10^{-1}$	$10^{-1}$	$10^{-2}$	$10^{-1}$	$10^{-2}$	$10^{-2}$	$10^{-1}$	$10^{-1}$
Temperature [ $^{\circ}C$ ]	20	20	20	20	20	20	90	150	90	150
Strain amplitudes $\Delta\varepsilon/2$	$\pm 0.1$	$\pm 0.1$	-	-	$\pm 0.1$	$\pm 1.5$	$\pm 0.1$	$\pm 0.1$	-	-
	$\pm 0.2$	$\pm 0.2$	$\pm 0.2$	-	$\pm 0.2$	$\pm 1$	$\pm 0.2$	$\pm 0.2$	-	-
	$\pm 0.5$	$\pm 0.5$	$\pm 0.5$	$\pm 0.5$	$\pm 0.5$	$\pm 0.5$	$\pm 0.5$	$\pm 0.5$	$\pm 0.5$	$\pm 0.5$
	[%]	$\pm 1$	$\pm 1$	$\pm 1$	$\pm 1$	$\pm 1$	$\pm 0.2$	$\pm 1$	$\pm 1$	$\pm 1$
	$\pm 1.5$	$\pm 1.5$	$\pm 1.5$	$\pm 1.5$	$\pm 1.5$	$\pm 0.1$	$\pm 1.5$	$\pm 1.5$	$\pm 1.5$	$\pm 1.5$
Holding time [hh:mm:ss]	-	13:58:00	00:25:23	14:13:52	15:06:00	-	00:43:49	00:21:00	00:21:12	00:19:23

181

### 182 3. Experimental results

183 The typical set of data captured by the extensometer in each cyclic test is shown in Fig. 8. Fig. 8a  
 184 illustrates an example of nominal strain - time history imposed by the machine on the length of specimen  
 185 comprised between the two extensometer's blades. The time derivative of such signal yields the nominal  
 186 strain rate imposed on the specimen volume, which is plotted against time in Fig. 8b. Despite the noise,  
 187 the target nominal strain rate value ( $10^{-2} s^{-1}$  in the case shown in Fig. 8) is clearly obtained and  
 188 maintained throughout the entire test. The strain rate oscillates from positive to negative according to

189 the machine's crosshead direction of motion. Figure 8c finally shows the corresponding stress-strain  
 190 curve as recorded by the system. Several effects related to the ductile behaviour of lead can be observed  
 191 in the hysteresis curves: as the strain amplitude increases, the plastic component of deformation  
 192 gradually becomes more relevant and shows evidence of Bauschinger effect. At lower strain amplitudes  
 193 ( $\Delta\varepsilon < 1\%$ ), a degree of strain hardening is detected. The magnitude of cyclic hardening decreases for  
 194 each subsequent cycle until reaching saturation within the 30 cycles imposed for each strain level. The  
 195 saturation of cyclic hardening is reached for a stress value that increases with the strain amplitude. For  
 196  $\Delta\varepsilon \geq 1\%$ , this effect reaches a plateau, and the peak stress does not increase further with increasing  
 197 strain amplitude.

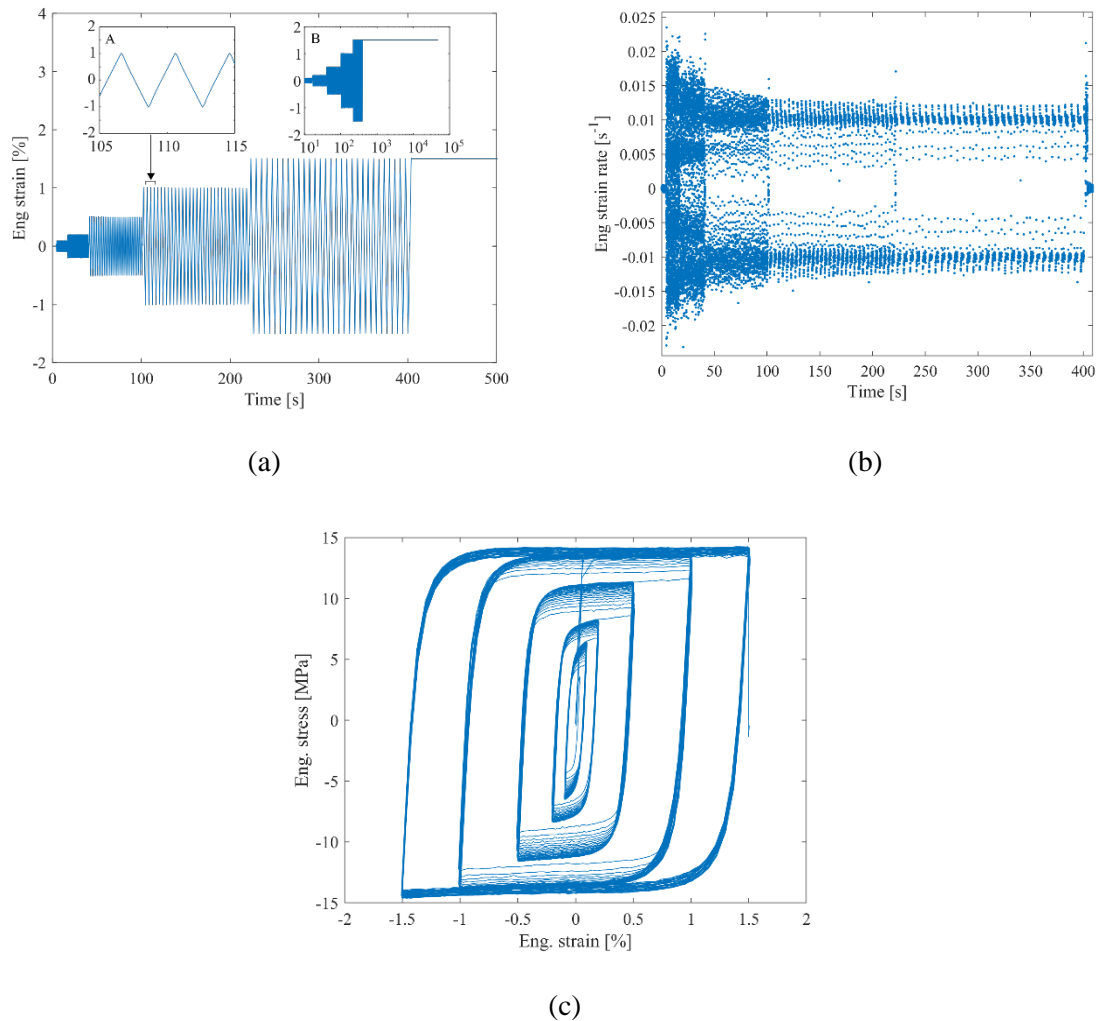


Fig. 8. Output curves for test 5:(a) extensometer strain vs time history: inset A shows a detailed view of 3 cycles with  $\Delta\varepsilon/2 = 1\%$ , and inset B shows the whole history in semi-log coordinates including the final relaxation stage; (b) engineering strain rate vs time; (c) engineering stress vs engineering strain.

198 In addition, the recorded pictures of the specimen surface were analysed with 2D DIC to gain greater  
 199 insight into the local strain variations during the test. Strain histories were extracted from virtual  
 200 extensometers of different lengths passing both inside and across the gauge length (Figure 9a-b). The  
 201 strain evolution from the three shortest extensometers shows a positive drift of the average deformation,  
 202 i.e., an elongation of the central section of the sample. Additionally, the strain range in this section  
 203 appears to be greater than the one measured by the extensometer, while the strain range obtained through  
 204 DIC and measured by the longest vectors is slightly smaller. The drift in the mean stress levels obtained



205 by the DIC measurements is likely due to progressive bending of the specimen caused by  
 206 inhomogeneous material flow during the cyclic deformation. Such inhomogeneities in the strain  
 207 distribution along the specimen's longitudinal coordinate shall be accounted for in post-processing the  
 208 results for material model calibration.

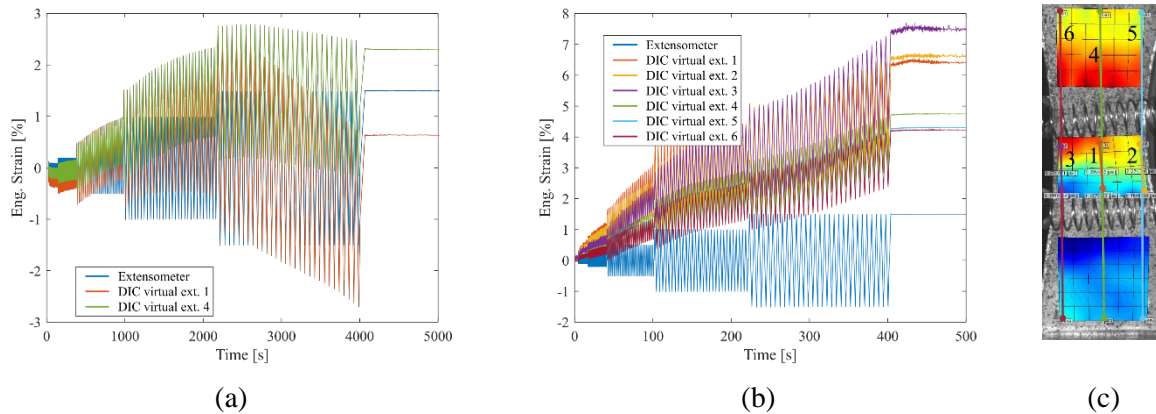


Fig. 9: DIC and extensometer strains: (a) test 2 and (b) test 1T. (c) The strains were calculated from the length variation of six vectors placed longitudinally along the specimen surface. Short vectors 1,2, and 3 measured the displacement within the gauge length, long vectors 4,5, and 6 measured the largest displacement available from the images. The areas occupied by the extensometer were not included in the analysis.

209 Fig. 10a-b shows some examples of the hysteresis cycles obtained at fixed strain rate and varying  
 210 temperatures. For a given temperature, increasing the nominal strain rate from  $10^{-2}$  to  $10^{-1} \text{ s}^{-1}$  always  
 211 results in a stress level increase, at least within this strain rate range. However, it must be pointed out  
 212 that for the tests at room temperature, creep deformation mechanisms are active but less relevant than  
 213 at higher temperature. Observing Fig. 10a-b we can see how the stress change from one strain rate to  
 214 the other is relatively greater at the higher temperature levels. Analogously, the impact of testing  
 215 temperature is more prominent at lower strain rates: a single cycle allows more time for creep  
 216 deformation mechanisms to act, mechanisms that are subjected to even greater activation as the  
 217 temperature is raised. In Fig. 10c the peak stresses were reported against the number of cycles. Clearly,  
 218 for all the tests with increasing  $\Delta\epsilon$ , the peak stresses reached a stabilized value before 15 – 20 cycles.  
 219 Fig. 10d, with the help of Fig. 10c (dashed black line), shows the hysteresis cycles for a test in which  
 220 the stepwise application of the target strain amplitude levels is applied in a decreasing order (test 6).  
 221 While the initial loading cycles clearly show cyclic hardening, the convergence to a stabilized stress is  
 222 approached by cyclic softening at every reduction of strain amplitude. The latter appears also faster than  
 223 the convergence under increasing strain amplitudes and cyclic hardening.

224 In Figure 11, the stress is reported against the relaxation time where the strain is held constant at the  
 225 maximum value of the last cycle. The time needed to recover the stress at 20% and 10% of the initial  
 226 maximum load are reported in the side table of Figure 11. In general, tests performed at room  
 227 temperature show a much slower recovery than tests executed at high temperatures. However, at least  
 228 in the first stages of recovery, a faster decrease is observed for tests at higher strain-rates. Note, for  
 229 example, that in test 5 ( $10^{-1} \text{ s}^{-1}$ ), 80% of the initial load is recovered in 22.14 s, which is much faster  
 230 than in tests 2 and 4. However, it then experiences a milder descent and slows down until reaching 10%  
 231 of the maximum load in 370 s. Similarly, the higher strain-rate tests 3T and 4T recover faster down to  
 232 20% of the maximum load but then markedly slow down the recovery.

233 A non-monotonic regime appears when the stress is almost recovered, especially at high temperature.  
 234 The stress also decreases below zero, probably as a result of residual stress from the previous cyclic  
 235 history.

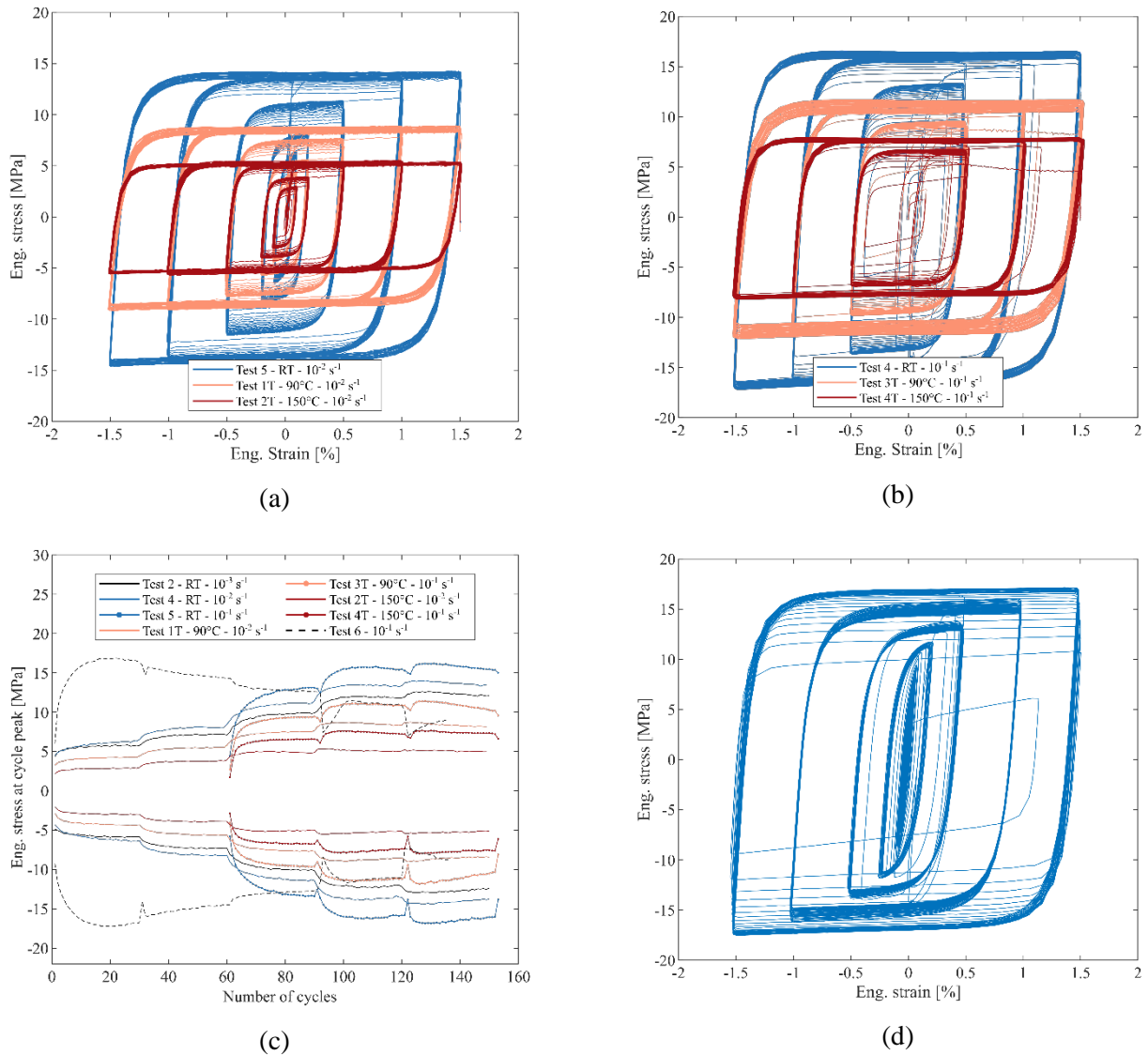
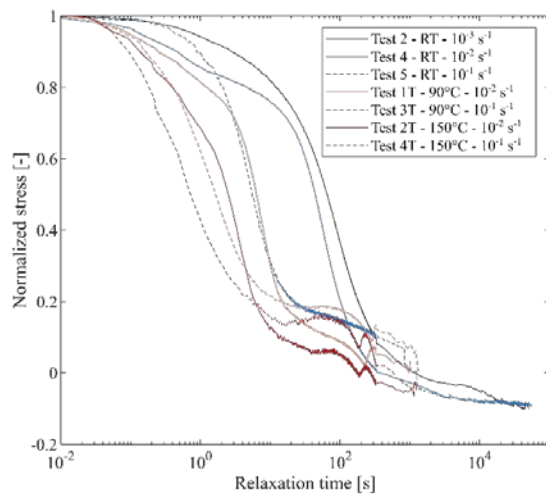


Figure 10. Stress vs extensometer strain curves at room temperature (RT),  $90^\circ\text{C}$ , and  $150^\circ\text{C}$ . (a) Strain-rate =  $10^{-2} \text{ s}^{-1}$ . (b) Strain-rate =  $10^{-1} \text{ s}^{-1}$ . (c) The peak stress at each cycle is reported against number of cycles. The plots of tests 5, 3T, and 4T have been shifted to visually match the strain amplitude levels. (d) Stress vs extensometer strain curves for test 6 with decreasing strain amplitudes.



Test id.	Recovery time [s] for 20% of max. load	Recovery time [s] for 10% of max. load
2	181.01	316.812
4	101.27	154.155
5	122.139	370.021
1T	15.071	67.971
3T	12.867	258.78
2T	5.963	12.88
4T	5.166	148.92

Figure 11. Stress relaxation tests. The engineering stress at constant strain is reported against time in semi-logarithmic coordinates. The curves have been shifted so that the zero-time is immediately following the last cycle. On the side, the values of recovery time at specific load levels extracted from the plot.

237

## 238 Conclusion

239 The present work is focused on the characterization of the mechanical response of cast high-purity lead  
 240 under cyclic loading at various temperatures and strain rates. The main conclusions can be summarized  
 241 as follows:

- 242 • The initial metallographic investigation revealed that the grains of the as-received material  
 243 appear to have an equivalent size ranging from 2 to 6 mm. Due to the large grain size observed  
 244 and the dimension of the typical cross-section used in the analysis, it is not possible to provide  
 245 a reliable quantitative estimate. No grain size directional dependency emerged with respect to  
 246 the section plane,
- 247 • The sample subjected to heat treatment, that is exposed to 150°C for 2 hours, exhibited a  
 248 reduction in the average grain size, due to recrystallization, when compared to the as-received  
 249 sample,
- 250 • The preliminary series of tensile tests performed on dog-bone specimens with a gauge cross  
 251 section of 20×5 mm<sup>2</sup> showed a significant reduction in ultimate stress as the testing strain rate  
 252 decreased. However, the strong influence of the free surface on the given material, visualized  
 253 by the "orange peel" effect, demonstrated the unreliability of the initial specimens' design and  
 254 led to maximize the cross-section for the subsequent cyclic characterization,
- 255 • Cyclic tests were performed imposing a sequence of strain amplitude levels at three different  
 256 temperatures i.e., 20°C, 90°C and 150°C, and nominal strain rates between 10<sup>-3</sup> and 10<sup>-1</sup> s<sup>-1</sup>.  
 257 The strain was controlled through an extensometer and, additionally, the tests were recorded by  
 258 a DIC system. It was observed that for a given strain amplitude, the stress amplitude is reduced  
 259 at higher temperature. Such effect is amplified at lower strain rate, most probably because of  
 260 the longer deformation time allowing for more diffusion and/or dislocation climb (depending  
 261 on the dominant creep mechanism) to take place. After changing between two strain levels, the  
 262 hysteresis cycle stabilizes in a few hardening cycles and reaches strain history-independent  
 263 levels whose magnitude is related to the imposed strain amplitude.

264 The results obtained in this work will serve as foundation for calibrating appropriate cyclic material  
265 models that take into account the impact of cyclic hardening, strain memory, and creep effects (Esposito  
266 2022).

267

#### 268 **Data availability**

269 Data will be made available on request.

#### 270 **Acknowledgements**

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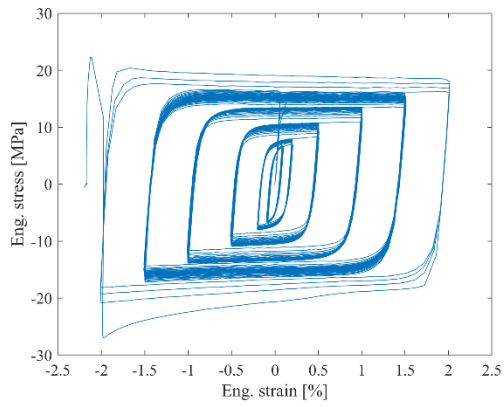
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## Appendix A

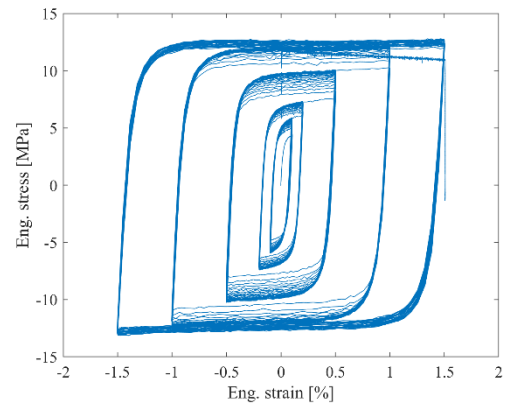
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### Room temperature tests data

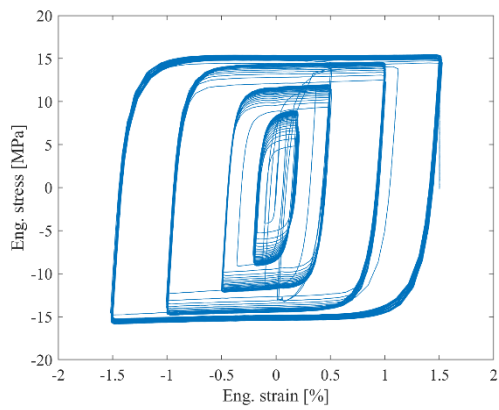
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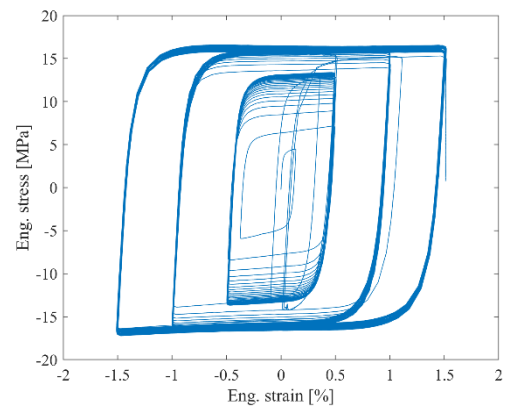
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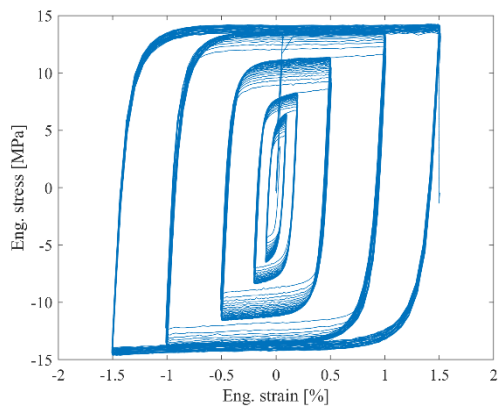
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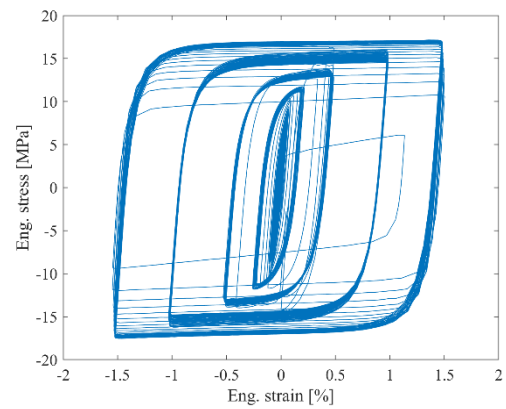
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Test 5 ( $10^{-2} \text{ s}^{-1}$ ,  $20^\circ\text{C}$ )



Test 6 ( $10^{-1} \text{ s}^{-1}$ ,  $20^\circ\text{C}$ )



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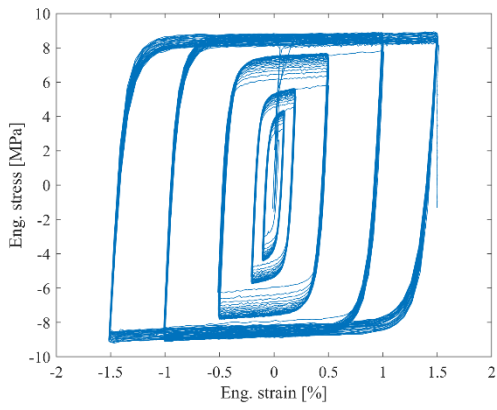
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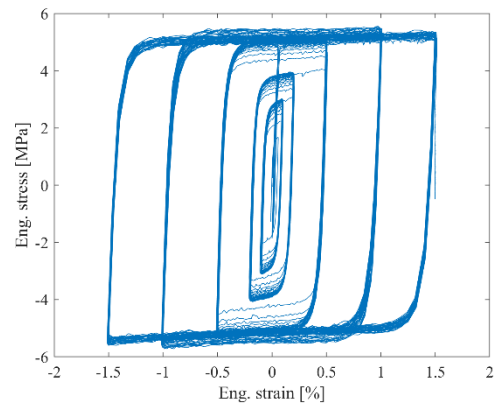
### Appendix B

#### High temperature tests data

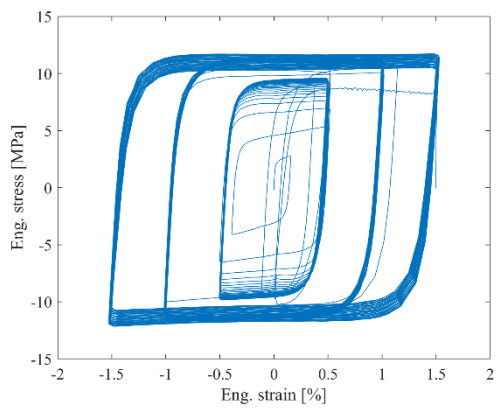
Test 1T ( $10^{-2} \text{ s}^{-1}$ ,  $90^\circ\text{C}$ )



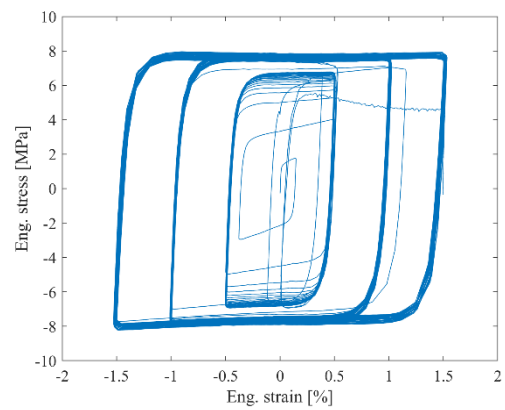
Test 2T ( $10^{-2} \text{ s}^{-1}$ ,  $150^\circ\text{C}$ )



Test 3T ( $10^{-1} \text{ s}^{-1}$ ,  $90^\circ\text{C}$ )



Test 4T ( $10^{-1} \text{ s}^{-1}$ ,  $150^\circ\text{C}$ )



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