

Numerical/experimental impact events on filament wound composite pressure vessel

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Abstract

Impacts on pressure vessels, produced by winding glass fibre with vinyl ester resin over a polyethylene liner, were numerically and experimentally investigated in the current work.

Pressure vessels were experimentally tested under low velocity impact loads. Different locations and incident energies were tested in order to evaluate the induced damage and the capability of the developed numerical model.

An advanced 3-D FE model was used for simulating the impact events. It is based on the combined use of interlaminar and intralaminar damage models. Puck and Hashin failure theories were used to evaluate the intralaminar damages (matrix cracking and fibre failure). Cohesive zone theory, by mean of cohesive elements, was used for modelling delamination onset and propagation.

The experimental impact curves were accurately predicted by the numerical model for the different impact locations and energies. The overall damages, both intralaminar and interlaminar, were instead slightly over predicted for all the configurations.

The model capabilities to simulate the low velocity impact events on the full scale composite structures were proved.

Keywords: *B. Impact behaviour, C. Finite element analysis (FEA), D. Mechanical testing, E. Filament winding,*

1. Introduction

Composite materials are becoming more and more attractive for several different applications mainly due to the corrosion properties and weight saving capabilities. Nowadays a very popular commercial application of composite is represented by pressure vessel.

In the last decades, filament winding composites (both carbon and glass fibre) have been progressively replacing metal for pressurized vessels [1] in both high tech and commercial applications. The increasing use of composite, coupled with the design complexly of such material, is increasing the demand of specialized tools capable to simulate the structural behaviour of these components reducing the necessity of expensive tests.

For pressure vessel, one of the most critical safety issues is the failure induced by low velocity impact of foreign objects (always happening during the production and/or in the service life). These events can severely affect the structural integrity leading to dangerous situations. According to the standard EN 14427 [2], the ability of the vessel design to withstand loadings other than internal pressure need to be demonstrated by a series of experimental impact/dropping tests. These need to be performed on both the cylindrical and the dome section of the vessel in order to verify the most critical part of the structure. This is one of the most severe design requirements that need to be fulfilled for their commercialization. In this

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1 scenario, the availability of numerical tools capable of properly simulate the impact event can reduce the
2 experimental costs during the design phase. Even more, the composite layup/constituents and more
3 generally the complete vessel design can be simply numerically optimized in order to fulfil the same safety
4 requirements but reducing the production cost (high benefit considering the amount of produced units).

5 The effect of impact on filament wound structures is still not well understood and even more its numerical
6 simulation is extremely complicated. A first numerical investigation was conducted by Changliang et al. [3]
7 where 3D finite element (FE) model was used to evaluate the impact induced damage on metal liner
8 composite vessel. Parametric analyses, varying the incident energy and the internal pressure, were
9 carried out. Matrix cracking and delamination were evaluated by the use of Chang and Chang criteria [4].
10 Even if the results were consistent with the physical behaviour, the model accuracy was not verified
11 against experimental data.

12 There is more available literature concerning the impact on filament wound composite structures (not
13 specifically for pressure vessel). Alderson and Evans [5, 6] compared the damage induced by an impact
14 event against simple static tests on thin filament wounded E-Glass/Epoxy tubes with a $\pm 55^\circ$ winding angle.
15 They observed that the first modes of damage were always delamination and local crushing, just like for
16 carbon composites [7]. Geometrical effects, such as boundary conditions and curvature are also important
17 for impact induced damage [3,4]. Christoforou et al. [8] and Curtis et al. [9] investigated the influence of
18 impact damage on the burst pressure for thin composite pipes. Both researches showed a drastic
19 reduction of the pressure resistance due to impact damage. Ozdil et al. [10] investigated the influence of
20 defects and impact damage on the external (implosion) pressure. It was shown that the damage produced
21 by low energy impact leads to a reduction of the implosion pressure. Tarfaoui et al. [11-14] carried out an
22 extensive test program, arriving at the same conclusion that the impact damage reduces considerably the
23 implosion pressure. Moreover, the same author [15] was able to predict the impact curves with good
24 accuracy, using finite element model with progressive failure analysis (based on Hashin failure criterion
25 [16]). The model was not intended to predict the onset and the propagation of delamination. A more
26 complex numerical model was used by Zou et al. [17] and Li et al. [18] that investigated the impact
27 induced damage on filament wounded pipes. A progressive interlaminar approach was used, based on a
28 stress criterion for the damage onset and principles of fracture mechanics for the damage propagation.
29 The numerical predictions showed good agreement with the experimental data for both the size and the
30 shape of delaminations.

31 No numerical models (with the simultaneous evaluation of interlaminar and intralaminar damages) have
32 been used so far, to simulate the impact event/damage on filament wound component/structures.

33 In the current work several experimental impact tests were carried out on commercial filament wound
34 composite vessel with internal polyethylene liner. Different impact configurations (energy and position of
35 impact) were experimentally testes in a fully instrumented drop weight machine. All the tests were also
36 recorded by a high speed camera. The experimental tests were then accurately simulated using a
37 commercial finite element software coupled with an advanced damage model for composite material.
38 This, developed for the commercial software ABAQUS Explicit [19], was based on a combination of:
39 interlaminar (by means of the cohesive zone approach) and intralaminar models (by a combination of
40 Puck [20-22] and Hashin [16] strength based failure criteria).

2. Methodology

2.1. Pressure vessels

All the experimental/numerical tests were performed on filament wound pressure vessels. The vessels were produced with an internal polyethylene liner covered by E-Glass fibre and vinyl ester resin composite produced by filament winding.

The vessels were also equipped with an inlet/outlet brass valve for the pressurization. For safety reason, the samples were not pressurized during the impact tests; a low overpressure was anyway present (approximately 2 bar) in order to keep the proper sample's shape.

The vessels presented a height of 460mm (including the main valve), maximum diameter of 300mm (measured in the central section) and an engineering/nominal thickness varying from 1.3mm to 3.4mm (central and dome section respectively). More details about the layout orientations in the different sections of the vessel are reported in the following sections.

2.2. Material properties

The vessels were made of three distinct parts: the internal liner, the external composite shell and the main valve. In order to properly simulate the impact events, the material properties of the different parts were required.

The properties of the internal liner and the valve were provided by the material supplier and reported in Table 1. The properties of the composite were instead measured for the specific material/production process by means of a full campaign of experimental tests. Split disk [23] and biaxial [24-26] tests were carried out in order to evaluate the material moduli and strengths. The results of the material characterization are reported in the Table 1.

Currently, no test techniques are available for the evaluation of the critical fracture toughness energies (G_{Ic} , G_{IIc} and G_{IIIc}), fundamental for the evaluation of the interlaminar damage (delamination). A first attempt to evaluate these values was carried out by the author and reported in [27]. The curved double cantilever beam test technique used in [27] was not usable in the present work for the specific material. The data used here (reported in Table 1) were defined using data evaluated on similar material previously characterized.

2.3. Experimental Impact Tests

Following the general suggestion of the EN 14427 [2] standard, two different configurations were defined for the impact tests.

- **Central section:** the impact position was located in the cylindrical section of the vessel (more details in Figure 1). This section is characterized by the presence of both helical and hoop layers. The impact in this region could damage the hoop layer (fibre failure) with the consequent reduction of the maximum burst pressure of the vessel. The correct simulation of the damage in this section is fundamental to improve the vessel safety.
- **Dome section (angle of 45°):** the impact position was located on the dome section (same side of the valve) of the vessel. The samples were inclined with an angle of 45° (respect to the cylindrical axis) using a custom fixture (see Figure 1). This configuration was selected in order to evaluate the model capability to simulate the damage onset and propagation in a region where the fibre orientation is continuously varying. This results in an increase of the simulation complexity that can affect the model accuracy.

1 As reported before, for safety reason, during the impact the vessels were pressurized at approximately 2
2 bars. Further work should be done in order to evaluate the influence of the internal pressure on the
3 impact damage and the model capabilities.

4 All the tests were carried out in a full instrumented Instron CEAST 9350 drop weight machine with
5 automatic anti-rebound system. The machine was equipped with accelerometer, embedded directly in the
6 impactor, in order to measure the impact data. The data were recorded by a high frequency acquisition
7 system, CEAST DAS 64k, using a sampling rate of 1000k Hz for a total time of 20ms. All the tests were also
8 recorded with a high speed camera in order to visually evaluate the damage initiation and propagation
9 (on the external part of the vessel). A FASTCAM SA1.1 camera, at 15000 frames per second, was used. The
10 camera was triggered directly on the impactor movement by a speed sensor (placed just before the
11 impactor got in contact with the sample).

12 All tests were carried out using a spherical impactor with a diameter of 16mm and mass of 5kg that was
13 kept constant for all the tests. The mass was selected in order to use the lower weight but fulfilling the
14 energy requirements (to produce a consistent damage) without exceeding the machine capability. A set of
15 preliminary impact tests was carried out to evaluate the induced damage at several impact energies. The
16 selected energies were defined in order to produce a consistent damage (mainly matrix cracking and
17 delamination) without affecting the sealing of the vessel. This choice was done in order to produce
18 damage (similar to a dropping of a tool during the vessel handling) not noticeable by a depressurization of
19 the vessel (a leakage is simply detected). The presence of a barely visible damage (BVID) is the most
20 critical situation for the vessel safety.

21 A common problem for filament wound structures [1] is the possibility of small asymmetry of the dome
22 section (mainly generated during the placement process of the helical layers). For this reason, a
23 preliminary investigation was carried out to evaluate the influence of the impact position (at the dome
24 section along the sample circumference). The results showed a variation of approximately 10% for the
25 impact results (maximum force and total impact time) at the different impact points (four points tested).
26 The weakest area was used for all the further tests here reported.

27 A summary of all the different test configurations is given in Table 2.

28 **2.4. Damage model for composite material**

29 An advanced numerical model was developed to simulate the damage onset and development in the
30 external composite part of the vessel. The damage model, based on the combined use of Puck [20-22] and
31 Hashin [16] failure criteria, was used to evaluate the intralaminar damage (matrix cracking and fibre
32 failure). The model was implemented by a user defined subroutine to be used in the commercial FE
33 software Abaqus 6.11 [19]. The onset and propagation of interlaminar damage (delamination) was
34 evaluated by the cohesive zone model (CZM) implemented by cohesive elements.

35 More details about the damage models and their basic assumptions are reported in the following
36 paragraphs.

37 **2.4.1. Intralaminar damage model**

38 The intralaminar damage model is based on the combined used of two different strengths based failure
39 criteria. The classical Hashin criterion [16] was used for the evaluation of the fibre failure, while the
40 innovative Puck criterion [20-22] was used for the matrix cracking. The Puck criterion for fibre failure

was not used due to the complexity to measure the required material properties (more details in [20-22]). Both methods were applied on the ply level using a user defined material model coded in a VUMAT subroutine, written in FORTRAN, for Abaqus/Explicit [28]. The damage is evaluated at each integration point at each time step of the simulation for all the elements.

Hashin criterion

According to the Hashin criterion [16], the fibre failure occurs when the parameter $f_{ff} \geq 1$. f_{ff} is evaluated by equation (1) different for tension and compression loads condition:

$$f_{ff} = \begin{cases} \left(\frac{\sigma_1}{X_t}\right)^2 + \frac{1}{S_{12}^2}(\tau_{12}^2 + \tau_{13}^2) & \text{for } \sigma_1 \geq 0 \\ \left(\frac{\sigma_1}{X_c}\right)^2 & \text{for } \sigma_1 < 0 \end{cases} \quad (1)$$

where σ_1 is the stress in the direction of fibre, τ_{12} and τ_{13} are the in-plane and out-of-plane shear stresses respectively. X_t and X_c are the tension and compression strengths in the direction of the fibre. S_{12} is the in plane shear strength. More details about this failure theory can be found in [16].

Puck criterion

The Puck failure criterion [20-22] is an interactive stress-based criterion applicable for unidirectional (UD) composite lamina. The matrix failure criterion is based on the assumption that failure is created only by the stresses that act on the fracture plane (σ_n , τ_{nl} and τ_{nt}) inclined at θ_{fp} to the material plane (see Figure 2). The normal and shear stresses acting on this plane are calculated by rotating the three-dimensional stress tensor from the material coordinate system to the fracture plane using classical tensor transformations. The matrix failure is then described by an inter-fibre failure criterion (see equation 2) that is only a function of the stresses acting on the fracture plane. Failure is reached when $f_{iff} \geq 1$:

$$f_{iff} = \begin{cases} \sqrt{\left[\left(\frac{1}{R_{\perp}} - \frac{P_{\perp\psi}^+}{R_{\perp\psi}}\right)\sigma_n(\theta)\right]^2 + \left(\frac{\tau_{nt}(\theta)}{R_{\perp\perp}}\right)^2 + \left(\frac{\tau_{nl}(\theta)}{R_{\perp\parallel}}\right)^2 + \frac{P_{\perp\psi}^+}{R_{\perp\psi}}\sigma_n(\theta)} & \text{for } \sigma_n \geq 0 \\ \sqrt{\left(\frac{\tau_{nt}(\theta)}{R_{\perp\perp}}\right)^2 + \left(\frac{\tau_{nl}(\theta)}{R_{\perp\parallel}}\right)^2 + \left[\left(\frac{P_{\perp\psi}^-}{R_{\perp\psi}}\right)\sigma_n(\theta)\right]^2 + \frac{P_{\perp\psi}^-}{R_{\perp\psi}}\sigma_n(\theta)} & \text{for } \sigma_n \leq 0 \end{cases} \quad (2)$$

where R_{\perp} is the failure resistance perpendicular to the fibers, $R_{\perp\psi}$ and $R_{\perp\parallel}$ are the shear resistances, and $P_{\perp\psi}^+$ and $P_{\perp\psi}^-$ are the slope parameters representing the internal friction effects in the Mohr-Coulomb failure criterion (more details in [22]). The parameters presented before can be calculated using the following expressions:

$$\begin{aligned} \frac{P_{\perp\psi}^+}{R_{\perp\psi}} &= \frac{P_{\perp\perp}^+}{R_{\perp\perp}}(\cos \psi)^2 + \frac{P_{\perp\parallel}^+}{R_{\perp\parallel}}(\sin \psi)^2 & \frac{P_{\perp\psi}^-}{R_{\perp\psi}} &= \frac{P_{\perp\perp}^-}{R_{\perp\perp}}(\cos \psi)^2 + \frac{P_{\perp\parallel}^-}{R_{\perp\parallel}}(\sin \psi)^2 \\ (\cos \psi)^2 &= \frac{\tau_{nt}^2(\theta)}{\tau_{nt}^2(\theta) + \tau_{nl}^2(\theta)} & (\sin \psi)^2 &= \frac{\tau_{nl}^2(\theta)}{\tau_{nt}^2(\theta) + \tau_{nl}^2(\theta)} \\ R_{\perp} &= Y_t & R_{\perp\parallel} &= S_{21} & R_{\perp\perp} &= \frac{Y_c}{2(1 + P_{\perp\perp}^-)} \end{aligned} \quad (3)$$

where Y_t and Y_c are the tension and compression in-plane material strengths, respectively, in the direction perpendicular to the fibres. In addition to the standard material parameters, special Puck parameters are needed. The measurement of these parameters requires complicated multi-axial testing. However, Puck

recommends using the default parameters reported in Table 3. The default parameters were used in this study.

The damage propagation was simulated by a progressive failure analysis. When failure is predicted in a particular position of the composite, the elements of the stiffness matrix are reduced according to the failure type predicted by the failure criterion. In the case of fibre failure, all of the components of the stiffness matrix are reduced to zero. In the case of matrix cracking, only the transverse and shear components are reduced. In both cases, the out of plane component of the stiffness matrix is kept equal to the undamaged one to avoid any unnatural penetration. This degradation modelling is a simple and reasonable approach that does not need any further testing to establish properties after first damage.

2.4.2. Interlaminar damage model

The delamination initiation and propagation was simulated using the cohesive zone model (CZM) approach. The model is based on the assumption that a thin material, with a different constitutive law, is present between the different composite layers. This interface connects the different layers, and it is simulated by thin cohesive elements placed between each layer where the delamination is expected to propagate. Delamination can propagate only between differently oriented layers [29] due to the interlaminar shear stresses, and thus, the delamination path is known a priori.

The classical bi-linear traction-separation laws based on the total dissipated energies was used in the cohesive zone elements. The cohesive behaviour was defined directly in terms of a traction-separation law. The following assumptions were used for the cohesive model:

- Undamaged behaviour based on a linear elastic traction separation law
- A quadratic nominal stress criterion was used for the evaluation of the damage initiation
- Linear damage evolution law based on the total dissipated energies
- Linear degradation law function of the dissipated energy
- The Benzeggagh-Kenane [30] (BK) law for the mixed opening mode (mode I plus mode II or III)
- The material properties of the interface can be considered matrix dominated. For this reason the following assumptions were used:
 - Normal modulus $K_{nn}=E_2$
 - Normal strength $t_n=Y_t$
 - Equal shear moduli in both directions $K_{ss}=K_{tt}=G_{12}$
 - Equal shear strengths in both directions $t_s=t_t=S_{12}$

The parameters K_{nn} , K_{ss} , K_{tt} , t_n , t_s and t_t are the stiffnesses and strengths of the CZM model, as described in detail in the ABAQUS manual [19].

2.5. Numerical implementation of the impact tests

The experimental impact tests reported before were simulated using the commercial finite element software Abaqus Explicit 6.11 [19] coupled with the numerical damage model previously described.

The impact test was numerically modelled assembling several parts as schematically reported in Figure 3. The modelling details of each part will be discussed in the following paragraphs.

2.5.1. External composite

The external composite part of the vessel is produced by filament winding using the material described before. Due to the production process and the sample geometry, the layup definition is trivial. The dome

1 section presents a continuous variation of the fibres orientation that needed some simplifications in order
2 to be modelled. Several trials were done to find the optimum compromise between the model complexity
3 and the simulation accuracy. The best was obtained dividing the dome in eight subsections in which the
4 layup orientation was step by step varied (each subsection presented a fix layup/orientation). A schematic
5 drawing is reported in Figure 4.

6
7 The damage model (presented in the previous section) required to model each composite ply separately
8 placing the cohesive interfaces between the plies. Each ply was discretized using two (in the thickness
9 direction) standard continuum solid hexahedral element C3D8R [19] with eight nodes and reduced
10 integration scheme. The intralaminar damage model, coded in a VUMAT subroutine, was integrated in the
11 elements and evaluated at each time increment for each integration point. The hourglass, by means of the
12 enhanced method, and the distortion controls were used for all of the elements [19].

13
14 The interfaces between differently oriented plies were discretized using the cohesive element COH3D8
15 [19] defined with the classical bilinear traction separation law (more details in the previous section). Each
16 interface was modelled with a thickness of 0.01 mm, which was deducted from the thickness of the
17 adjacent layers to obtain the same total laminate thickness. The cohesive thickness of 0.01 mm was
18 defined to get the best compromise between the computational time and the reduction of the global
19 laminate stiffness related to the presence of the cohesive interfaces.

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21 In order to reduce the computational time, only small part of the vessel around the impact zone was
22 discretized using the approach presented before (C3D8R + COH3D8 elements with the damage model
23 implemented). This area was defined after the evaluation of induced damage on the experimental
24 impacted samples. In Figure 5, the different areas are showed for both configurations. The remaining part
25 of the external composite part of the vessel was modelled with purely elastic (no damage) eight nodes
26 reduced integrated continuum shell elements, SC8R [19], with a layered section. These elements were
27 preferred to the classical shell S4R elements in order to keep a low computational cost without affecting
28 the model accuracy. The precision of the used contact algorithm (more details in the following
29 paragraphs) could have been affected using shell elements [19].

30 **2.6. Impactor, base, internal liner and valve**

31 The impactor and the base were simulated as infinite rigid surface by mean of R3D4 elements [19]. For
32 both two impact configurations, the geometry of the base was modified in order to reduce the
33 computational cost of the contact simulation. A V-shaped base with a 33° angle was used.

34 The internal liner was modelled with one (through the thickness direction) continuum shell element SC8R
35 [19]. The valve was instead modelled with standard solid element C3D8R [19]. For both parts, linear
36 elastic material models were used with the properties reported in Table 1.

37 **2.7. Boundary conditions and contact algorithm**

38 The boundary conditions were defined in order to better simulate the experimental tests. A resume
39 scheme of them is reported in Figure 6 for both two impact configurations.

40 The general contact algorithm, available in Abaqus Explicit 6.11 [19], was used between all the surfaces.
41 The normal behaviour was defined by hard contact law [19] while the Coulomb model was selected for the
42 friction formulation [19]. No experimental measurements were conducted to evaluate the friction
43 coefficient between the different involved materials (impactor/composite, composite/composite and
44 composite/composite).

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1 composite/base). Several studies investigated the friction coefficient between metal and composite and
2 composite/composite [31, 32]. In the present work, an average friction coefficient of $\mu=0.3$, was used for
3 all of the implemented contacts with no distinctions.

4 **2.8. Mesh details**

5 The element sizes of the different model parts need to be carefully defined in order to obtain accurate
6 results [33]. For both two configurations a very fine mesh was used. Moreover, due to the complexity of
7 the layup and the curved surface, the composite and cohesive layers where modelled with shared nodes
8 [19] (instead of modelling the different parts individually and connect them by tie constrains). This
9 modelling technique did not allow the use of a finer mesh only for the cohesive interfaces (reducing the
10 computation cost of the simulation). For this reason, both the cohesive interfaces and composite layers,
11 were discretized with elements of an approximately in plane dimension of 1x1mm (two elements in the
12 thickness direction for the composite layers and one element for the cohesive interfaces).

13 More coarse mesh was used in the remaining part of the sample. Elements of approximately 3mm length
14 were used for the remaining part of the external composite and internal liner (one element in the
15 thickness direction). Elements of 0.5x0.5mm were used for the impactor and 10x10mm for the base.

16 The final element sizes previously reported were defined after a preliminary mesh sensitivity analysis.
17 The different meshes (varying the in plane elements dimension) were compared in order to obtain the
18 best compromise between the computational time and the results accuracy (evaluated by the comparison
19 of the delamination shape and impact curve against the experimental data).

20 **3. Results and discussion**

21 **3.1. Experimental impact tests**

22 At least three samples were tested for each configuration and impact energy. As reported in Figure 7, the
23 impact curves showed a very good reproducibility with a low scatter (<8%). The data for each set of tests
24 were averaged and are reported in Figure 8.

25 The impact curves presented a very similar behaviour. The initial response is almost linear for all the
26 different configurations (dome and central section at different energy) followed by a reduction of the
27 curve slope representing the damage initiation (matrix cracks and delamination). Slightly different the
28 behaviour at higher impact energies (60J and 100J) where a drastic drop of the contact force is showed
29 after the initial elastic response. This behaviour can be related to the different type of failure happening
30 during the impact. Analysing the recorded videos, it was possible to clearly see a small amount of fibre
31 failure happening at early stage (in correspondence of the drop in the force curve) of the impact event. For
32 lower energies (20J and 40J) the fibre failure occurred later in correspondence of the maximum reached
33 displacement.

34 Due to the transparent nature of the used material, the induced damage was evaluated by the back light
35 technique [5, 34, 35] for the different configurations. The induced damage showed quite a large variation
36 for both size and shape (for the same configuration/energy). For this reason no representative images are
37 reported here.

38 From a rough evaluation, the delamination and matrix cracks resulted anyway proportional to the
39 incident impact energy. A large amount of fibre failure was visible the impact on the central section of the
40 vessel. In this case the hoop layer, placed on the outer surface of the vessel, reported a single vertical

(transverse to the fibre direction) crack (fibre failure) whose length increased with the impact energy. Fibre failures were also visible for the impact on the dome section but only at the higher impact energies (60J and 100J).

3.2. Numerical impact simulations

The experimental impact tests, were simulated using the commercial FEM software Abaqus 6.11 [19]. In Figure 9 and Figure 10 the numerical/experimental data are reported and compared for the different configurations/impact energies.

The results showed a quite good accuracy of the numerical model to predict the experimental impact behaviour. The maximum impact force, the total impact time, the maximum displacement and the initial elastic response were accurately simulated.

In Figure 11 the numerically predicted and experimentally measured absorbed energies are reported for the different configurations. All the plots shown in Figure 11 are normalized by the maximum incident impact energy. The simulations were able to predict the kinetic energy evolution quite well. Small discrepancy is showed for the data of central impact but the general trend is anyway well predicted.

The overall interlaminar and intralaminar damages were evaluated for the different configurations and reported in Figure 12 and Figure 13 (it was not possible to report the report the experimental damage). For the impact on the central section, the overall interlaminar and intralaminar damage showed a reasonable pattern with a slightly overestimation of the total size. More pronounced is the overestimation for the impact on the dome section. The error of the numerical model can be related to several factors. Mainly the lack of information about the interlaminar fracture toughness could have affected the overall delaminated area. This coupled with the complexity of the geometrical model for the dome section, could have increased the mismatch. The matrix cracks overestimation can be instead related to the used material properties or geometrical errors of the numerical model. The material properties were evaluated on the same constituents and the same production process but with different production parameters in order to be made in a lab scale facility. This could have affected the values reducing the model accuracy. Moreover, due to the industrial production process, the vessel showed consistent local variation of the thickness of the external composite section. The thickness in the numerical model was defined as an averaged value between the different measured ones for each section. In addition, the implemented failure model could be a source of error. The elements of the stiffness matrix were reduced when damage was predicted (matrix cracking and fibre failure). A better modelling method may be the continuum damage approaches [36-38], but they were not implemented here. These models require material data (the dissipated energies during the damage) that are difficult to obtain. The increased test effort may be worth for high tech applications, but it can usually not be justified for the applications investigated here. The general variability of the properties of filament wound composite would also mask the benefits of additional testing.

Overall, the numerical impact curves (force-time and force-displacement reported in Figure 9 and Figure 10) showed very good agreement with the experimental data, indicating that damage was modelled with sufficient accuracy.

4. Conclusion

Impacts on full scale composite pressure vessel were numerically and experimentally investigated.

1 The numerical simulations were carried out using an advanced 3-D FE model, with the simultaneously use
2 of intralaminar and interlaminar damages theories. The Hashin failure criterion was used for the
3 evaluation of fibre failure and the Puck criterion for matrix cracks. Delamination onset and propagation
4 was evaluated by cohesive theory. The bilinear traction separation law, based on the critical strain energy
5 release rates, was used. The material model was implemented in the FE software Abaqus Explicit [19] by a
6 VUMAT subroutine.
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9 The FE simulations were able to accurately predict the impact events. The total impact time as well as the
10 maximum impact force was well captured for all impact configurations (different impact positions and
11 impact energies). The induced damage was over predicted by the numerical model. This error can be
12 related to both the inaccuracy of the used material properties, geometrical error (thickness variation was
13 not considered in the model) and due to the implemented stiffness matrix degradation method. Higher
14 accuracy was found for the impact energy that was predicted with less than 5% of error.
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17 Future work should focus on the improvement of the developed damage model. A continuum damage
18 approach, evaluating the total energy dissipated during the matrix cracking evolution, should be
19 implemented in order to reduce the damage overestimation of the model. Overall the FE model and its
20 failure criteria showed good accuracy for modelling impact damage on full scale composite component.
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22 **5. Acknowledgements**

23 This work is part of the collaborative project "Composite structures under impact loading - COMPACT".
24 The authors would like to express their thanks for the financial support by the Norwegian Research
25 Council (grant 193238/i40) and the industrial partners. The authors would also like to thank all partners
26 in the project for constructive discussions.
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Table 1: Material properties

Composite properties:

Properties	Value
Fibre volume fraction	45.7%
Density	1230 kg/m ³
Elastic properties	$E_1 = 61.54 \text{ GPa}$; $E_2 = E_3^* = 13.93 \text{ GPa}$; $G_{12} = G_{13}^* = G_{23}^* = 1.43 \text{ GPa}$; $\nu_{12} = \nu_{13}^* = 0.30$; $\nu_{23}^* = 0.5$;
Strength [MPa]**	$X_t = 837$; $X_c = 414$; $Y_t = Z_t^* = 25.8$; $Y_c = Z_c^* = 100.2$; $S_{12} = S_{13}^* = S_{23}^* = 44.24$;

*Assumed

**Note: X is the fibre direction, Y is the matrix direction, t is for tension and c for compression; S12 is for shear

Interlaminar properties:

Properties	Value
Elastic properties	$K_{nn}^* = 13.93 \text{ GPa}$; $K_{ss}^* = K_{tt}^* = 1.43 \text{ GPa}$
Strength [MPa]	$t_n^* = 25.8$; $t_c^* = t_t^* = 44.24$;
Fracture toughness [N/mm]	$G_{Ic}^{**} = 0.83$; $G_{IIc}^{**} = G_{IIIc}^{**} = 3.15$
Mode interaction – BK	$\eta^* = 1.40$

*See section "Interlaminar damage model" for more detail

**Data from similar material (E-Glass/Epoxy produced by filament winding) from [39]

Liner properties:

Properties	Value
Density	1230 kg/m ³
Elastic properties	$E = 3.5 \text{ GPa}$; $\nu_{12} = 0.30$;

Valve properties:

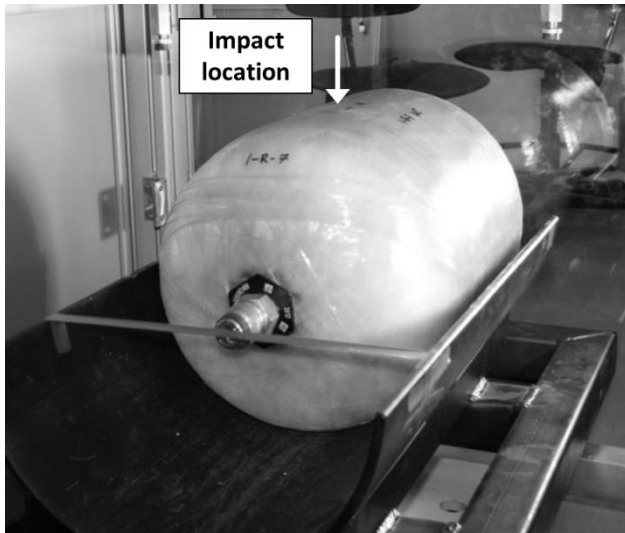
Properties	Value
Density	1230 kg/m ³
Elastic properties	$E = 7 \text{ GPa}$; $\nu_{12} = 0.30$;

Table 2: Resume of the different impact configurations

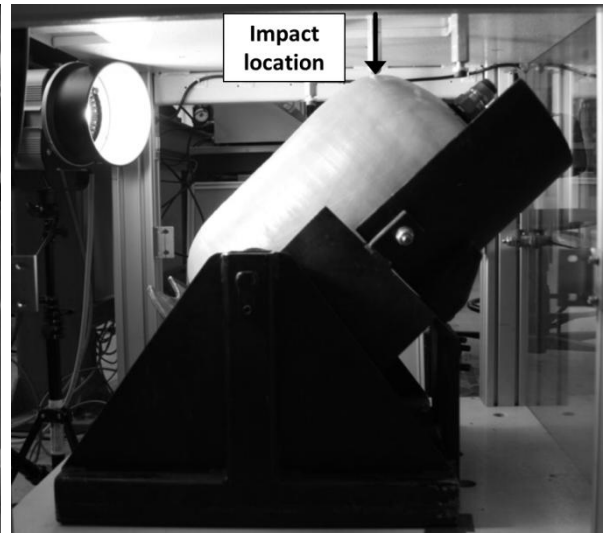
Configuration	Impact energy [J]	Impactor mass [kg]	Impactor velocity [m/s]
Central section	20	5 Kg	2.82
	40		3.98
Dome section	20		2.82
	40		3.98
	60		4.88
	100		6.3

Table 3: Special Puck parameters from [20]

Fibre Type	$P_{\perp\parallel}^+$	$P_{\perp\parallel}^-$	$P_{\perp\perp}^+$	$P_{\perp\perp}^-$
Glass Fibre	0.30	0.25	0.20 – 0.25	0.20 – 0.25
Carbon Fibre	0.35	0.30	0.25 – 0.30	0.25 – 0.30



Central section



Dome section

Figure 1: Test configurations

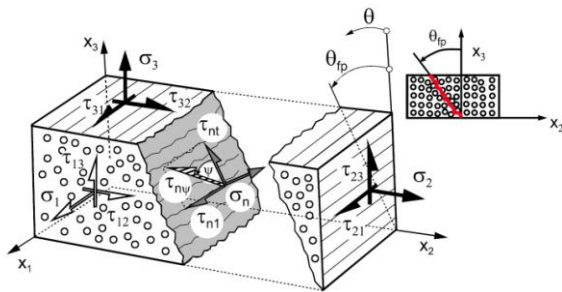


Figure 2: Puck fracture plane definition [22]

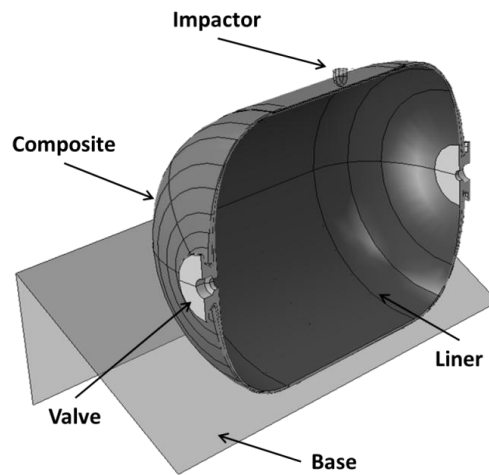


Figure 3: Different part of the model (only half of the model is reported in this figure)

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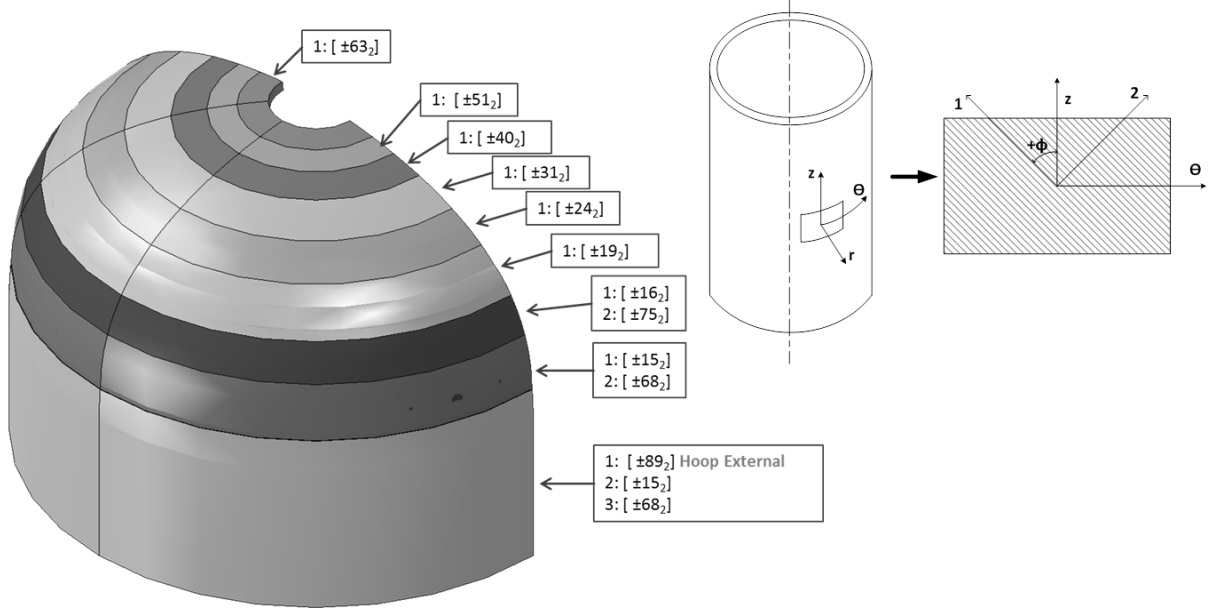


Figure 4: Used layup for finite element model with the reference coordinate system – Only a quarter of the model is reported in order to simplify the visualization

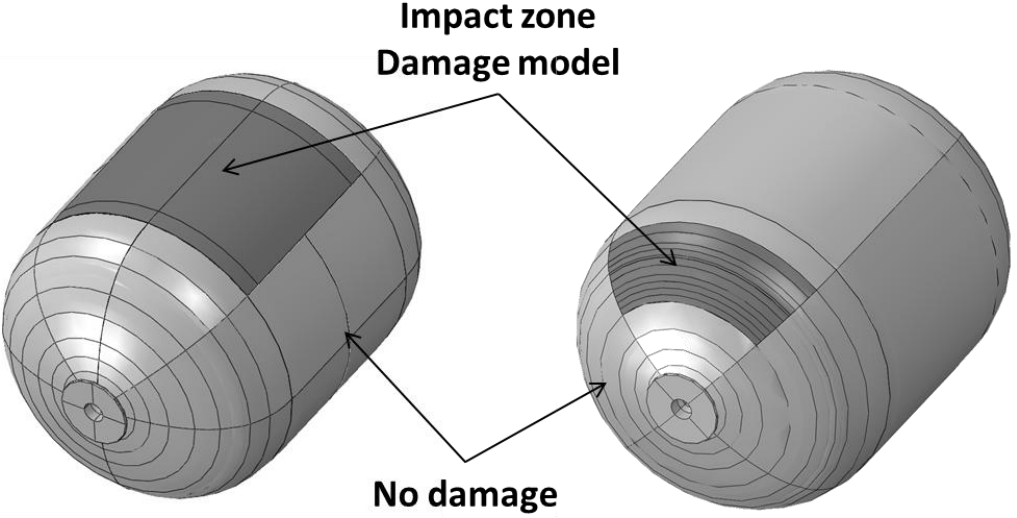
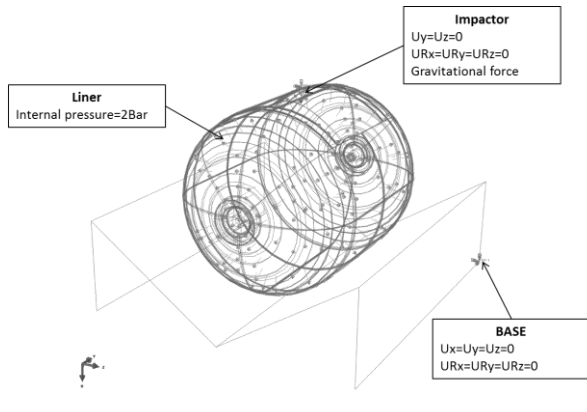
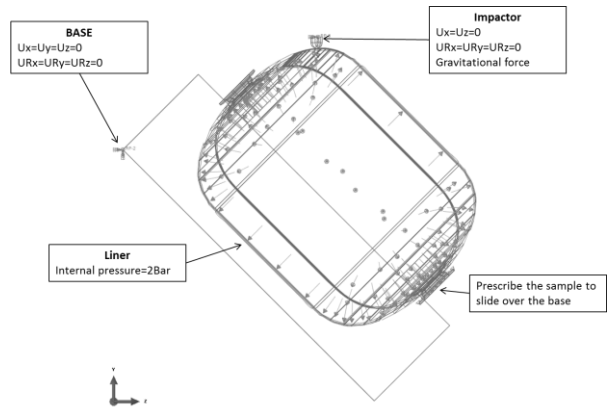


Figure 5: FEM model. In red the impact zone modelled with the developed damage model



Central section impact



Dome section impact

Figure 6: Model boundary conditions

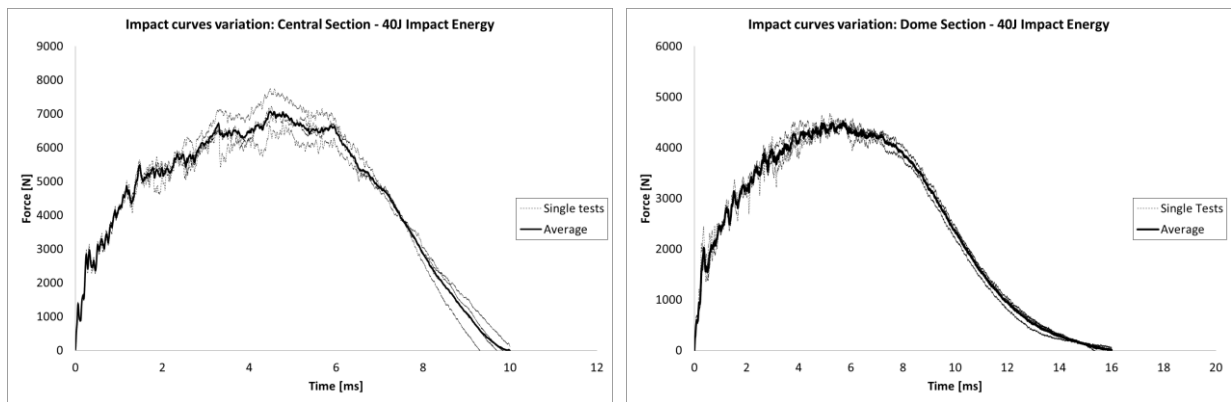


Figure 7: Example of the reproducibility of the experimental impact tests. The impact data for the single tests and the average curve are reported for the impact energy of 40J for both central and dome sections of the vessel.

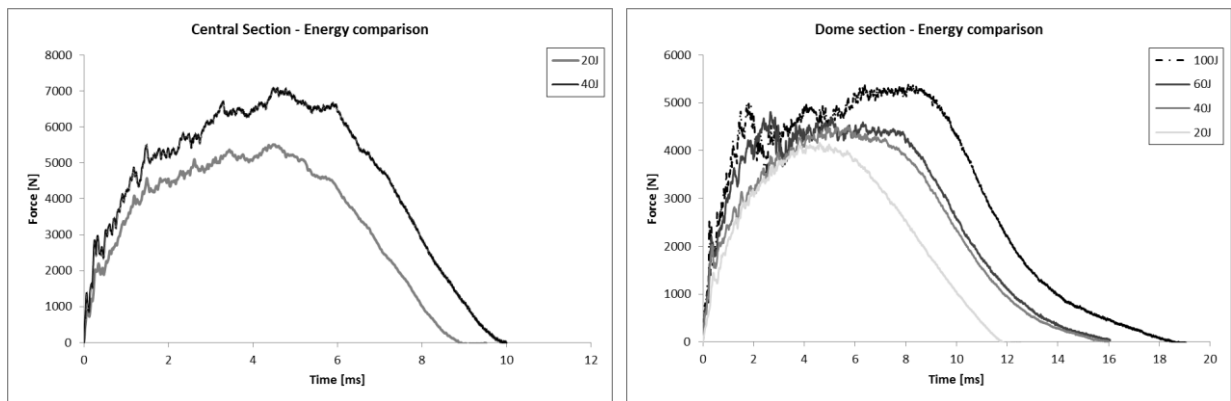


Figure 8: Experimental impact tests (averaged results)

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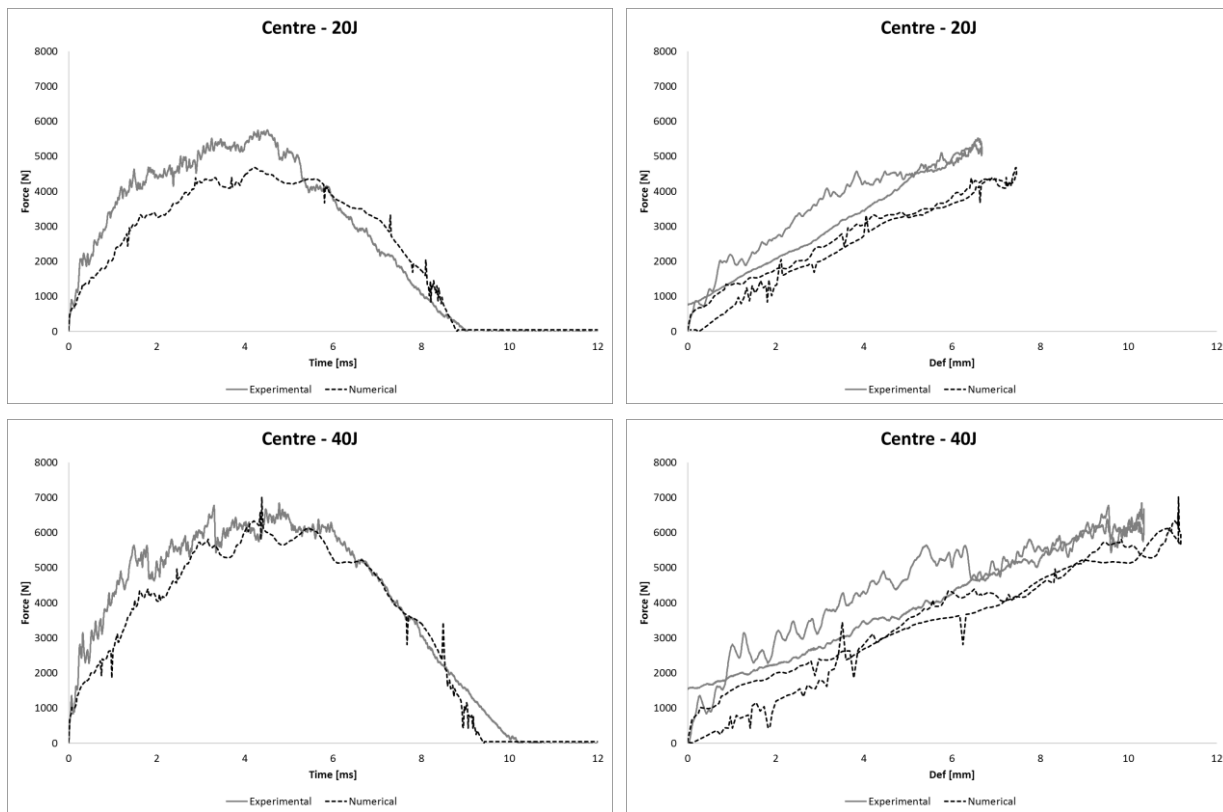


Figure 9: Num/Exp - Impact Central section - 20J

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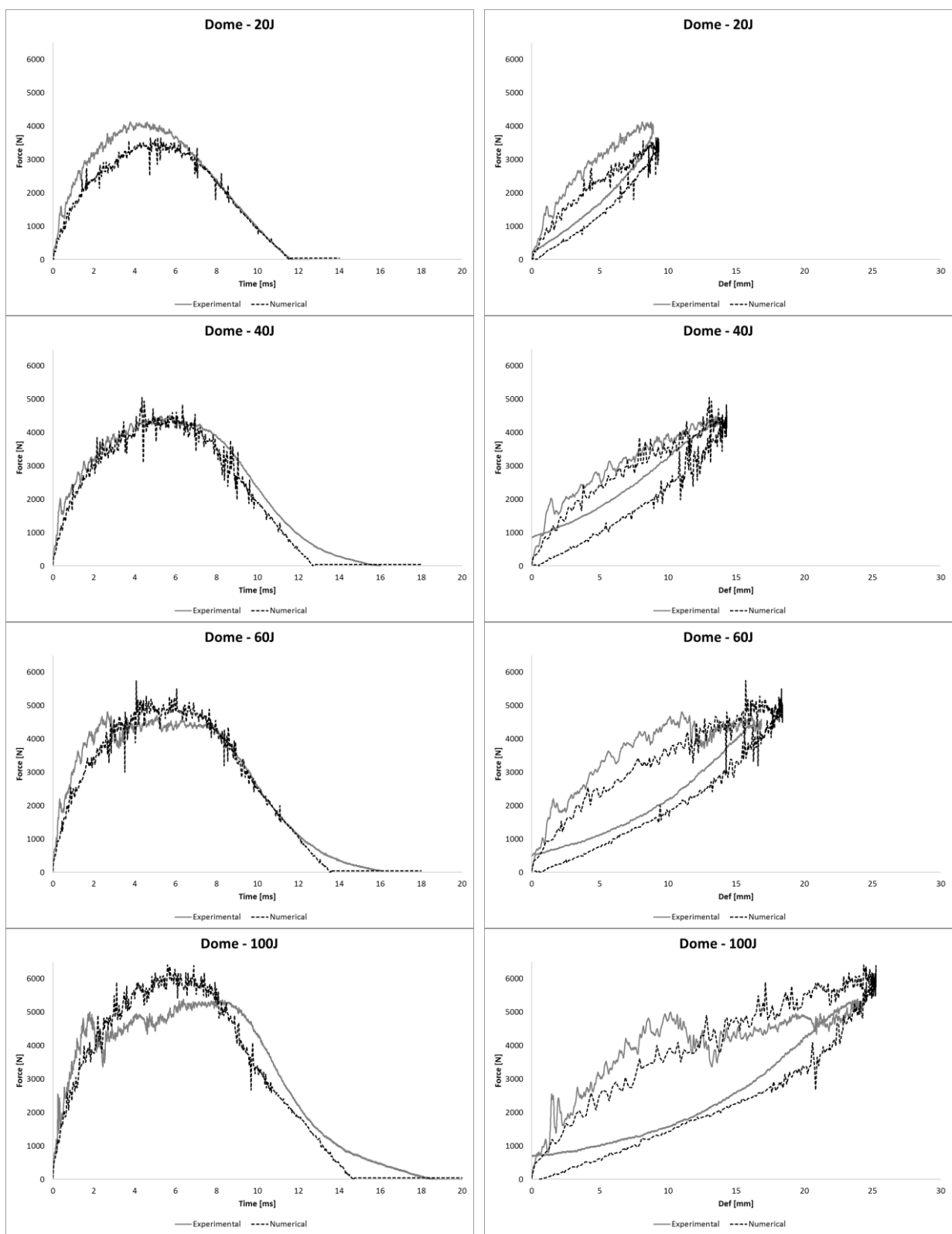


Figure 10: Num/Exp - Impact Dome section

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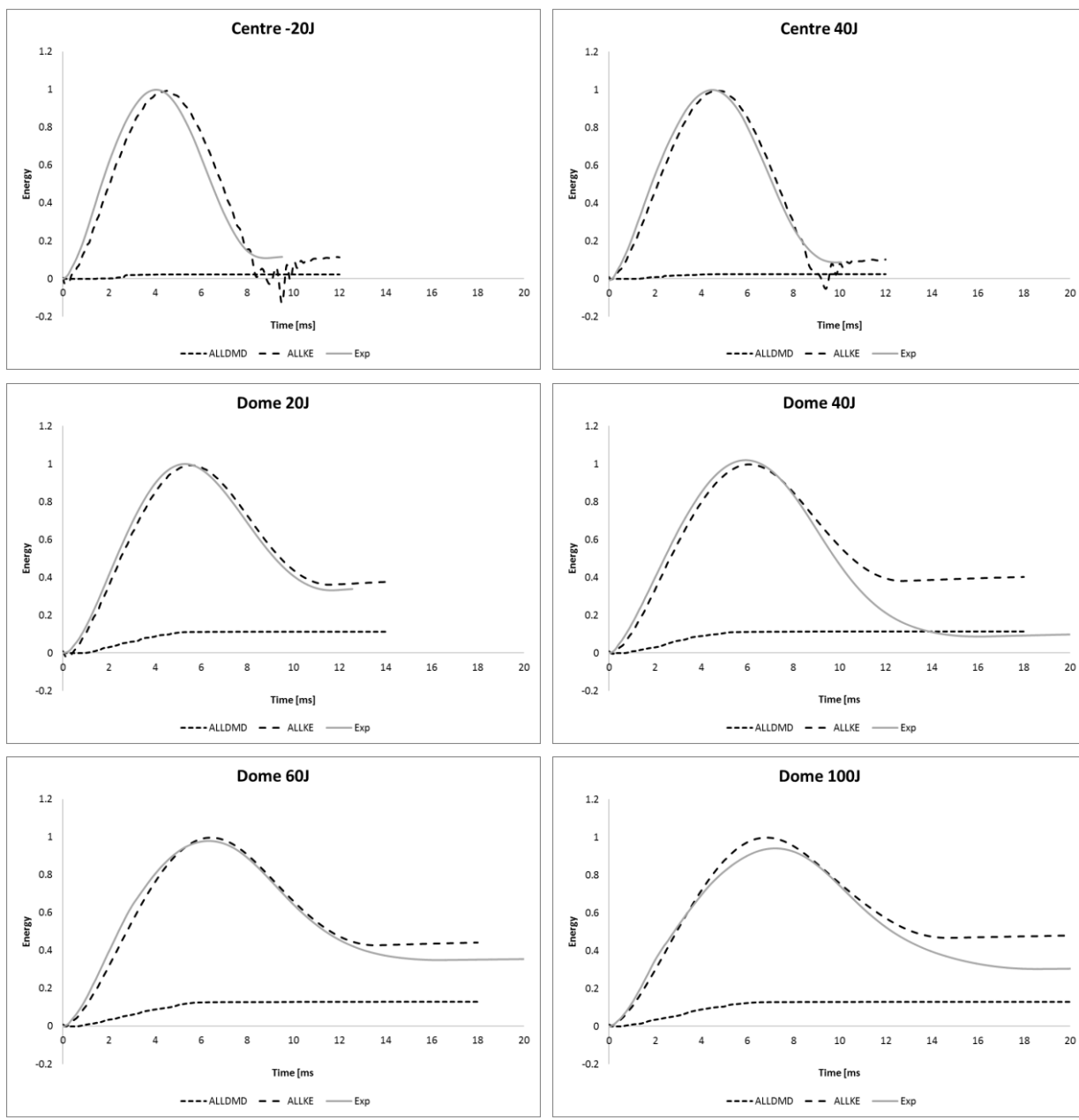


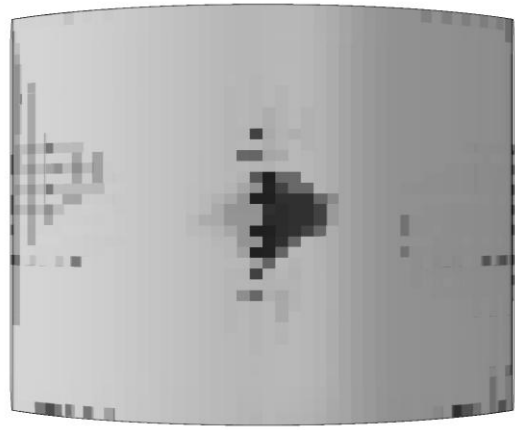
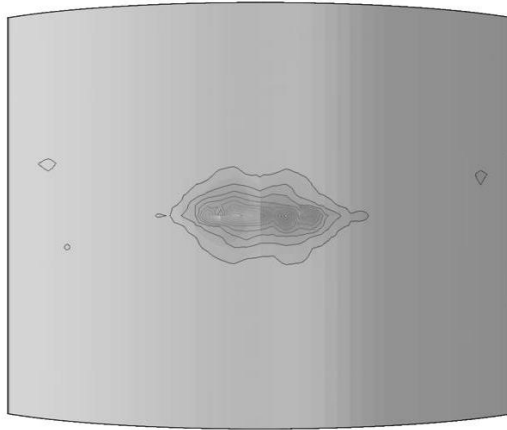
Figure 11: Num/Exp dimensionless energies comparison (ALLDMD: numerical damage energy, ALLKE: numerical kinetic energy, Exp: experimental kinetic energy)

Energy

Delamination

Matrix cracks

20J



40J

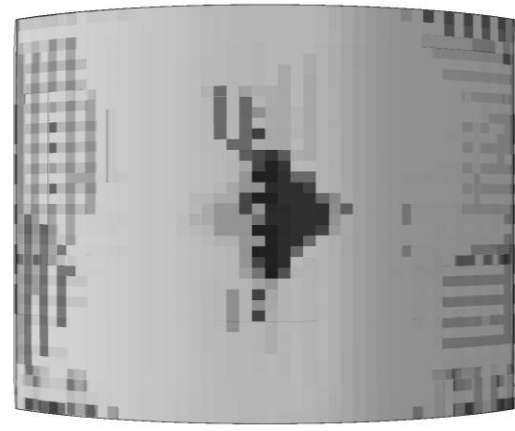
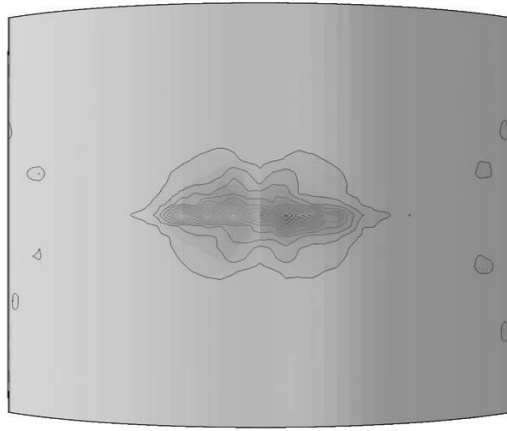


Figure 12: Impact on the central section - Numerical damages for the different impact energies. Colour scale varying from grey representative of no damage, to black for the full damage (all the element in the thickness direction)

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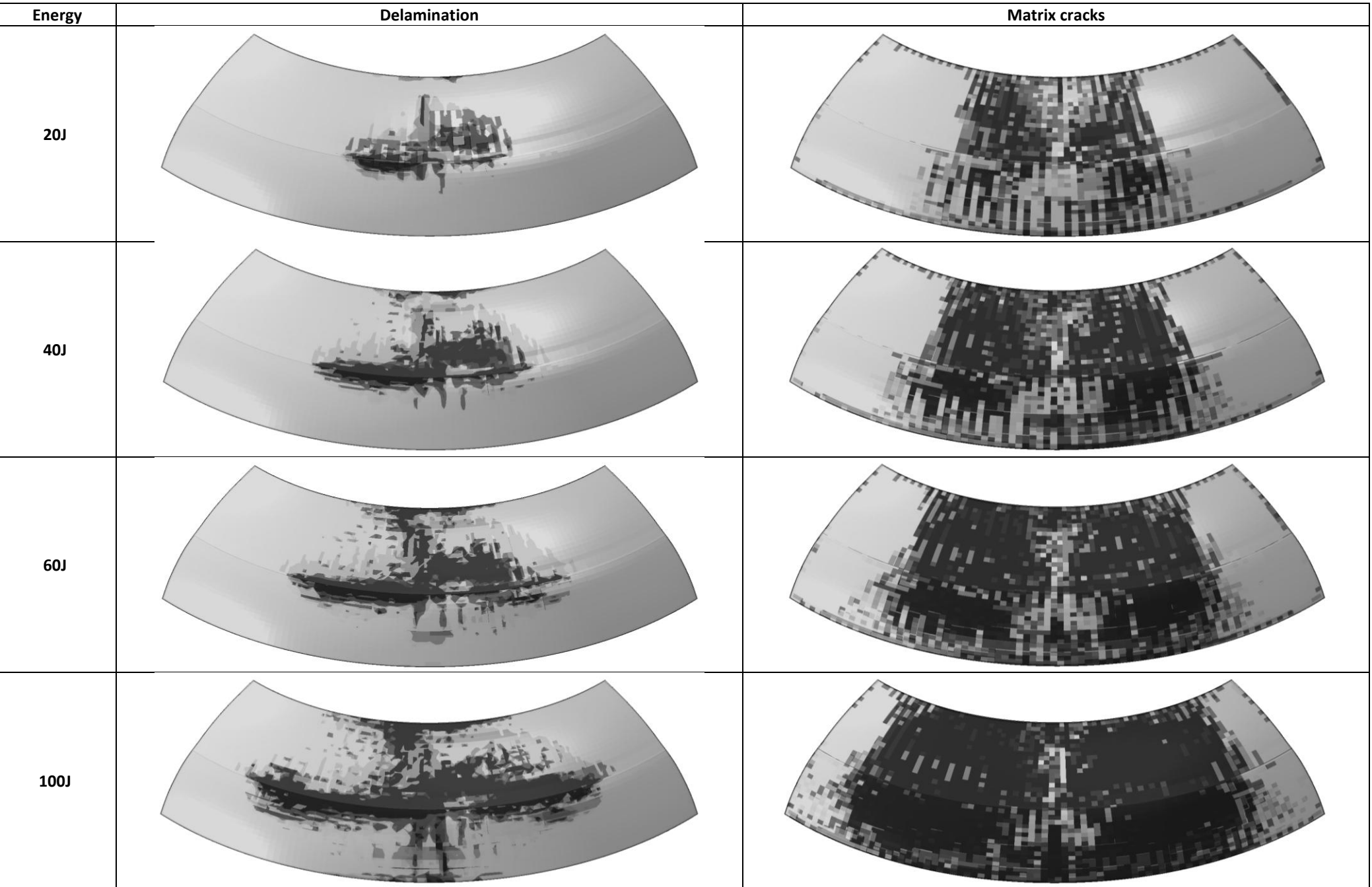


Figure 13: Impact on the dome section - Numerical damages for the different impact energies. Colour scale varying from grey representative of no damage, to black for the full damage (all the element in the thickness direction)

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