| 1 | Estimating purse seine volume during capture: implications for fish densities and |
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| 2 | survival of released unwanted catches |
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| 8 | |
| 9 | Abstract |
| 10 | High fish densities negatively impact catch welfare and the survival of unwanted catches |
| 11 | released from purse seines. To avoid overcrowding fish before being released, regulations |
| 12 | have been implemented in Northeast Atlantic mackerel and Atlantic herring fisheries that |
| 13 | set a limit to the proportion of the full length of the seine that can be hauled in before |
| 14 | catches are released. However, it is yet unknown how seine volume, and thus fish density, |
| 15 | relates to proportion of seine hauled. In this study, we have estimated the in-water volume |
| 16 | of purse seines during commercial fishing from multibeam sonar screen images and |
| 17 | applied a log-linear mixed effects model to the data. The prediction intervals from the |
| 18 | model in combination with a long-term dataset on mackerel and herring catch sizes were |
| 19 | used to estimate fish densities inside the seine. The results indicate a 33-fold decrease in |
| 20 | contained volume from 10 to 80% seine hauled in and significant differences between |
| 21 | different sized seines. Average fish densities were predicted to be within safe crowding |
| 22 | levels in median sized catches while mackerel densities may reach critical levels in larger |

23 catches at 80% seine hauled aboard. The results question the rationality of having the same

24 catch release limit for all seine sizes.

Keywords: catch release, crowding density, multibeam sonar, 3-D reconstruction, purse
seine volume

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29 Introduction

30 Purse seining is a highly efficient fishing method for catching aggregated and schooling 31 pelagic species and accounts for about a quarter of the total world catch of all fish (Watson 32 and Tidd, 2018). Research on purse seine performance has mainly focused on increasing 33 catch success and efficiency by studying the sinking performance (Misund et al., 1992; 34 Hosseini et al., 2011) and in-water behaviour of purse seines (Kim and Park, 2009) during 35 the early catch stages. Purse seine geometry and behaviour during hauling has received 36 relatively little attention but is of importance from a fish welfare point of view. Fish 37 density in the seine is affected by the available volume and thein-water volume of the seine 38 may thereby influence the survival of unwanted catches released from the net and catch 39 quality. However, the seine can take a range of different shapes depending on 40 environmental conditions and fishing techniques (Ben-Yami, 1994; Decew et al., 2013; 41 Zhou et al., 2015) and the in-water volume may vary significantly under different fishing 42 conditions. Understanding how the seine behaves in the water during hauling is also 43 important for future developments in gear designs and by-catch release methods. 44 Northeast Atlantic (NEA) mackerel (Scomber scombrus) and Atlantic herring 45 (Clupea harengus) support large and valuable purse seine fisheries in NorwayWith annual 46 landings ranging between 500 000 and 1 000 000 t since 2010 (data from the Norwegian 47 Fisheries Directorate). Unwanted catches, e.g. large catches that exceed vessel handling 48 capacity or the allocated fishing quota, by-catches of non-target species and low value 49 target catches is a are commonly released from the seine (slipped) before being brought

50 aboard. The mortality rate of the released catches is density and time dependent and may

be high if released at a late stage of the catch process. NEA Mackerel mortality has been
estimated to be about 80% after 10 to 30 minutes crowding at a fish spatial density of
about 200 kg m⁻³ (Lockwood et al., 1983; Huse and Vold, 2010) while Atlantic herring
mortality was estimated to be about 50% following 15 minutes crowding at fish densities
between 400 and 480 kg m⁻³ (Tenningen et al., 2012). The weight of large catches may
also cause the net to burst with consequently high, up to 90%, fish mortalities (Misund and
Beltestad, 1995).

58 In recent years, considerable effort has been made to reduce mortality of catches 59 released from purse seines by developing better acoustic school biomass estimation before setting the net (Tang et al., 2009; Vatnehol et al., 2017), more gentle fish release methods 60 61 (Vold et al., 2017), and introducing regulations that aim to ensure survival of the released 62 catches (Anon, 2008; EU, 2013). The regulations for slipping in mackerel fisheries in 63 Norwegian waters require that the seine is opened and ready for release before 88% of the 64 seine length has been retrieved, to ensure survival of the released catch. In EU waters, 65 mackerel and herring can be released as long as the proportion of the seine length retrieved 66 is no more than 80% and 90% respectively.

The catch release limits are based on estimates of seine volume (Tenningen et al., 2015), observations at sea, and discussions between fishermen, managers and scientists. However, it is questionable whether it is sensible to have the same release limit for all seine and catch sizes. Ideally, fish density and behaviour should be monitored throughout the catch to ensure that any unwanted catches are released carefully and before harmful behaviour or densities occur, but monitoring fish schools inside the purse seine is challenging (Tenningen et al. 2015; 2017)

The objective of this study was to estimate the three-dimensional (3-D) shape and
in-water volume of purse seines used in Norwegian mackerel and herring fishing as a

function of proportion of seine retrieved and seine size. The data collected in this study
was combined with previously collected data on purse seine geometry (Tenningen et al.,
2015). Our hypothesis was that seine volume reduces as a function of proportion retrieved,
at the same rate for different sized seines, but with initial volumes differing between
different sized seines. The results were used to assess how variation and reduction in the
contained volume may affect fish densities inside the seine and thereby the survival of
released catches.

83

84 Methods

85 Field data collection

86 In the current study, data were collected from five purse seine sets during the annual 87 Northeast Atlantic (NEA) mackerel fishery in September and October in the northern 88 North Sea and Norwegian Sea. These data were combined with previously collected at-sea 89 measurements of purse seines (Tenningen et al., 2015) to increase the data set. Combining 90 the two datasets resulted in data from 13 purse seine sets with four different seine sizes that 91 represent seines use dby the larger off-shore fleet in Nordic mackerel and herring fisheries 92 (Table 1). A purse seine "set" refers to the full capture process from deploying the net in 93 water until the whole net is retrieved aboard. The Norwegian purse seiners MS "Kings 94 Bay" with a gross register tonnage (GRT) of 4027 and a length of 77.5m, and MS "Asbjørn 95 Selsbane" with a GRT of 1191 and length of 55 m were used in this study and MS "Libas" 96 with GRT of 4377 and length of 94 m was used in Tenningen et al., (2015). The purse 97 seines ranged from 677 – 796 m in length and 180 to 265 m in depth (Figure 1). 98

90

99 The proportion seine retrieved

100 The proportion of the total length of the seine retrieved (proportion hauled) is the key 101 explanatory variable of seine volume. We have assumed a constant hauling speed in our 102 model approach. Thus, the proportion of the seine aboard the fishing vessel at any given 103 time was estimated as the time since hauling started, divided by the time taken to retrieve the entire seine aboard. Average seine retrieval rates varied between 0.16 and 0.33 m s⁻¹ in 104 105 the monitored purse seine sets (Table 1). Fishermen tend to maintain a constant hauling 106 speed to avoid unnecessary strain on the gear and stressing the fish, but there may be short 107 stops and changes in the hauling speed lasting from some seconds to some minutes due to 108 gear related complications that may violate this assumption.

109

110 Sonar data collection

111 We used a multibeam fish finding sonar (Simrad SN90, Kongsberg Maritime AS) to 112 monitor the seine. The SN90 sonar has a flat transducer with 265 transmission and receiver 113 channels covering a 160-degree sector horizontally and a 90-degree sector vertically 114 (Figure 1). The beam width varies with the frequency from 5 to 8 degrees. The transducer 115 was mounted on the vessel hull in the starboard bow and the sonar was operated at 75 - 80116 kHz frequency with a pulse duration varying between 4 and 7 ms and a pulse rate of about 2 s⁻¹. Tenningen et al. (2015) used a Simrad SH80 sonar mounted on the drop keel. The 117 118 SH80 sonar is omnidirectional, has a slightly wider opening angle (9°) , slower ping rate 119 (about 1 s⁻¹) and higher frequency (116 kHz) compared with the settings used on the SN90 120 sonar.

121 The sonar data were collected by systematically moving the vertical sonar fan 122 across the entire seine. One crossing lasted on average 73 s and consisted of 8-13 vertical 123 cross-sections of the seine at 5 to 10-degree intervals (Figure 2, Table 1). The seine was 124 crossed between 2 and 11 times during each purse seine set. The quality of the acoustic 125 images varied depending on interference from propeller and wave created air bubbles.

126 Only images where the seine contours were clearly visible were used for the analyses,

127 resulting in a variable number of crossings per set.

128

129 Sonar image analyses and volume reconstruction

130 Tenningen et al (2015) extracted seine contours from single images by manually drawing 131 the outline in the center of the visualized echoes from the cross-sections of the seine. In the 132 current study we used image analyses to extract the contours. Gravscale images were 133 captured from the SN90 software and processed using a custom Python script, using the 134 OpenCV library for image processing (Bradski, 2000) (Figure 2a). First, a 21-by-21-pixel 135 Gaussian blurring filter with a standard deviation of 3.5 pixels was applied to suppress 136 small-scale features. A per-pixel median filter was then applied over several images from 137 the same seine section, to suppress temporal noise, resulting in one grayscale image per 138 seine section. The position of the sonar transducer was identified and used to define a 139 coordinate system with the transducer location as the origin and the central beam projected 140 at the horizontal plane as the x-axis. Next, the grayscale image was segmented into regions 141 using an adaptive threshold with block size 251-by-251 pixels (Gonzalez and Woods, 142 2002) (Figure 2b). The local threshold was determined by the weighted average of the 143 values in the respective block. Gaussian weights with a standard deviation of 38 pixels 144 were used. From the thresholded image, the regions belonging to the seine were extracted 145 using a watershed transform (Roerdink and Meijster, 2000), and its contours extracted 146 (Figure 2c). The 3-D coordinates relative to the sonar position of the seine contour were 147 generated using information about the sonar setting (inclination angle and heading) and the 148 spatial resolution in the SN90 software display.

The extracted seine contours overestimate the real area of the seine cross section because the echoes are smeared over the entire sonar voxel (Misund, 1997) and the image analyses detects the outer edges of sonar voxels. To address this, a correction was applied across beams by moving each point in a seine cross section half a beam width towards the center beam. The along beam resolution is high, about 20 mm, and correction was not necessary.

Multiple cross-sections were merged into one file containing a 3-D point cloud representation of the seine (Figure 2d and e). 3-D point clouds extracted from previously collected data on purse seine geometry during commercial mackerel fisheries (Tenningen et al., 2015) were at this stage combined into one data set. 3-D Delaunay triangulation was used to construct a closed surface of the 3-D point cloud and calculate volume (Ahrens et al., 2005) (Figure 2d and e). The estimated seine volumes were related to corresponding proportions of seine retrieved.

162

163 Modeled seine volume as a function of haul proportion and seine size

164 To estimate how seine volume relates to proportion hauled and seine size, we log 165 transformed the data, and fitted a mixed effects model with gaussian error distribution to 166 the data: $\log(Volume) \sim \log(1-proportion hauled) + \log(seine size) + (\log(1-proportion hauled)) + \log(1-proportion hauled) + \log(1-proportion hauled)) + \log(1-proportion hauled) + \log(1-proportion hauled)) + \log(1-pr$ 167 hauled)|Set). The linear mixed effects model was implemented in the R-environment, 168 package lme4 (Bates et al., 2015; R-Core-Team, 2018). The amount of seine still in the 169 water (1-proportion hauled) and seine size were used as fixed explanatory variables. Seine 170 size was expressed as the theoretical maximum volume of the net (net length² * net 171 height / 4π) corresponding to the point where the whole net is in water, but not pursed, i.e. 172 the seine takes the shape of a cylinder. When the fishermen start hauling, the seine is 173 usually pursed and the volume is smaller than the maximum theoretical volume. We

174 included purse seine set as a random factor and allowed both the slope and intersect to vary 175 between sets. We tested whether including random slopes or an interaction effect between 176 the theoretical maximum volume and the proportion hauled improved model fit with AICc 177 in package AICcmodavg (Mazerolle, 2017). AICc is an adaptation of AIC for small sample 178 sizes, a decrease in AICc of more than two indicates a significant increase in model fit 179 (Mazerolle, 2017). We simulated the posterior predictive distribution with sim (10000 180 simulations) (Gelman and Yu-Sung, 2018) and provided the mean and the 95% credible 181 interval controlling for net size. The credible interval is an estimate of the interval in which 182 future observations will fall with a 95% probability. We used likelihood ratio test to obtain statistical significance of net size on contained volume by comparing the full model with a 183 184 model where net size was left out. The model was based on the assumption that the reduction in the contained seine volume follows a power law, i.e., $V = -V_0 * p^b$. Where p is 185 186 the proportion of the net that is still in the water, i.e. p = (1 - proportion hauled), V is the seine volume at p, V_0 is the initial volume at start of hauling, and b is how the change in 187 188 volume relates to p. The value of b will then tell whether a seine behaves more like a 189 cylinder $(b \sim 2)$ or more like a sphere $(b \sim 3)$ when it is hauled in.

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191 Fish density predictions

To get an idea of how seine volume may affect fish densities, hypothetical fish density estimates were made by dividing common catch sizes with the predicted purse seine volumes from our model (mean and 95% credible intervals). The same purse seine is used for catching NEA mackerel and Atlantic herring and densities were also predicted for herring catches. For catch sizes we chose to use median, upper 95th quantile and maximum size of individual catches reported in the years 2015 – 2017. In the data were included purse seine catches of Atlantic herring (Norwegian spring spawning herring stock) and

199 NEA mackerel landed in Norway by vessels with GRT larger than 1000 to represent the fleet that uses the seine sizes measured. The median, 95th quantile and maximum catch 200 201 sizes were 190, 620 and 1100 t for herring and 270, 650 and 985 t for mackerel, 202 respectively(data from electronic catch log books, the Norwegian Fisheries Directorate). 203 Translating volume predictions directly into fish densities in this way assumes that fish are 204 evenly distributed in the whole seine volume and thereby provides an estimate of average 205 fish density inside the seine. Patchy distribution could result in higher densities in parts of 206 the seine and lower densities in other parts of the seine.

207

208 Results

209 Estimated at-sea seine volume

210 The in-water volume of the purse seines was estimated to reduce by on average 17 times

211 from < 20% to > 70% hauled seine. The estimated volume reduced from 500 000 m³ at

212 12% seine retrieved to 53 000 m³ at 80% retrieved in the 7 hm³ seine and from 2 350 000

213 m³ at 7% retrieved to 99 000 m³ at 72% retrieved in the 13 hm³ seine (Figure 3). The

volume in the 13 hm³ seine was on average 3.8 times greater than in the 7 hm³ seine before

215 20% was hauled and on average 1.7 times larger when more than 70% of the seine was

216 hauled.

217

218 Predicted seine volume and fish density

219 Seine size had a significant effect on contained volume ($\chi^2(1)=9.31$, p=0.00228). The

model predicted that the contained volume reduced from 800 000 m^3 at 10% to 23 000 m^3

- at 80% hauled seine for the 7 hm^3 net and from 2 399 000 m^3 to 73 000 m^3 for the 13 hm^3
- net (Figure 3). This reflects a 33-fold decrease in contained volume from 10 to 80% hauled

seine and about three times larger volume in the largest (13 hm³) compared with the
 smallest (7 hm³) measured seine.

Average fish densities were predicted to below 5 kg m⁻³, credible intervals ranging 225 from 0.2 to 6.9 kg m⁻³, until 50% of the seine was hauled in (Figure 5). At 80% seine 226 227 hauled in, fish density was predicted to below 10 kg m⁻³ (credible intervals: 1.2 - 17.9 kg m⁻³) in median sized mackerel and herring catches. In maximum and 95th quantiles of catch 228 sizes, densities were predicted to range from 8 to 39 kg m⁻³ (credible intervals: 4 - 73 kg m⁻ 229 ³) for herring and from 8 to 35 kg m⁻³ (credible intervals: 4 - 65 kg m⁻³) for mackerel at 230 231 80% seine hauled in. Beyond 80% seine hauled in the predicted fish densities increase 232 dramatically, but few estimates of net volume are available, and the model fit is weak.

233

234 Model fit

235 Including net size as a factor in the model significantly improved the model (AICc 86.2 vs 236 93.2). While including an interaction effect between net size and the proportion hauled did 237 not further improve model fit (AICc 86.2 vs 86.2). A model where random slopes were 238 used was significantly better than a model with only random intercepts (AICc 90.1 vs 239 170.1). The estimate for slope of the effect of log(1-proportion hauled) of the model was 240 2.28, with a credible interval between 1.8 and 2.6 (Table 2). Resulting in a volume reduction of the seine that goes as $V \sim x^{2.28}$. Thus, the reduction is more similar to a 241 242 cylinder (b \sim 2) than a sphere (b \sim 3). The model fitted well up to around 80% seine hauled 243 onboard, but poorly beyond this due to few data-points and increased variation in the 244 measured volume (Figure 5).

245

246 **Discussion**

247 The purpose of regulating at which time during purse seining unwanted catches can 248 still be released is to avoid detrimental fish densities inside the seine before release. Fish 249 density in the seine is affected by catch size and seine contained volume. Our results 250 indicate that the in-water volume of purse seines used by the larger vessels in the 251 Norwegian mackerel and herring fisheries reduces by 33 from start of hauling until 80% of 252 seine was hauled in. Furthermore, the volume of the largest seine used was 3 times greater 253 compared with the smallest measured seine. Large variation in fish densities at the point 254 where the decision of keeping or releasing a catch needs to be made is problematic. In 255 some situations, fish densities may already be above safe levels. While in other situations, 256 fish density may be so low that no fish can be observed at the surface and the skipper has 257 no visual cues about the catch quantity or quality and nothing to base his decision on. To 258 ensure high survival among released unwanted catches while maintaining high catch 259 values, catch release limits should consider variations in seine size. Alternatively, efficient 260 catch monitoring systems should be developed. Acoustic and optic methods for estimating 261 fish school biomass (Nishimori et al., 2009), spatial density (Peterson et al., 1976), size 262 (Rosen et al., 2013) and species (Korneliussen et al., 2009) are available but applying these 263 methods into a purse seine capture situation can be challenging. This is due to the large 264 size and flexible, continuously changing, shape of purse seines under operation. 265 Monitoring systems where stereo-cameras and echosounders are deployed inside the seine 266 and with real time data transfer are currently being tested and developed. 267 268 Acceptable short-term stressor limits for mackerel have previously been set to a crowding

density of 30 kg m⁻³ (Handegard et al., 2017). These stressor limits are supported by the results from crowding experiments on mackerel carried out by Lockwood et al. (1983).

271 Herring has been shown to tolerate considerably higher crowding densities than mackerel.

A crowding density of 150 kg herring m⁻³ held for 10 minutes was estimated to result in a 272 273 mortality rate below 2% (Tenningen et al., 2012). In the Norwegian mackerel and herring 274 purse seine fisheries catches range from less than 50 t to over 1000 t (data from the 275 Norwegian Fisheries Directorate). To get an idea of what levels of fish densities may be 276 expected in the predicted seine volumes, common mackerel and herring catch sizes were 277 divided with seine volume. Fish densities in common mackerel and herring catch sizes 278 were predicted an average fish density in median sized mackerel and herring catches (270 279 t) to be well below critical densities at 80% hauled seine. In larger catches average fish 280 densities were predicted to be below 20 kg m⁻³ in all seine sizes, but the upper credible interval exceeded 30 kg m⁻³ in all but the largest seine size. These results suggest that 281 282 fish densities in Nordic mackerel and herring fisheries are generally within safe limits 283 when 80% of the seine is hauled in. However, mackerel densities may reach detrimental 284 levels in large schools caught in smaller seines. It is also important to consider that catch 285 quantities including slipped catches may be greater than the reported catches as slipped 286 catches are not reported. Furthermore, our study only represents the larger vessels in the 287 purse seine fleet. Smaller vessels tend to have somewhat smaller seines than the ones used 288 in this study and even though average catch sizes are smaller due to smaller loading 289 capacity it is not sure whether smaller schools are always targeted and caught. The current 290 limits for catch release are at 80% (EU) and 87% (Norway) for mackerel and 90% (EU) for 291 herring. Beyond 80% seine hauled our seine volume predictions are highly uncertain. 292 During later stages of hauling the net may take complex shapes with large folds of netting, 293 as observed by cameras inside the net (M. Breen, pers. comm.), making it difficult to 294 predict seine volume. Thus, fish densities may unexpectedly reach high crowding levels 295 when most of the net is hauled in.

296 Fish densities predicted in this study are based on the assumption that fish in the 297 seine use the whole available volume. Acoustic (Tenningen et al., 2017) and camera-based 298 (M. Breen, pers. comm.) observations of fish schools inside purse seines indicate that this 299 is not the case in the early stages of capture. Therefore, our density predictions are likely to 300 underestimate real fish densities in the beginning of hauling. However, experiments where 301 small mackerel schools were crowded in net pens show that the fish initially maintained a 302 density independent of available volume, but eventually utilized all available volume as the 303 volume was reduced (Handegard et al., 2017). In the later stages of purse seine capture 304 estimates of seine volume combined with catch size may then give a realistic indication of 305 fish density.

306 In this study the focus was on describing the in-water volume of purse seines, how 307 it varies with seine size and hauling proportion and what the implications may be on fish 308 crowding densities. Monitoring the fishing gear during operation and understanding how it 309 behaves under different fishing conditions is also essential for any future development of 310 the purse seine gear and for controlling fishing operations. It may also be important for 311 estimating by-catch quantities when only parts of the catches are sampled and fishing 312 effort is used to estimate the total quantity (Hall et al., 2017). Our study has demonstrated 313 that multibeam sonar can be used to obtain rough estimates of seine geometry until about 314 80% of the seine is hauled aboard. After this the resolution of the sonar may not be high 315 enough to capture the shape of the net. Previously, purse seine geometry during hauling 316 has been studied in small scale experiments in tanks (Kim, 2000) and using positioning 317 transponders under commercial fishing (Tenningen et al., 2015). Computer simulation 318 models have been developed to describe the geometry and performance during deploying 319 and pursing the seine (Kim and Park, 2009; Hosseini et al., 2011; Zhou et al., 2015) but are 320 still lacking for the hauling phase. Future work should aim at further developing real time

monitoring systems of purse seine geometry and improve our understanding of purse seine
 performance during hauling under different environmental and operational conditions.

323 The results in this study provide estimates of in-water volume of different sized 324 seines used in the Nordic mackerel and herring fisheries. Based on the volume estimates 325 we have predicted fish densities and considered the effects on mortality following slipping. 326 The results suggest that regulations on release of unwanted catch from purse seines should 327 take into consideration the potential effect of seine size on fish densities. Ideally, release 328 limits should reflect real fish densities, but that will require further development of real-329 time catch and gear monitoring methods and instruments. There are currently no efficient 330 methods available for estimating catch size or content inside the seine. Target school size 331 is usually estimated before capture with sonar, but it may be difficult to get accurate 332 estimates, especially when schools form large and dense aggregations and only parts of the 333 school is targeted.

334

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Tables and figures

Table 1. Summary of the acoustic data used to reconstruct the 3-D shape and in-water volume during seine hauling. Purse seine volume was estimated in 13 sets using three vessels and four different seine sizes. Seine size is presented as length (L) and depth (D) in meters, wind and current speed at 30 m depth in knots (kn) and direction relative to vessel heading ($^{\circ}$), catch size in tonnes, haul rate (Haul r), the number of times the seine was reconstructed during the set (Rec.) and the average number (\pm standard deviation) of cross sections used in each reconstruction.

| Year | Set | Vessel | Seine | ; | Wind | | Current | | Catch | Haul r | Rec. | Sections |
|------|-----|-------------|-------|-----|------|-----|---------|-----|-------|-------------------|------|------------|
| | | | L | D | (kn) | (°) | (kn) | (°) | (t) | m s ⁻¹ | | |
| 2011 | 1* | Libas | 720 | 220 | - | - | - | - | 0 | 0.16 | 8 | 3.8 (0.9) |
| 2011 | 2* | Libas | 720 | 220 | - | - | - | - | 0 | 0.26 | 5 | 4.6 (0.9) |
| 2011 | 3* | Libas | 720 | 220 | - | - | - | - | 320 | 0.33 | 12 | 9.1 (3.3) |
| 2011 | 4* | Libas | 720 | 220 | - | - | - | - | 115 | 0.21 | 3 | 5.3 (0.6) |
| 2012 | 5* | Libas | 720 | 200 | - | - | - | - | 635 | 0.24 | 10 | 5.5 (1.4) |
| 2012 | 6* | Libas | 720 | 200 | - | - | - | - | 150 | 0.18 | 21 | 5.3 (0.9) |
| 2012 | 7* | Libas | 720 | 200 | - | - | - | - | 0 | 0.26 | 9 | 5.6 (0.7) |
| 2012 | 8* | Libas | 720 | 200 | - | - | - | - | 440 | 0.19 | 7 | 6.3 (0.8) |
| 2014 | 9 | Kings Bay | 796 | 265 | 11 | 9 | 0.2 | 238 | 68 | 0.23 | 8 | 8.0 (2.1) |
| 2014 | 10 | Kings Bay | 796 | 265 | 8 | 148 | 0.3 | 326 | 0 | 0.26 | 2 | 10.0 (3.5) |
| 2014 | 11 | Kings Bay | 796 | 265 | 7 | 93 | 0.8 | 345 | 25 | 0.28 | 8 | 7.0 (1.0) |
| 2016 | 12 | A. Selsbane | 677 | 182 | 4 | 74 | 0.6 | 280 | 0 | 0.22 | 8 | 13.0 (3.5) |
| 2016 | 13 | A. Selsbane | 677 | 182 | 5 | 160 | 0.5 | 27 | 170 | 0.25 | 3 | 13.0 (2.5) |

Table 2. Results from the linear mixed effects model: $log(Volume) \sim log(1-proportion hauled) + log(Seine Size) + (log(p) | Set), where proportion hauled is the amount of seine still in water. Credible intervals (95% CI) were estimated by simulating (10000 runs) the posterior predictive distribution.$

| Fixed effects | | | | | | | |
|---------------|-----------------------------------|--|--|--|--|--|--|
| Estimate | Std. error | t-value | 95% CI | | Variance | Std.Dev. | |
| 10.58 | 1.02 | 10.41 | 8.52 - 12.09 | Intercept | 0.15 | 0.39 | |
| 2.29 | 0.22 | 10.39 | 1.85 - 2.62 | Set | 0.47 | 0.68 | |
| 1.70 | 0.46 | 3.69 | 0.78 - 2.39 | Residual | 0.07 | 0.26 | |
| | Estimate 10.58 2.29 1.70 | Estimate Std. error 10.58 1.02 2.29 0.22 1.70 0.46 | EstimateStd. errort-value10.581.0210.412.290.2210.391.700.463.69 | EstimateStd. errort-value95% CI10.581.0210.418.52 - 12.092.290.2210.391.85 - 2.621.700.463.690.78 - 2.39 | Estimate Std. error t-value 95% CI Intercept 10.58 1.02 10.41 8.52 – 12.09 Intercept 2.29 0.22 10.39 1.85 – 2.62 Set 1.70 0.46 3.69 0.78 – 2.39 Residual | Estimate Std. error t-value 95% CI Variance 10.58 1.02 10.41 8.52 – 12.09 Intercept 0.15 2.29 0.22 10.39 1.85 – 2.62 Set 0.47 1.70 0.46 3.69 0.78 – 2.39 Residual 0.07 | |

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Figure 1. A draft of a common Norwegian mackerel and herring purse seine with the main
parts illustrated. Mesh size and twine diameter vary in the different parts of the seine, e.g.
34 mm meshes are common in the bunt, 39 mm in the main body of the seine and 157 mm
in the "bonett". Catches are crowded in the bunt before being pumped aboard. If catches
are released it is done by creating an opening in the bunt gavel or by allowing fish to swim
over the floatline.



460 Figure 2. A schematic overview of the monitoring setup, indicating the position of the
461 SN90 sonar transducer and the area covered by the acoustic beams in relation to the vessel
462 vertically and horizontally.



465 Figure 3. The method used to reconstruct the 3-D shape of a purse seine during hauling 466 from sonar screen images. The vertical fan was used to obtain cross sections of the seine 467 (a). An adaptive threshold was used to segment the image into regions (b). The regions 468 belonging to the seine were then extracted using watershed segmentation and the contours 469 of the regions was computed (c). Multiple slices were merged to construct a 3-D point 470 cloud and 3-D Delaunay triangulation was used to create a closed surface (sideview from 471 stern:d and planview fomr above: e). The scale in panels and c is in pixels while the other 472 scales are in meters.



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475 Figure 4. Estimated seine volume as a function of proportion of the seine hauled based on
476 3-D reconstructed seine shape from acoustic data. Colours represent different seine sizes
477 and the lines are values predicted from the linear mixed effects model matrix, including
478 95% credible intervals in the linear domain, 0.5 to 0.95 proportion seine hauled.



481 Figure 5. Predicted average fish density in the estimated seine volumes in median
482 (mackerel: 270t; herring: 190t), upper 95th percentile (mackerel: 650t; herring: 620t) and

483 maximum (mackerel: 985t; herring: 1100t) catch sizes in 2015 to 2017. The vertical

484 stippled lines represent the slipping limits (Norway mackerel = 0.87, EU mackerel = 0.8

485 and EU herring = 0.9). The white regions represent safe crowding limits for herring (150

486 kg m³) and mackerel (30 kg m³). The y-scale has been truncated to 170 kg m⁻³.

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Figure 6. Posterior distribution of the in-water seine volume predicted from the model matrix, including 95% credible intervals by purse seine set (1-13). The vertical line is at log (1-0.8), i.e. 80% haul proportion and haul proportions beyond this are to the left of the vertical line. The discrepancy between the predicted (blue) and observed (green) data to the left of this line indicates a decrease in model fit at around 80% haul proportion.