

# **Analysis and Design of Floating Prestressed Concrete Structures in Shallow Waters**

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## **ABSTRACT**

Prestressed concrete floating structures have been used for over a century with notable success in various parts of the world. However, there still exist issues related to the analysis and design, and the service performance of concrete floating structures. This paper highlights the design concepts, material behavior, analysis approaches and structural systems for floating prestressed concrete structures deployed in shallow waters. Material and design requirements related to prestressed concrete floating structures in particular are reviewed and potential technical challenges are identified. Moreover, some recommendations and suggestions are summarized as a guide for future practice.

**Keywords:** Analysis and Design; Floating Structures; Prestressed Concrete; Shallow Waters.

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1 **1. BACKGROUND**

2 The use of concrete in floating structures dates back to the early twentieth century. The first  
3 reinforced concrete sailing vessel, *Namsenfjord*, was built in Norway in 1917 [1]. Subsequently,  
4 hundreds of concrete ships were built in the first and second world wars due to the shortage of  
5 steel. In particular, two vessels were constructed of prestressed concrete (PC) precast cellular  
6 modules during World War II [2]. In the late 1950s, some ocean-going barges made of pre-  
7 tensioned concrete were designed and constructed in the Philippines. In 1975, the world's first  
8 large PC floating liquefied petroleum gas (LPG) storage vessel was constructed and deployed in  
9 Java Sea [3]. The vessel hull was designed and constructed as a post-tensioned concrete segmental  
10 structure to carry twelve independent steel tanks with a total capacity of 375,000 barrels. As the  
11 largest existing PC floating barge in the world, N'Kossa Oil Production Unit, was constructed in  
12 1996 off the coast of Congo. It measures 220 m in length, 46 m in width and 16 m in depth. The  
13 N'Kossa barge has successfully operated on site without interruption for 20 years [4, 5]. In 2002,  
14 the world's largest concrete floating dike, 352 m long and 28 m wide, was installed in Monaco  
15 harbor, which serves as a breakwater as well as a cruiser terminal. It was built in a 15 m deep dry  
16 dock and towed to Monaco for installation. It is expected to fulfill its functions for 120 years [6].

17 For the purpose of oil exploration and production, the first major base-supported concrete  
18 offshore structure, Ekofisk tank, was installed in 1973 in the North Sea. Since then, more than 40  
19 concrete fixed offshore platforms have been built in the North Sea, the Gulf of Mexico and West

20 Africa [7]. These offshore concrete platforms have performed extremely well in the seawater  
21 environment with little maintenance. In 1995, an innovative type of floating concrete platform  
22 structure, known as tension-leg platform (TLP), was first installed at the Heidrun field of the North  
23 Sea at a water depth of 345 m. In the same period, Troll Oje's floating platform, a semi-submerged  
24 concrete hull anchored by catenary moorings, was also built in the deep waters of the North Sea.

25 For some metropolis with coastal areas, such as Singapore, Shanghai and Tokyo, there is a  
26 need for usable space expansion to address the issue of land scarcity in an urban setting. Previous  
27 experience shows that land reclamation and the use of floating structures are two main options to  
28 increase usable space to accommodate industry facilities, habitation and infrastructure as the city  
29 grows and develops. Compared to land reclamation, floating structures are preferred because they  
30 are more environmental friendly and require less construction costs, especially when the water  
31 depth is large and the seabed is soft.

32 Most existing floating concrete structures have been located in deep seawater area, and  
33 may not be suitable or appropriate for shallower coastal areas. Figure 1 presents two floating  
34 concrete piers located in shallow coastal areas. According to previous engineering experiences,  
35 one major difference between floating structures in deep and shallow seawater areas is in the  
36 mooring system, whose function is to keep the structure in position and prevent it from drifting  
37 under critical sea conditions [8]. As compared to conventional mooring systems, like chain/cable,  
38 tension leg and others, the dolphin - fender system (Figure 2 (a)) is more suitable for floating  
39 structures in shallow waters because it can effectively restrict the lateral motions [9]. The dolphin

40 - fender mooring system was first adopted in the two floating oil storage bases at Kamigoto and  
41 Shirashima islands in Japan, and has since been used for other facilities [10, 11]. Figures 2 (b) and  
42 (c) show practical lateral and roller fenders installed at the interfaces between the dolphin and  
43 floating structure, which are able to undergo large deformations and absorb kinetic energy of  
44 floating structures [9]. When the topside is to be installed on the substructure, the intersection  
45 should be carefully designed to take account of interface shear forces. Given that floating structures  
46 often undergo relatively larger displacement than fixed structures, it is preferable that the topside  
47 structure can be de-coupled from the floating substructure's deformation. Due to the lack of  
48 documented interface configurations from existing concrete floating structures, engineering  
49 solutions from FPSO can be referred herein and they include the use of: (1) multiple snipped  
50 column supports; and (2) supporting stools fitted with roller and sliding joints or elastomeric pads  
51 [12, 13].

52 This paper provides a critical review of the design considerations and requirements  
53 pertaining to materials and analyses for general purpose floating concrete structures. Issues  
54 pertaining to PC floating structures deployed in shallow waters are highlighted, and some  
55 recommendations are made.

## 56 **1.1 Characteristics of PC Structures in Seawater Environment**

57 Marine structures have been built of iron-and-steel for more than a century due to historical reasons.  
58 However, engineering experience shows that, when properly designed and constructed under strict  
59 quality control, prestressed concrete may be a preferred material over steel for floating structures

60 because of its excellent durability and corrosion resistance [3]. The advantages of prestressed  
61 concrete over steel in the seawater environment have been recognized by many researchers [14-  
62 16], among which the main ones are:

- 63 (a) the use of concrete material generally results in a lower initial construction cost;
- 64 (b) large structures can be assembled with precast components integrated by post-tensioning  
65 tendons and cast-in-place (CIP) joints, leading to easier construction;
- 66 (c) the concrete shows superior durability in seawater environment, which reduce the costs for  
67 maintenance, inspection and repair;
- 68 (d) concrete structures result in reduced damages caused by fatigue-type loadings;
- 69 (e) concrete structures have larger local and global stiffnesses, and show superior performance  
70 in withstanding accidental impact loads;
- 71 (f) with proper mix design, high-performance concrete shows excellent corrosion resistance;  
72 moreover, prestressing keeps the concrete in compression, which improves water tightness  
73 and limit crack formation in the structural members; and
- 74 (g) concrete structures have superior thermal insulating and fire resistance properties.

## 75 **1.2 Special Design Considerations for Floating Structures**

76 The application of concrete to floating structures in the seawater environment usually requires  
77 more extensive considerations than typical land-based concrete structures due to different loading  
78 conditions and environmental situations [17-19]. Some special considerations are as follows:

- 79 (a) the self-weight of floating structures are automatically balanced by the buoyancy force,

80 and there is no need for massive and expensive supporting foundations;

81 (b) sizing of the floating structures depends on the function and environmental conditions,

82 such as current, wave and wind; the design may be dominated by peak loads from

83 permanent and variable actions or by fatigue strength due to cyclic environmental loads;

84 (c) possible accidental events need to be considered in design, such as vessel collision and

85 explosion, to ensure overall safety;

86 (d) unlike land-based constructions with their foundations poured in place, floating structures

87 are often constructed at shore-based sites remote from the installation site; forces during

88 construction and towing may impose different stresses than those encountered by the

89 structural elements when in service; and

90 (e) owing to the corrosive sea environment, floating structures have to be provided with a good

91 steel corrosion protection system.

### 92 **1.3 Design Guidelines**

93 The design of floating PC structures should follow rules and regulations for general concrete

94 structures laid down by government authorities and classification societies [20]. Although no

95 specific design codes and standards are found for PC floating structures, relevant design

96 philosophy and criteria for offshore concrete structures can be referred to. In particular, the

97 American Concrete Institute (ACI) Committee 357 has published a report on floating and float-in

98 concrete structures, which can be considered as a design guide [2]. Other guidelines such as EN

99 1992 Eurocode 2: Design of Concrete Structures [21], Canadian standard CSA S474 Concrete

100 Structures [22], DNV-OS-C502 Offshore Concrete Structures [23], DNV-OS-C503 Concrete LNG  
101 Terminal Structures and Containment Systems [24], ISO 19903 Fixed Concrete Offshore  
102 Structures [25], OTG-02 Floating Liquefied Gas Terminals [26] and Japanese Floating Bridge  
103 Design Specifications (JFBDS) [27] also provide useful information.

## 104 **2. MATERIALS**

105 Materials used in floating PC structures should provide the required performance during the  
106 construction, service and operation phases throughout the prescribed design life of the structure.

### 107 **2.1 Concrete**

108 The material requirements vary with the environmental conditions in which floating PC structures  
109 are constructed. According to EN 1992, exposure class XS3 is applicable for structural members  
110 in the tidal, splash and spray zones, and should generally be adjusted accordingly for floating  
111 concrete structures in coastal areas [21]. This exposure class requires the choice of adequately  
112 durable concrete for corrosion protection of reinforcing and prestressing steels. In general, the  
113 concrete should have adequate strength for the purpose of prestressing and installation. It should  
114 be of a sufficiently low density so as to facilitate buoyancy of the structure and to carry a higher  
115 payload. Thus, the concrete mixture proportions for general-use floating structures must be tailored  
116 to meet the specific requirements of density, strength and durability. As for floating fuel storage  
117 and production structures, special requirements of fire-resistance should also be taken into  
118 consideration. In addition, the prevention of pollution needs to be carefully handled in accordance

119 with MARPOL Rules [28].

### 120 **2.1.1 Concrete Density and Strength**

121 Both Normal Weight Concrete (NWC) and Light Weight Aggregate Concrete (LWAC) can be used  
122 in floating PC structures. LWAC is made with lightweight aggregates having a density of 20-35%  
123 less than NWC. In order to achieve weight reduction and a shallower draft, LWAC with a density  
124 lower than 2000 kg/m<sup>3</sup> is recommended. In some situations, it may be beneficial to use NWC in  
125 the lower portion and LWAC in the upper portion of floating structures in order to lower the center  
126 of gravity and consequently improve the stability of the structure. Alternatively, Modified Normal  
127 Density Concrete (MNDC) produced by partly replacing the natural coarse aggregates with high-  
128 quality structural lightweight aggregates can serve as a compromised material option for floating  
129 structures. In-situ MNDC products with a reduced density of 2250 kg/m<sup>3</sup> and satisfactory  
130 mechanical properties equal to NWC have been successfully achieved and applied in existing  
131 engineering practices, such as in the Hibernia Concrete Platform, Troll GBS Platform and others  
132 [29, 30].

133 The required concrete mix and strength shall be established based on the aggressiveness of  
134 environment and the design service life as well as for the purpose of introducing prestress. The  
135 service life of floating concrete structures is generally expected to be between 50 and 100 years  
136 with preferably a low maintenance cost. Table 1 lists the minimum concrete strength classes  
137 specified in various codes and standards for PC structures in seawater environment. Specifically,



138 EN 1992 requires a minimum concrete cylinder compressive strength,  $f'_c$ , of 45 MPa (6,500 psi)  
139 for concrete structures with a design working life of 100 years in the seawater environment. It is  
140 worth mentioning that common values of compressive strength,  $f'_c$ , used for PC structures in the  
141 United States are between 35 and 70 MPa [31].

142         Significant progress has been achieved in the development of high strength LWAC, thus  
143 placing concrete in a more competitive position as a material for floating structures. In the  
144 engineering practice, compressive strengths of 83 MPa (12,000 psi) and 62 MPa (9,000 psi) are  
145 normally achievable for NWC and LWAC [2]. High-strength LWAC can now be economically  
146 produced by ready-mix concrete suppliers, and it can therefore be supplied for the construction of  
147 floating structures.

148         The relationship between density and compressive strength for both NWC and LWAC has  
149 been investigated by many researchers [32-34]. Figure 3(a) shows that the compressive strength  
150 of NWC increases with density, but a relatively large variation exists in the relation. As for LWAC,  
151 the compressive strength is highly dependent on the type of lightweight coarse aggregates used.  
152 Figure 3(b) shows a positive correlation between these two properties for different types of LWAC.  
153 Because of the higher aggregate strength, expanded clay, slate, shale are commonly utilized for  
154 lightweight concrete structures. Careful selection of the lightweight aggregate is important to  
155 ensure that the desired compressive strength could be achieved.

## 156 **2.1.2 Durability**

157 As one of the key characteristics, durability is essential to ensure the functionality of floating  
158 concrete structures in expected exposure environments throughout their required service life.  
159 Although a minimum level of compressive strength is commonly required in structural design, it  
160 should be noted that compressive strength cannot be considered as a surrogate test to ensure  
161 durable concrete [35]. While there may be a general trend that both properties improve in the same  
162 direction, no evidently positive correlation was observed between compressive strength and  
163 durability [36-38]. Concrete that meets only the strength requirement may fail to develop the  
164 expected durability. Different mixture proportions, consolidation practices, curing techniques and  
165 other aspects may produce concrete with similar strengths but different durability levels. Therefore,  
166 appropriate quality control system and corresponding practices throughout the full process,  
167 including mixture design, structural layout and construction process, are essential to the production  
168 of high quality durable concrete products.

169 The concrete durability is influenced by various deterioration mechanisms in different  
170 environmental conditions, including chloride ingress, alkali-aggregate reaction, sulfate attack,  
171 carbonation, abrasion and others. According to existing engineering practices, for the severe sea  
172 environment, especially in the spray and tidal zones, the deterioration of floating structures arising  
173 from chloride-induced corrosion of the reinforcing and prestressing steels is a main cause of  
174 concern [39]. By proper mixture proportioning, concretes with low permeability and low seawater  
175 reactivity can be used to alleviate this problem. To achieve this, a low water to cementitious

176 material ratio ( $w/cm$ ) coupled with the addition of silica fume and/or fly ash can effectively reduce  
177 the permeability of concrete and improve chloride penetration resistance [40, 41]. For concrete  
178 made with  $w/cm$  of 0.40 and 0.50, chloride-ion permeability increases to approximately 4 to 6  
179 times greater than that for concrete made with  $w/cm$  of 0.32 [42]. A desirable low  $w/cm$  value (0.40  
180 maximum) is specified by ACI Committee 357 for fixed offshore concrete structures in splash  
181 zones [43]. Similarly, the Norwegian Public Roads Administration set an upper level of  $w/cm$  value  
182 of 0.38 for the most exposed parts of the bridges in marine environments [44]. ACI reported that  
183 fly ash is typically added to concrete mixture in amounts of 10 to 30% by mass of cement in large  
184 marine structures to improve the resistance against chloride-induced corrosion [42]. The use of  
185 silica fume works in several ways to reduce the risk of corrosion [45-47]. Figures 4(a) and 4(b)  
186 show a decrease in chloride penetration with silica fume replacement. Silica fume is known to  
187 enhance concrete durability by lowering the chloride diffusion coefficients, and a low level of  
188 silica fume replacement could reduce the diffusion values rapidly [48].

189         Also, the provision of sufficient concrete cover for reinforcing and prestressing steel would  
190 establish a barrier against the seawater environment, which helps to improve durability of the  
191 structure. Significant research studies indicated that 25 mm concrete cover is inadequate for  
192 chloride protection of steel reinforcements, even if the  $w/cm$  value is as low as 0.30. Experimental  
193 tests also show that chloride ingress reaches to a depth of 50 mm, and the chloride content can be  
194 very high in the outer 12 mm, even in high-quality concrete [49, 50]. Van Daveer and Sheret  
195 recommended that a design nominal cover of at least 65 mm over reinforcing steel be provided

196 while Kjaer suggested that typical concrete cover should be 75 mm to reduce the likelihood of  
197 corrosion in chloride environments [51, 52].

198 Table 2 lists the minimum concrete cover specified by various codes and standards for PC  
199 structures in seawater environment, where, in particular, EN 1992 designates a minimum concrete  
200 cover of 45 mm and 55 mm for reinforcing and prestressing steels, respectively. According to the  
201 requirements specified in DNV-OS-C502, the concrete cover shall not be less than 70 mm for 100-  
202 year design lifetime in tidal, splash and spray zones. Moreover, ISO 19903 indicates that a  
203 minimum of 50 mm and 90 mm is adequate as concrete cover to reinforcing steels and prestressing  
204 tendons, respectively. Herein, it is recommended to adopt 50 mm and 70 mm as the minimum  
205 concrete cover for reinforcing and prestressing steels without the consideration of construction  
206 tolerances. However, when concrete with low-permeability and high chloride penetration  
207 resistance is used, a reduction in concrete cover may be allowed in design.

208 When it comes to the durability performance of floating concrete structures in practice,  
209 engineers should not rely solely on appropriate mixture proportion and concrete cover. Good  
210 quality control related to operation and construction phases should also be ensured, including  
211 workmanship, curing and other aspects. For instance, proper consolidation practices are vital to  
212 avoid segregation and honeycombing in concrete, which can help to secure uniform concrete with  
213 low permeability [42]. Besides, the hydration of the cement can be enhanced with good curing,  
214 which is also beneficial in reducing permeability. Acker reported that excessive early thermal  
215 stresses should be carefully handled to prevent initial crack formation [55]. ACI suggests that it is

216 necessary to specify a minimum of 7-day uninterrupted moist-curing or membrane-curing.  
217 Furthermore, long-term inspections on in-service floating structures are useful to monitor the  
218 concrete durability performance and detect the level of deterioration, which will provide engineers  
219 with clues on the necessity of remedial works.

### 220 **2.1.3 Discussion**

221 LWAC may offer the following advantages over NWC in improving the serviceability of floating  
222 structures in seawater environment: (a) its low density helps to decrease the draft and bring extra  
223 buoyancy for imposed loads; (b) it provides a higher resistance to micro-cracking due to the  
224 reduced modulus of elasticity (MOE) of the aggregates; (c) it leads to lower stress as caused by  
225 creep and shrinkage; and (d) it is expected to have higher fire resistance because of a lower thermal  
226 conductivity and coefficient of thermal expansion [2].

227 Table 3 shows concrete mix designs for some existing floating structures in Norway, Japan  
228 and United States [56-58]. Note that the values for Norwegian floating concrete structures are in  
229 terms of cube compressive strength, while cylinder compressive strength are used in Japan and the  
230 United States. It is seen that either lightweight fine aggregate or coarse aggregate has been used to  
231 reduce the density of concrete. Besides, a relatively low water to cementitious material ratio ( $w/cm$ )  
232 was used to give higher compressive strength, where cementitious materials include cement, silica  
233 fume and fly ash. Silica fume or fly ash are adopted to improve resistance to chloride penetration.  
234 It would thus be challenging to develop a LWAC mix with a density less than  $1800 \text{ kg/m}^3$  and

235 compressive strength more than 45 MPa that have adequate durability in seawater environment.

236 In recent years, great efforts were devoted to exploring unconventional concrete products  
237 for use in the marine environment. Geopolymer has attracted considerable attention and is  
238 considered to be an alternative to ordinary Portland cement because of its advantageous properties,  
239 which include good chemical resistance, low permeability and excellent fire resistance behaviour  
240 [59-61]. However, it presents significant challenges to work out generalization of water-  
241 geopolymer solids ratio, bond between reinforcement and geopolymer paste, long-term durability  
242 behaviour and stable mix designs in the field [62]. Furthermore, it should be noted that no existing  
243 floating concrete structures are found to be constructed with geopolymer concrete. In view of this,  
244 there is a great need to perform further research studies on geopolymer concrete before applying  
245 it in floating structures.

## 246 **2.2 Reinforcing and Prestressing Steels**

247 The steel reinforcement and prestressing system used for general-purpose floating concrete  
248 structures are principally identical to those used in ordinary onshore structures. Reinforcing and  
249 prestressing steels should be suitable for the intended service and operation conditions, and have  
250 adequate properties and viable detailing layout to comply with the relevant standards.

### 251 **2.2.1 Steel Grade**

252 While prestressing steel may be used to eliminate most tensile stresses in PC structures, reinforcing  
253 steel are still needed as shear reinforcement or supplementary reinforcement in regions subject to

254 high local stresses. Characteristic yield strength values of common steel reinforcement specified  
255 in the EN 1992 range from 400 MPa to 600 MPa. In the United States, ASTM standardized  
256 properties of reinforcing steel are widely used; and the yield strengths of commonly used steel  
257 grades (Grade 40, 50, 60, 75) range from 280 MPa to 520 MPa.

258         The most common prestressing steel used in the industry is the 7-wire strand with diameters  
259 of 12.9 mm or 15.7 mm, which is used either singly for pre-tensioning or in bundles to form multi-  
260 strand tendons. Larger post-tensioning tendons comprise 7, 12, 19, 27 or more strands. The tensile  
261 strength of the strands typically ranges from 1670 MPa to 1860 MPa, and strands are commonly  
262 stressed up to the limit of 75% of ultimate strength during the construction. High-strength bars are  
263 available in diameters ranging from 15 mm up to 75 mm, and are used in post-tensioned connection  
264 design and some temporary works. The typical minimum ultimate characteristic tensile strength is  
265 between 1000 MPa and 1080 MPa in practice [31].

### 266 **2.2.2 Layout and Detailing**

267 Reinforcing and prestressing steels shall be placed in such a way that casting of concrete will not  
268 be obstructed and sufficient bond between the concrete and steels can be achieved. This is  
269 facilitated by specifying minimum steel spacing, which are commonly controlled by aggregate size  
270 and bar/duct diameter. Table 4 lists the minimum spacing of individual prestressing tendons and  
271 ducts as specified in EN 1992 and ACI 318, where  $\phi$  is the bar diameter and  $d_g$  is the maximum  
272 size of aggregate. Note that values specified in EN 1992 are clear spacing while those in ACI 318

273 are center-to-center spacing. It can be seen that the effect of concrete strength is considered in ACI  
274 318 to determine the minimum spacing, but the critical parameter, and maximum size of aggregate,  
275 are not included. Taking a pre-tensioned concrete beam for example, with  $f_c' = 45$  MPa,  $d_g = 20$   
276 mm,  $d_b = 12.7$  mm,  $\phi = 20$  mm, the minimum spacing values determined from EN 1992 and ACI  
277 318 are 40 mm and 44.5 mm, respectively.

### 278 **2.2.3 Discussion on Corrosion Protection**

279 The corrosion of reinforcing and prestressing steels is a critical issue in the service of floating  
280 concrete structures in a seawater environment. An effective method to address the corrosion issue  
281 is the application of fusion-bonded epoxy coating. Where the coating adheres tightly to the steel,  
282 the epoxy prevents the steel from acting as a cathode to support corrosion at specific locations.  
283 Besides, the use of stainless reinforcement is preferred by engineers because it can tolerate chloride  
284 levels higher than ordinary carbon steels [63]. Stainless steel does not rely on concrete for its  
285 corrosion protection and is a straightforward solution when concrete is subject to the ingress of  
286 chlorides from the marine environment, thus a relatively smaller concrete cover value is required  
287 in the engineering practice. Some alternative protection approaches, such as galvanic cathodic  
288 protection system, impressed current cathodic protection system, chemical corrosion inhibitors and  
289 others, can also be utilized to resist corrosion in severe exposure conditions.

### 290 **2.3 Application of Fiber-reinforced Polymer (FRP)**

291 Fibre-reinforced polymers (FRPs) are composite materials that are made of fibers embedded in



292 polymeric resin. FRP reinforcements have been increasingly used in various structural applications  
293 in severe environments as they do not corrode like steel reinforcement. The most common fibres  
294 used in FRP reinforcing bars and prestressing cables are glass, carbon and aramid, and more lately,  
295 basalt fibres. FRP bars normally have higher tensile strength, but lower Young's modulus, as  
296 compared to conventional steel bar and wire. All types of fibres exhibit a linear-elastic behavior  
297 under tensile loading up to failure without showing any plastic behavior. Carbon fibre-reinforced  
298 polymer (CFRP) bars have relatively higher tensile strength and modulus of elasticity compared  
299 to other types of FRP bars.

300 The durability of different FRP elements in seawater environment has been investigated by  
301 many researchers [64-67]. For concrete structures exposed to the seawater environment, it is  
302 difficult to distinguish the effects of chloride attack and degradation caused by moisture diffusion  
303 of the fibres. In general, CFRP and aramid fibre-reinforced polymer (AFRP) reinforcements are  
304 insensitive to chloride ions. Conversely, glass fibre-reinforced polymer (GFRP) reinforcements  
305 can be seriously damaged in a marine environment or in the presence of de-icing salts [64].  
306 Burgoyne reported that CFRP bars show little degradation with time when exposed to combined  
307 chloride moisture attack, while up to 50% strength and stiffness losses are observed in AFRP and  
308 GFRP bars. [68]

309 Wolff and Miesslerer [69] claimed that carbon and glass fibres do not absorb water. On the  
310 contrary, water absorption in aramid fibres results in degradation of between 15 and 25% of

311 mechanical characteristics, which includes a reversible decrease in tensile strength and modulus  
312 of elasticity and irreversible decrease in fatigue strength [70]. Furthermore, wet/dry cycles in  
313 splash zones can cause the swelling of AFRP reinforcement and induce bond cracking. It is inferred  
314 that aramid fibres are not suitable for use in a marine environment, despite the low sensitivity to  
315 chloride.

316 ElSafty et al. [71] evaluated the characteristics of prestressing carbon fiber composite  
317 cables (CFCC) in severe environment and concluded that CFCC showed excellent performance,  
318 maintaining very high guaranteed tensile strength retention and elastic modulus retention after  
319 conditioning for over 7,000 hours in an alkaline solution at 60°C. Sen et al. [67] conducted  
320 experimental studies to assess the durability of carbon and aramid pretensioned elements in the  
321 marine environment. Test results indicated that AFRP is not the ideal candidate for replacing steel  
322 in pretensioned elements deployed in tidal waters. When CFRP is used to replace steel in  
323 pretensioned elements, driving stresses should be carefully monitored to prevent any damage.

324 Adequate bond strength between FRP bars and the concrete is required to ensure the  
325 satisfactory structural performance. Significant research studies have been performed to  
326 investigate the bond behavior between FRP bars and the concrete, and it is observed from a large  
327 amount of pullout tests that various key parameters influence the bond performance, such as  
328 concrete compressive strength, bar cross section, embedment length and others [72-78]. Okelo  
329 reported that the actual pullout of FRP rebars occurs for shorter embedment lengths with higher

330 concrete compressive strength, while the splitting failure mode happens for longer embedment  
331 length with lower compressive strength [72]. Smaller diameter FRP bars develop relatively higher  
332 bond strengths as compared to larger diameter bars. The bond strength of FRP bars is typically 40  
333 – 100% that of steel rebars for the pullout failure mode. No significant difference is observed  
334 between the bond strengths developed by CFRP and GFRP bars, while AFRP bars show slightly  
335 lower bond strengths [74].

336 In view of the above, CFRP shows more favourable behaviours in terms of mechanical  
337 characteristics, chloride resistance and anti-moisture compared to GFRP and AFPR. Therefore,  
338 CFRP is a preferable substitute for the reinforcing and prestressing steels in general-purpose  
339 concrete floating structures. However, mechanical properties, strength and stiffness in particular,  
340 of FRP is known to significantly decrease with the increase of temperature [79]. Kumahara  
341 reported that 20% reduction of tensile strength occurs in CFRP and GFRP rebars occurs at a  
342 temperature of 250°C while the tensile strength reduction of AFRP can reach 60% at the same  
343 temperature [80]. Moreover, test results indicated that the bond strength between FRP bars and the  
344 concrete decrease by 80 ~ 90% as the temperature increase from 20°C to 250°C, while only 38%  
345 reduction of bond strength occurs in ordinary deformed steel bars for the same temperature range  
346 [73]. Therefore, the use of FRP may not be suitable where high temperature is of concern, such as  
347 in floating fuel storage facilities.

### 348 **3. ANALYSIS AND DESIGN CONSIDERATIONS**

### 349 **3.1 Design Philosophy**

350 Currently, most codes providing design rules and guidelines for concrete structures are based on  
351 the limit state design philosophy, and they can be referred to in the design of floating concrete  
352 structures. In general, two limit states, serviceability limit state (SLS) and ultimate limit state  
353 (ULS), are specified. Various design situations are taken into consideration, that is, persistent  
354 situation in normal use, transient situation under temporary conditions, accidental situation under  
355 exceptional conditions (e.g. fire and explosion) and special situation under tsunamic action.

### 356 **3.2 Action Effects**

#### 357 **3.2.1 Actions**

358 Table 5 lists three main categories of actions specified in EN 1990 for common structural designs:  
359 permanent (G), variable (Q) and accidental actions (A). For the design of floating concrete  
360 structures, environmental loads are predominant among various action effects. Representative  
361 actions include: buoyancy, wind loads, wave loads, hydro-dynamic loads induced by waves and  
362 currents, wave induced inertia forces and others. Note that floating structures are independent of  
363 tidal effects and storm surges. Possible approaches for calculating the environmental loads include  
364 a quasi-static procedure and a time- or frequency-domain dynamic procedure [2]. In addition, load  
365 effects at the construction and transportation stages, such as launching, towing, erection and  
366 equipment installation, also need to be checked.

### 3.2.2 Combination of Actions

Realistic combinations of permanent, variable and accidental actions shall be taken into account for floating concrete structures, which should be the same as that used in the design of general concrete structures. EN 1990 defines three combinations that may need to be taken into account for designs at SLS, as described by

$$\text{Characteristic Combination: } \sum_{j \geq 1} G_{k,j} + P + Q_{k,1} + \sum_{i > 1} \psi_{0,i} Q_{k,i} \quad (1)$$

$$\text{Frequent Combination: } \sum_{j \geq 1} G_{k,j} + P + \psi_{1,1} Q_{k,1} + \sum_{i > 1} \psi_{2,i} Q_{k,i} \quad (2)$$

$$\text{Quasi-permanent Combination: } \sum_{j \geq 1} G_{k,j} + P + \sum_{i \geq 1} \psi_{2,i} Q_{k,i} \quad (3)$$

where  $G_{k,j}$  is the characteristic value of permanent action  $j$ ;  $P$  is the relevant representative value of prestressing action;  $Q_{k,1}$  and  $Q_{k,i}$  are the characteristic values of the leading variable action  $1$  and the accompanying variable action  $i$ ;  $\psi_0$ ,  $\psi_1$  and  $\psi_2$  are factors for combination value, frequent value and quasi-permanent value of variable actions.

The characteristic combination and frequent combination are normally used for irreversible and reversible limit states respectively, while the quasi-permanent combination is normally used for long-term effects. The combinations of action effects at ULS are defined according to various design situations and partial factors are specified for various actions. For general prestressed concrete structures, EN 1992 recommends a partial factor value of 1.0 for prestressing forces in persistent and transient design situations. For offshore concrete structures in the marine environment, DNV-OS-C502 and ISO 19903 suggest that the more conservative of 0.9 and 1.1 be used as the partial factor of prestressing forces. Specially for structures with FRP reinforcement,

387 DNV-OS-C502 indicates that more conservative values of 0.9 and 1.2 should be used.

### 388 **3.3 Analysis Approaches for Floating PC Structures**

389 Compared with general land-based structures, floating concrete structures have no associated  
390 foundations, and they interact with the surrounding seawater during the service life. The analysis  
391 of floating concrete structures typically comprises a two-step procedure: a global response analysis  
392 followed by detailed structural analysis. In the first step, the global response of floating structures  
393 and the associated hydrostatic and hydrodynamic pressures are estimated based solely on rigid  
394 body (hydrodynamic analysis) or simplified plates (hydro-elastic analysis).

395 In the second step, detailed structural analysis is performed using the first-step output, and  
396 cross-sectional forces and wave forces acting on the floating structures, as input. In this step, a  
397 simplified analysis approach or 2D/3D finite element (FE) method may be utilized, and stress  
398 distributions are obtained for further design purpose. The global response analysis and detailed  
399 structural analysis can be carefully decoupled or integrated, considering different design situations  
400 and computational capabilities.

#### 401 **3.3.1 Global Response Analysis**

##### 402 *3.3.1.1 Hydrodynamic analysis*

403 For general floating structures whose horizontal dimensions are comparable to its depth, it is  
404 permissible to conduct rigid-body hydrodynamic analysis because structural deformations are  
405 seldom of a magnitude sufficient to affect the calculation of environmental loading and structural  
406 motions. In hydrodynamic pressure estimations, the fluid surrounding the floating structure is often

407 assumed to be inviscid, incompressible and with irrotational motion. Under these assumptions, a  
408 fluid velocity potential exists and its spatial derivatives correspond to fluid velocity components.  
409 Potential flow theory works generally fine for large volume structures, where the dimension of the  
410 structure is comparable or even larger than the dominant wave length. Another condition for  
411 applying potential flow theory is that the viscous effect is small and it does not have a significant  
412 contribution to the overall hydrodynamic performance of the floating structure.

413 An illustration of the hydrostatic and hydrodynamic pressure (due to an incoming regular  
414 wave only) onto a 2D body at a representative time instant is presented in Figure 5. The length of  
415 the arrows represents the magnitude of the pressure. The hydrodynamic pressure due to incoming  
416 regular wave is derived based on the known velocity potential of linear regular wave. In reality,  
417 one has to consider the hydrodynamic pressure due to the scattering of incoming wave and body  
418 motion induced radiation wave, in addition to the hydrodynamic pressure due to incoming wave.

419 Potential flow theory has certain limitations in practice. For example in shallow waters,  
420 one has to evaluate the validity of the potential flow theory. Shallow water condition is defined  
421 when the ratio of water depth over the dominant wave length is smaller than 0.05. In shallow water  
422 conditions, the horizontal velocity of a fluid particle on the sea bottom is not zero and the horizontal  
423 fluid particle velocity on the body surface may still be relatively large as well. Viscous effects  
424 becomes important in such a scenario. For some specific tasks, one may have to apply the Navier  
425 Stokes equations to solve the fluid motion, while for other tasks, one may still be able to apply  
426 potential theory with viscous effect properly considered separately by other means like

427 computational fluid dynamics (CFD) analysis and model tests [81, 82].

428         Frequency domain hydrodynamic analysis is often performed in the first place due to its  
429 relative simplicity. Hydrodynamic forces and motion of the floating structure are solved at each  
430 frequency of interest [83]. Fluid velocity potential is governed by the Laplace equation, and the  
431 fluid velocity potential on the boundary of the fluid domain can be solved by the Boundary Element  
432 Method [84], for example. Once the velocity potential on the body surface is solved, one can obtain  
433 the hydrodynamic pressure distribution and further the integrated total forces and moments. John  
434 provided the earliest solution to this boundary problem by using the Green's function within a  
435 boundary integral formulation to solve for the wave scattering from floating bodies [85, 86].  
436 Wehausen and Laitone [87] published detailed description of the linear wave theory to give  
437 benchmark solutions for wave-structure interaction problems. By using the 3D panel code WAMIT,  
438 one can easily obtain the fluid velocity potential, hydrodynamic pressure and integrated forces on  
439 floating bodies [88]. The boundaries of the fluid domain include the free surface, sea bottom, body  
440 surface and far field surface.

441         The time domain approach is necessary when the transient response or the nonlinear effect  
442 is important for the floating structure. As a common approach, by applying Inverse Fourier  
443 transform, the frequency domain motion equation of the floating structure in waves is transformed  
444 into time domain [89, 90]. Nonlinear force terms can be added to this time domain motion equation  
445 directly. The radiation added mass and damping obtained from frequency domain analysis are  
446 represented as memory effect function in the time domain. Depending on the nonlinear behavior



447 of the problem under consideration, one may also choose to solve the fluid-structure interaction  
448 problem directly in the time domain, skipping the solution in the frequency domain [91]. The  
449 approach is often applied to solve strongly nonlinear problems such as slamming and sloshing. In  
450 the coupled analysis of the floating structure and its mooring/station keeping system in shallow  
451 water condition, time domain analysis is often required due to nonlinear behavior of the coupled  
452 system.

#### 453 *3.3.1.2 Hydro-elastic analysis*

454 Depending on the shape of the floating structure, it might be necessary to consider their  
455 flexibility/deformation in order to obtain a proper estimation of their response when deployed at  
456 sea. An example of this is the thin plate type of floating structure which can be a few hundred  
457 meters long and wide in the horizontal plane but only a few meters deep in the vertical direction.  
458 In this case, the flexible deformation of the floating structure has to be considered in its  
459 hydrodynamic response analysis on the one hand, while on the other hand, the deformation of the  
460 floating structure also changes the surrounding fluid motion. Hydroelastic theory needs to be  
461 applied in such a circumstance and a certain number of flexible modes in addition to the six rigid  
462 body modes have to be considered when solving the fluid velocity potential, hydrodynamic  
463 pressure, motion of the floating structures in wave and others [92]. The load effect due to this type  
464 of fluid-structure interaction is termed hydro-elastic load, which is important in design. Hydro-  
465 elastic analysis is thus necessary for the design of plate-type floating structures in order to assess

466 the dynamic motion and stresses due to wave action. Similar to hydrodynamic analysis, hydro-  
467 elastic analysis can be performed in both frequency domain and time domain [93-96]. The  
468 frequency domain approach is often used when determining the hydro-elastic response amplitude  
469 operator of the floating structure because of its simplicity and ability to capture the pertinent  
470 response characters in a steady state condition. A uniform isotropic plate model as well as  
471 thin/thick plate theory are generally used for hydro-elastic response analysis. Such a simple  
472 structural model is effective for the determination of global stiffness parameters that fulfil the  
473 requirements for serviceability and safety.

474 For plate-type floating structures constructed in the coastal area, the hydro-elastic response  
475 becomes sensitive to the variation in the seabed topography, especially in shallow waters. Under  
476 such circumstances, the conventional boundary element method using infinite/finite water depth  
477 Green function becomes inappropriate. Various techniques have been developed by researchers to  
478 address this problem associated with variable water depth, such as fast multipole algorithm (FMA)  
479 [97], localized finite element method (LFEM) [98], finite element method (FEM) [99, 100], Eigen  
480 function expansions in conjunction with step-like bottom approximation [101], and local-mode  
481 series expansions using coupled-mode technique [102].

482 For the purpose of reducing the hydro-elastic response of floating plate-type structures,  
483 many innovative approaches were proposed for the large floating structures designed in the past  
484 decade, such as the use of bottom-founded breakwaters close to floating structures [103], anti-  
485 motion devices attached to floating structures [89, 104], pneumatic air-cushion [105, 106], gill

486 cells [107], flexible line connectors [108], and others.

### 487 **3.3.2 Detailed Structural Analysis**

488 The hydrostatic and hydrodynamic loads derived from waves and structural motions will be used  
489 in the structural analysis to obtain detailed structural responses. Although the numerical modeling  
490 of the hydrodynamic behavior remains an open problem for both commonly used potential flow  
491 models and general CFD codes, on the structural side, the situation is slightly less complex because  
492 very efficient numerical tools based on finite element method (FEM) , such as ABAQUS and  
493 ANSYS, are available for both quasi-static and dynamic structural problems [109].

#### 494 *3.3.2.1 Simplified Analysis*

495 For a floating structure, the most common loads considered in the design include self-weight,  
496 hydrostatic pressure, hydrodynamic pressure from waves, wind load, current load, imposed loads,  
497 thermal effects and loads due to towing and construction. All these loads generally have both global  
498 and local effects on the structure.

499 Figure 6 illustrates the simplified analysis approach, in which global and local load effects  
500 are considered and superimposed. The approach is more suitable for the analysis of rectangular-  
501 shaped floating structures. For the global response, the entire structure is loaded as a beam when  
502 it is subjected to non-uniform wave conditions and asymmetric still-water loads. The local  
503 responses include stresses and deflections of the structural parts between major support points, that  
504 is, bulkheads, side shells and others. They are commonly caused by local hydrostatic and

505 hydrodynamic pressure distribution and cargo loads. As for the simplified analysis approach,  
506 global membrane and local bending actions are considered separately, and the corresponding  
507 responses can be determined with simple hand calculations in the early stage. The end conditions  
508 are normally approximated by engineers with assumptions of fixity, which may result in a certain  
509 degree of errors. Therefore, it is suggested that hand calculation solutions should be verified at a  
510 later stage by comparison with more accurate computer-aided structural analysis results, which are  
511 described in the next section.

#### 512 3.3.2.2 *Finite Element (FE) Analysis*

513 The concrete floating structure can also be analysed by modelling the structure as a complete unit  
514 by using finite element method (FEM) computer programs to calculate the overall structural  
515 responses. Current advanced FEM tools offers engineers a wide range of analysis sophistication  
516 which can be applied to a variety of concrete structures. The analysis sophistication level varied  
517 with different design stages as well as load intensities applied on the particular concrete structure  
518 [2]. Grosch et al. [110] suggested that several types of analyses could be conducted for floating  
519 structures, such as static linear FE analyses, static nonlinear FE analyses considering material  
520 and/or geometric nonlinearities and others.

521 Simple estimates of general behaviour are often used by engineers in preliminary design  
522 stage to determine initial sizing. The most common modelling procedure is to assume reinforced  
523 concrete structures to behave as a linear elastic composite material; thus, a linear FE model which

524 is a straightforward and relatively inexpensive could be used to solve the engineering problem.  
525 The typical linear FE analysis is effective and sufficient to evaluate internal forces in the global  
526 structural system at a relatively low level of loading.

527         When the load level becomes high and significant nonlinear behaviour exists, the results  
528 of the linear analysis would be inappropriate. Owing to the cracking of concrete and yielding of  
529 reinforcement steels, the reinforced concrete as a “composite material” behaves in an inelastic  
530 manner when subjected to actual load effects (material nonlinearity). Furthermore, large  
531 compressive forces and high slenderness ratios may cause significant second-order geometric  
532 effects. For these reasons, nonlinear structural analyses are generally adopted to assess the  
533 structural behaviour and load bearing capacity of critical members. Since such analyses are  
534 normally costly and time-consuming, they are usually introduced as further supplementary  
535 verification, confined typically to local analyses of critical sections. The use of nonlinear  
536 techniques is, in general, related to the ultimate limit state design.

537         Lately, significant progresses of nonlinear FE analysis have been made to achieve an  
538 efficient assessment on the global structural responses. Particularly, Dr.techn. Olav Olsen  
539 Company has developed a powerful design tool, ShellDesign, to perform nonlinear global FE  
540 analyses on large concrete structures with less time consumption by using the “consistent stiffness  
541 method” [111]. This new method makes it feasible to obtain nonlinear responses by iterative linear  
542 analyses, in which the element stiffness matrix is repeatedly updated according to the cracked shell  
543 section analysis results. The updated stiffness parameters are then applied in the linear-elastic

544 analysis as inputs, and the repeated process will continue until a specified stiffness convergence  
545 criterion is satisfied. The consistent stiffness method as well as ShellDesign have been extensively  
546 tested and verified in the design of concrete structures, and is expected to have broader applications  
547 in more engineering practices [19]. In Demark, the consulting company Ramboll has also  
548 developed a program which is able to calculate plasticity theory on complicated constructions, and  
549 similar products are under development by Technical University of Denmark (DTU) and the  
550 Concrete Component Association[112].

### 551 **3.3.3 Integrated Hydrodynamic-Structural Analysis**

552 The two-step analysis approach, described above, is commonly adopted in general engineering  
553 practice. This approach necessitates an efficient procedure for pressure transfer from a  
554 hydrodynamic model to a structural model. If this step is not performed properly, the final loading  
555 case will not be balanced and the resultant structural response will be incorrect especially close to  
556 the artificial supports. In that situation, some researchers tried to achieve an integrated  
557 hydrodynamic-structural analysis, which enables engineers to do more realistic simulations, check  
558 the numerical accuracy of the outputs in the intermediate steps, and obtain accurate and reliable  
559 final results. However, this one-step approach places a heavy demand on computer capacity, so  
560 that its application may be limited to small floating structures [109, 113]. It is worth mentioning  
561 that the Bureau Veritas Research Department has developed a numerical software, HOMER, to  
562 cover all the aforementioned hydro-structural issues [114].

### 563 3.3.4 Physical Model Testing

564 Besides computer-aided engineering tools, the assistance of physical model testing is favorable for  
565 the analysis of floating concrete structures to investigate irregular environmental action effects,  
566 determine hydrodynamic behavior for complex geometries and validate numerical approaches  
567 [115]. In planning physical model tests, geometric similitude, hydrodynamic similitude (Froude,  
568 Strouhal and Reynolds) and structural similitude (Cauchy) shall be satisfied to achieve similitude  
569 between the physical model and real structure [116]. A variety of materials, including paraffin wax,  
570 wood, foam, glass reinforced plastic and others, can be utilized for manufacture of scaled models.  
571 Appropriate environmental simulation is critical for the success of model testing. For wave  
572 simulation, it is very difficult to generate high-frequency wave components at a small scale, and it  
573 was suggested that the scale factor should not be smaller than 1:70 [116]. Current is often simulated  
574 by towing. Standard instruments are necessary to measure the responses, such as linear and angular  
575 potentiometers, load cells, accelerometers, pressure gauges, and others.

576 In shallow waters, the water particle has a horizontal velocity on the sea bed and water  
577 flow along the structure surface may increase as well, which will induce viscous effect. It is  
578 therefore crucial to evaluate the importance of this special phenomenon and physical model testing  
579 is suggested in the detail design of such concrete floating structures. In addition, test results from  
580 specific physical models can be used to validate computational fluid dynamics (CFD) models,  
581 which is a more economic numerical procedure to evaluate environmental action effects and can  
582 be applied to similar floating structures with few additional costs.

### 583 **3.4 Design Approaches and Detailing of Floating PC Structures**

#### 584 **3.4.1 General**

585 Durability requirements are critical for floating concrete structures to fulfil their function  
586 throughout the service lifespan. It is generally recommended that major structural components be  
587 designed such that tension stresses are eliminated or limited to very low values throughout the  
588 member thickness under normal service conditions [117]. In addition, the crack widths and  
589 corresponding reinforcing steel stresses should be controlled for all types of service loading [118].

590 EN 1992 specifies two criteria to control concrete cracking: decompression and crack  
591 width limitation. The decompression requires that all parts of the tendon or duct should lie at least  
592 25 mm within the concrete in compression. Cracking checks for prestressed concrete are carried  
593 out under frequent or quasi-permanent load combinations. For the control of cracking, EN1992  
594 tabulates bar size and spacing criteria to limit crack widths within appropriate values. Alternatively,  
595 formulae are provided for designers to calculate crack width. It is worth mentioning that ACI  
596 Committee [2] indicates that a common approach to prevent through-cracking is to require that a  
597 portion of the member remain in compression at all times.

598 Throughout the specified service life, floating concrete structures are subjected to repeated  
599 loading conditions due to the cyclic nature of environmental loads, which may result in serious  
600 fatigue problems. Two distinctive design methods, stress limitation control and comprehensive  
601 fatigue analysis, are used in practice to evaluate the structural members against fatigue failure. The



602 stress limitation control method assumes that structural members are safe against fatigue failure if  
603 allowable stress criteria for both concrete and reinforcing and prestressing steels are satisfied. If the  
604 specified stress range is exceeded, or the serious fatigue problem is likely to occur in specific  
605 structural members, a comprehensive fatigue analysis based on the cumulative damage theory  
606 becomes necessary in the design. The theory of cumulative damage uses a stress histogram  
607 comprising several constant stress range blocks to represent the long-term distribution of stress  
608 range:  $\sum_{i=1}^k \frac{n_i}{N_i} \leq \eta$ , where  $k$  is the number of load blocks,  $n_i$  is the actual load cycle number for block  
609  $i$ ;  $N_i$  is the load cycle number causing failure if load block  $i$  acts alone,  $\eta$  is the cumulative damage  
610 ratio, which is taken as 0.5 for structural members below or in the splash zone [23].

611           Extensive research studies have been performed on the fatigue issues of concrete structures.  
612 Internal microcracking is considered as the main cause of fatigue failure of concrete structures,  
613 and the microcracking initiates when the concrete compressive reaches  $0.7f_c$  [119]. For floating  
614 concrete structures, low-cycles of high-amplitude load effects can result in significant damages,  
615 like cracking and spalling, which should be handled with caution in design. In practice, cracks can  
616 open and close under subsequent cyclic loads at moderate magnitudes if there is no effective  
617 prestressing. Lately, a comprehensive R&D project “Innovation and Networking for Fatigue and  
618 Reliability Analysis of Structures (INFRASTAR)” has been initiated to predict the concrete  
619 infrastructure behaviour under fatigue load. Some research outcome has been achieved on damage  
620 detection, long-term cyclic effects and other aspects, and more significant achievements on fatigue  
621 behaviour of concrete structures are expected [120-122].

### 622 **3.4.2 Design for Prestressing**

623 PC structures are to a large extent designed to be uncracked under service load conditions. The use  
624 of high strength prestressing steel in place of a large quantity of ordinary steel reinforcement will  
625 decrease the weight of the structure, which would be advantageous in highly weight-sensitive  
626 floating structures [20].

627 The degree of prestressing of offshore concrete structures is often determined by  
628 counteracting the load effect of dominant actions such that no tensile stresses exist in the critical  
629 section, similar to the load balancing design philosophy proposed by Lin and Burns [123]. The  
630 prestressing effect is usually considered as a basic load in the global analysis. The time dependent  
631 losses of prestressing is taken into account by determination of an approximate single loss factor.

### 632 **3.4.3 Connector System**

633 Floating concrete can be built in drydocks in whole. However, some specific applications may also  
634 be assembled with modular units to facilitate the re-configurations if necessary. In this situation,  
635 mega-connector system is a critical component in the entire structure and should be carefully  
636 designed. A variety of connector designs have been developed in the past decades [124-126].  
637 Figure 7 presents two typical rigid connector systems, termed as male-female connector and  
638 frictional locking connector. Armin's connector design (Figure 6 (a)) consists of two male and  
639 female coupling members, which are placed diagonally on the floating module's sides adjacent to  
640 another module in order to align two modules. Vertical-oriented detachable pins are used to lock  
641 upper male and female coupling members after engagement. Similar devices have been developed

642 and adopted in the engineering practice, which utilize male and female coupling pairs, fitting and  
643 locking members to secure floating modules to each other. Hann-Ocean developed frictional  
644 locking connector to provide complete secured rigid connection between two floating modules, as  
645 shown in Figure 7 (b). The connector has two coupling parts, one each on one of the two adjacent  
646 floating modules. One part includes a downward directed receiving recess and the bearing surface  
647 increases in distance away from the abutment plane from top to bottom. The relative movement of  
648 two floating modules together causes the locking bars to drop down, resulting in a rigid connection.

649 In very large floating structures (VLFS), Fu et al. [127, 128] and Wang et al. [127, 128]  
650 proposed the use of hinge or semi-rigid connectors because they are found to be more effective in  
651 reducing the hydro-elastic responses. Riyansyah et al. [129] studied the effectiveness of semi-rigid  
652 joints in reducing the hydro-elastic response of a large floating structure modeled by  
653 interconnected beams. Gao et al. [130] further extended this idea and investigated the effect of  
654 flexible connectors by modeling VLFS with Mindlin plate theory. The response of VLFS  
655 connected by multiple hinge connectors were experimentally and numerically studied by Yoon  
656 [131]. Prestressing tendons are also utilized by practitioners in developing connector systems to  
657 achieve desired rigidity and meet design requirements. Figure 8 shows two adjacent floating  
658 modules connected with prestressing cables. When the modules is only connected at upper deck  
659 level, this connector system does not provide moment transformation between two modules. When  
660 prestressing tendons are arranged at both upper and lower deck levels, some amount of flexural  
661 bending resistance can be provided, which forms a semi-rigid connection.

#### 662 3.4.4 Structural Detailing

663 In addition to concerns for accurate assessment of design loads and stresses imposed on floating  
664 structures exposed to a highly variable set of service conditions, one should pay close attention to  
665 structural detailing as a mean of enhancing the service performance. The structural serviceability  
666 and, in some cases, the ultimate strength performance of a floating concrete structure will be  
667 greatly affected by details such as:

- 668 (a) Reinforcing steel lap splice and bond lengths in fatigue critical areas of the structure. For  
669 example, the lap length of prestressing development length should be increased by 50% if  
670 lap splices of reinforcement or pretensioning anchorage are subjected to cyclic tensile  
671 stresses greater than 50% of the allowable static stresses [119];
- 672 (b) Control of concrete crack widths and induced reinforcing steel stresses under service  
673 conditions. For the seawater exposure condition, the maximum crack width of structural  
674 members is recommended not to exceed 0.15 mm [132]. In usual practices for severe  
675 environments, the stress value in the steel reinforcement is limited to 120 – 140 MPa, which  
676 correspond to about  $0.33f_{yk}$ ;
- 677 (c) Adequate concrete cover over reinforcing and prestressing steel to avoid chloride-  
678 penetration corrosion in the coastal and offshore environment;
- 679 (d) Concrete mixture proportions that emphasize low permeability and high cement content;  
680 and
- 681 (e) Proper grouting and bonding of post-tensioning tendons, and proper preparation of post-

682           tensioning blockouts and anchorages.

### 683   **3.5 Special Considerations**

#### 684   **3.5.1 Fire Resistance**

685   In general, concrete is considered to be a better fire proofing material than structural steel for  
686   offshore oil or gas platforms. Two hydrocarbon fires were reported inside North Sea concrete  
687   platforms in 1970s. This accident resulted in approximately 10 to 20 mm deep surface scaling over  
688   a height of 5 to 10 m. This marginal impact is attributed to the large heat capacity and low thermal  
689   conductivity of concrete. No repair was found to be necessary, which clearly demonstrates the  
690   excellent fire resistance performance of concrete.

691           If fire is allowed to continue and concrete structures are exposed to extremely high  
692   temperature for a long time, it would suffer loss of strength and the steel reinforcement within the  
693   concrete may experience reduced capacity [19]. Lotfy et al. [133] carried out unstressed residual  
694   strength tests on LWAC mixtures made of three types of lightweight aggregates (furnace slag (FS),  
695   expanded clay (EC), and expanded shale (ES)) to assess their effects on the resistance against  
696   elevated temperatures. It is observed from the tests that the residual compressive strength reduced  
697   as the temperature was incrementally increased from 300°C to 600°C, and then to 900°C. The  
698   reduction in residual strength could reach up to 67% at 900°C, which may result in structural  
699   failure. The highest reduction in original compressive strength was recorded for LWAC mixtures  
700   made with FS aggregates followed by those with ES aggregates.

701 A significant amount of research work has been conducted on the effects of concrete  
702 mixture proportions to improve the fire resistance behavior. The use of fly ash is claimed to be  
703 effective in preventing strength reduction at elevated temperatures, which may be attributed to the  
704 improved interfacial property and the reduction in thermal conductivity [134, 135]. Some  
705 researchers also proposed to add polypropylene (PP) fibers to increase resistance to spalling caused  
706 by hydrocarbon fires [136, 137]. Severe spalling, 20% of total volume, was observed in normal  
707 concrete products during laboratory tests. By adding PP fibers in the concrete made with low-  
708 absorption aggregate, up to 60% less spalling volume can be achieved. In summary, it is suggested  
709 that fly ash and PP fibers be used in the concrete mixtures to improve the fire performance.

### 710 **3.5.2 Low Temperature**

711 Concrete itself shows satisfactory performances in low temperature conditions, which makes it be  
712 a preferable construction material for structures working in arctic areas or storage facilities  
713 carrying cryogenic liquids such as LNG (Liquefied Natural Gas). Well-known engineering  
714 examples include concrete offshore platforms off Sakhalin Island and in the Hebron oil field and  
715 many concrete LNG storage tanks [138, 139]. Previous research studies indicated that the concrete  
716 compressive strength and the posttensioning steel tensile strength do not reduce, but rather increase  
717 at low temperatures [140]. Also, prestressed concrete and prestressing tendons made of cold-drawn  
718 wire remain ductile at low temperatures. However, carbon steel rebars show a more brittle behavior  
719 at low temperatures. Therefore, ACI specifies tensile strength limits for different sizes of

720 reinforcing bars, for instance 83 MPa (12 ksi) for 10 mm (#3) and 12 mm (#4) bars and 69 MPa  
721 (10 ksi) for 16 mm (#5) to 22 mm (#7) diameter bars [141]. Also, prestressed concrete has been  
722 tested at extremely low temperatures e.g. -190°C, and proved to be a qualified material solution.

### 723 **3.5.3 Ship Collisions**

724 Concrete floating structures shall be checked against accidental impact actions from ship collisions  
725 to ensure the overall safety functions are not impaired. The design values for ship collision actions  
726 are characterized by kinetic energy, impact location, impact geometry and other relative parameters.  
727 The kinetic energy is determined on the basis of relevant masses, velocities and directions of ships.  
728 As indicated in DNV-OS-A101, the impact energy of vessels can be determined with the equation  
729  $E = 0.5(m_s + m_a)v^2$ , where  $m_s$  is the ship mass,  $m_a$  is the added ship mass, normally assumed to be  
730  $0.4m_s$  for sideways collision and  $0.1m_s$  for bow and stern collision, and  $v$  is the impact speed.  
731 Similar equation is also given by Norsok-004 for fixed installations, but no quantitative guidance  
732 was provided. DNVGL-OS-A101 specifies that the impact energy is normally not less than 14 MJ  
733 for sideways collision and 11 MJ for bow or stern collisions, which corresponds to a vessel of 5000  
734 tonnes moving at a speed of 2 m/s (4.5 mph) [142]. The impact energy may be distributed between  
735 floating structures, vessel and fender system, and most energy is assumed to be dissipated by  
736 plastic deformation [143]. Two approaches can be used to determine the structural effects induced  
737 from ship collisions: sophisticated nonlinear dynamic finite element analyses and energy  
738 considerations combined with simple elastic-plastic methods [144]. The latter option is described

739 in Norsok-004 for the design of offshore steel structures.

#### 740 **3.5.4 Stability Consideration**

741 Different with base-supported structures, special consideration on stability should be given to  
742 floating structures so that they can remain floating upright in various afloat conditions, including  
743 launching, towing, operating and others. One principal approach for stability control is to include  
744 sufficient numbers of compartments for ballasting at different parts of floating structures.  
745 Depending on specified load conditions, some compartments may need to be filled with water to  
746 certain levels to achieve adequate reserves of stability. Note that the existence of ballasting water  
747 changes the center of gravity in floating structures, and affects the stability behavior due to the free  
748 surface effect. The stability performance shall be evaluated for different compartment filling  
749 scenarios. For each of the possible filling scenarios, sufficient restoring moment when the structure  
750 starts heeling and/or trimming needs to be ensured. And the restoring moment versus heel/trim  
751 angle curve needs to be checked up to the maximum allowable heel/trim angle [145, 146].

752         Additionally, the use of compartments is beneficial to limit the accidental flooding to a  
753 small part of a floating structure, and manholes and bulkheads in the compartments are required  
754 to be sealed watertight. Single-compartment and two-compartment damages are recommended for  
755 concrete floating structures that are intended for infrequent and frequent towing, respectively [2].

#### 756 **4. CONCLUDING REMARKS**

757 A literature review on analysis and design of floating PC structures in coastal environment was



758 presented. Potential design issues and challenges are identified, and design suggestions and  
759 recommendations are summarized as follows:

760 1. For concrete floating structures, the weight can be supported with sufficient ballast  
761 volumes, and it is suggested to use LWAC so as to achieve a shallower draft. The design  
762 cylindrical compressive strength is suggested to be at least 45 MPa.

763 2. For the LWAC mixture proportions, expanded clay, slate, shale coarse aggregates are  
764 recommended for use due to their high aggregate strength. A low water to cementitious  
765 material ratio ( $w/cm$ ) coupled with the addition of silica fume can effectively reduce  
766 chloride diffusion and improve chloride penetration resistance. Moreover, fly ash and PP  
767 fibers may be used to improve fire and spalling resistance performance.

768 3. The minimum concrete cover for reinforcing and prestressing steel are recommended to be  
769 50 mm and 70 mm in the concrete floating structures subjected to the seawater environment  
770 respectively. When concrete with low-permeability and high chloride penetration  
771 resistance is used, a reduction in concrete cover may be allowed.

772 4. FRP reinforcement can be adopted in the floating concrete structures to address corrosion  
773 issues. Among different types of polymers, CFRP shows the most favourable behavior in  
774 terms of mechanical properties, chloride resistance and anti-moisture, and can be  
775 considered as a substitute for the reinforcing and prestressing steel.

776 5. Both serviceability and ultimate limit state should be considered in the design and analysis  
777 of concrete floating structures. In addition, combination of accidental actions shall also be

- 778 taken into account, including boat impact, blast and fire, tsunami and others.
- 779 6. For concrete floating structures deployed in shallow waters, it is vital to evaluate and  
780 quantify the importance of special phenomenon occurred in the shallow water condition.  
781 Model test is suggested for verifying a floating concrete structure design in shallow waters.  
782 CFD technique can be applied to provide practical estimation of viscous effect, which can  
783 then be applied in the global hydrodynamic analysis.
- 784 7. Risk assessment should be performed to ensure the safety of concrete floating structures  
785 throughout their service life, specifically, fire explosion and ship collision. Compartment  
786 ballasting approach is suggested for concrete floating structures to ensure sufficient  
787 stability.

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## 790 **Acknowledgement**

791 The authors are grateful to the Singapore Land and Liveability National Innovation Challenge  
792 Directorate, Ministry of National Development, National Research Foundation and JTC  
793 Corporation for providing the research grant to conduct this research on concrete materials for  
794 large floating structures on the sea.

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