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Highlights

- · Non-equilibrium approach for supersonic expansion of carbon-dioxide was presented.
- Phase-change intensity was calibrated on the basis of 150 experimental points.
- High quality of the motive nozzle mass flow rate prediction was obtained.
- <text> · Field results were analysed having regard vapour quality and velocity dis-

Non-equilibrium approach for the simulation of CO₂ expansion in two-phase ejector driven by subcritical motive pressure

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Abstract

A non-equilibrium approach was proposed for highly accurate modelling of the expansion process during two-phase flow in the convergent-divergent motive nozzle of an R744 ejector. Comprehensive mapping of the coefficients used in the source terms of the additional transport equation of the vapour quality was provided on the basis of four ejector geometries. The calibration range contained motive pressures from 50 bar to 70 bar, where the prediction quality of the homogeneous equilibrium (HEM) and relaxation (HRM) models, was unsatisfactory. The calibrated model was validated on the basis of experimental mass flow rate data collected from 150 operating points. The mapping results were utilised for final model derivation in the form of an approximation function for R744 expansion. The validation process resulted in satisfactory relative error below 10% for the vast majority of the cases. Moreover, 70% of the simulated cases were considered with a mass flow rate discrepancy below 7.5% in the inaccuracy. Finally, the selected cases were compared and discussed with the HEM approach on the basis of field results.

Keywords: transcritical ejector, two-phase expansion, non-equilibrium model, refrigeration system, R744, carbon dioxide

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1 1. Introduction

2 1.1. Natural refrigerants for refrigeration

The phase-down of synthetic refrigerants from CFC (chlorofluorocarbon) 3 and HFC (hydrofluorocarbon) groups was started by Montreal Protocol United 4 Nations Environment Programme (UNEP) (1987) and pushed forward by a meet-5 ing in Kyoto United Nations Framework Convention on Climate Change (UN-6 FCCC) (1997) and EU regulations European Commission (2014). Currently ratified by the European Commission (2018), the Kigali Amendment has been en-8 forced since the first day of 2019, making the phase-in of natural refrigerants an 9 even more global initiative. 10 Analysis of possible alternative refrigerants with low Global Warming Po-11 tential (GWP) concluded that natural refrigerants can overcome HFC and HFO 12 (hydrofluoroolefin) mixtures (Mota-Babiloni et al., 2015), (Purohit et al., 2017). 13 In the case of the main natural representative carbon dioxide (CO₂, R744), one 14

¹⁵ challenge is the application in hot climates due to its thermodynamic proper-

 $_{16}$ ties. Hence, substantial improvement in the CO₂ refrigeration technology was

¹⁷ pushed by the academic and industry sectors.

18 1.2. Ejectors in CO₂ refrigeration

The development of ejector technology has become an increasingly sub-19 stantial part of the state-of-the-art R744 refrigeration. Elbel and Lawrence, in 20 a comprehensive review of ejector technology in vapour-compression refrig-21 eration systems (Elbel and Lawrence, 2016), confirmed that cutting-edge re-22 frigeration is strongly connected with highly efficient ejectors. Moreover, these 23 authors concluded that there is still substantial potential to improve the ejec-24 tor systems with regard to the relations between the ejectors and other system 25 components. Another analysis of the current achievements and future per-26 spectives in the ejector technology was presented in the work of Besagni (2019). 27 That study contains a comprehensive review of current and possible ejector im-28 plementations. One of the developing areas is related to small units designed 29 for low ambient temperatures and thus low motive pressures between 50-60 30 bar, such as refrigerated sea water chillers (Bodys et al., 2018). 31

³² 1.3. Computational approaches for the CO₂ ejector modelling

Advanced tools from the scope of computational fluid dynamics were formulated by Smolka et al. (2013) and Lucas et al. (2014). The authors of these

studies used the homogeneous equilibrium model (HEM) assumption to sim-35 ulate two-phase flow inside an ejector. In this approach, mechanical and ther-36 modynamic equilibrium between the phases is assumed to result in instanta-37 neous evaporation processes. The described approach is suitable for high mo-38 tive pressures above the critical point where meta-stability effects are negligi-39 ble. In the study of Smolka et al. (2013), the commercial software Ansys Fluent 40 was used, whereas in the study of Lucas et al. (2014) OpenFOAM environment 41 was used. Both approaches allowed for the mass flow rate determination at ev-42 ery port of the ejector. The validation process resulted in motive nozzle mass 43 flow rate (m_{MN}) prediction with accuracy on an average level of 10%. In the 44 case of the suction nozzle stream, Smolka et al. (2013) reported approximately 45 20% for the suction nozzle mass flow rate prediction. In the study of Lucas et al. Δf (2014), the simulation result was the pressure lift recovery also at the level of 47 20% of accuracy. 48

The accuracy of the HEM approach proposed by Smolka et al. (2013) was 49 described extensively in a work by Palacz et al. (2015), where the authors sim-50 ulated a wide range of operating conditions (OC) and compared the experi-51 mental data. The authors focused on the relation between the motive and the 52 suction conditions and the resulting accuracy of the mass flow rate prediction. 53 The results showed that motive nozzle conditions are more crucial and can be 54 described as one of the main parameters that influence the prediction accuracy 55 of the m_{MN} . Moreover, the HEM approach was described as inaccurate up to 56 10% for high motive pressures above 75 bar. Decreasing motive pressures up 57 to 60 bar resulted in a decrease in the HEM accuracy to the level of 30%. This 58 trend was correlated with the meta-stability effects in the evaporation process, 59 which occur during expansion in the motive nozzle. 60

Meta-stability effects during two-phase flow have been reported in the nu-61 merical modelling literature. Moreover, advanced two-fluid approaches were 62 formulated for the water flow through the convergent-divergent motive noz-63 zle (Yixiang Liao, 2015). In that study of Yixiang Liao (2015), a simulation of 64 inter-phasial interaction based on the heat transfer, mass transfer and momen-65 tum transfer was described. In similar, a complex formulation for flashing flow 66 through a convergent-divergent nozzle was proposed by Dang Le et al. (2018), 67 where the thermal non-equilibrium between phases during the evaporation 68 process was simulated. However, in both studies (Yixiang Liao, 2015; Dang Le 69 et al., 2018), the mixing phenomenon and pressure recovery in the diffuser of 70 the ejector were not investigated. This level of complexity for two-streams flow 71 through the R744 ejector ducts based on the two-fluid approach were not pub-72

lished so far. The reasons could be located in the low computational time re-73 quired for ergonomic design tools as well as insufficient experimental data for 74 the aforementioned supersonic flow of carbon dioxide. Nevertheless, other ap-75 proaches were developed in order to model the non-equilibrium phase transi-76 tion and improve the prediction quality of the motive nozzle mass flow rate. In 77 particular, the homogeneous relaxation model (HRM) approach introduced in 78 the work of Bilicki et al. (1990) was utilised by several authors in the R744 sim-79 ulations. The HRM model equipped in a formulation for the relaxation time al-80 lowed for a delayed evaporation process, consequently leading to a higher mo-81 tive mass flow rate. Some first comparison of the HEM and HRM approaches 82 was delivered by Downar-Zapolski et al. (1996) where the HRM approach was 83 characterised as more accurate with regard to critical mass flow rate predic-84 tion, which was underestimated in the HEM simulations. The HRM approach 85 was adjusted for the R744 simulations in the work of Angielczyk et al. (2010) 86 and Colarossi et al. (2012). The accuracy of the motive mass flow rate predic-87 tion was still more than 10% for subcritical motive pressures. To extensively 88 compare the HEM and HRM approaches, Palacz et al. (2017a) implemented 89 the HRM formulation proposed by Angielczyk et al. (2010) onto the ejectorPL 90 platform described by Palacz et al. (2017b). The HRM results were compared 91 to the experimental data described in the previous work (Palacz et al., 2015) 92 where the HEM approach accuracy was mapped. That comparison proved that 93 the introduction of the relaxation time for a vapour quality field improves the 94 motive mass flow rate prediction by up to 5% for motive pressures higher than 95 65 bar. The authors concluded that the definition of the time relaxation should 96 be adjusted for specific conditions with regard to model constants proposed by 97 Angielczyk et al. (2010). Further improvement in the mass flow rate prediction 98 accuracy was delivered in the work of Haida et al. (2018c), where some modifi-99 cation of the previously proposed HRM approach was described. The authors 100 adjusted the coefficients in the relaxation time definition, obtaining high ac-101 curacy for motive pressure from 59 bar to 80 bar. In this region, the average 102 accuracy was 15%. Nevertheless, accuracy in regions below 59 bar of the mo-103 tive pressure still needs to be improved to provide proper computing tools for 104 designing the process of subcritical R744 ejectors. 105

A more advanced formulation of the phase change modelling in the R744 ejector was proposed in the work of Yazdani et al. (2012). A standard set of governing equations for continuity, momentum and energy supported by the additional vapour volume fraction was used. In the study of Yazdani et al. (2012), the approach called mixture was based on cavitation and boiling vapour gener-

ation, where the first term was proposed by Singhal et al. (2002) and the second 111 was modelled according to the multi-phase flow handbook (Carey, 2007). In the 112 case of both cavitation and boiling source terms, the coefficients need to be ar-113 bitrarily assumed. The authors did not describe the procedure of the coefficient 114 assessment. The obtained pressure distribution along the ejector axis was vali-115 dated against experimental data delivered by Nakagawa et al. (2009) with posi-116 tive results showing high potential of the approach utilised. On the other hand, 117 the authors did not analyse model accuracy in the subcritical region of the mo-118 tive pressures where the aforementioned HEM and HRM inaccuracy was rela-119 tively high. Finally, the capabilities of the approach proposed by Yazdani et al. 120 (2012) were limited to the prediction of mass entrainment ratio and pressure 121 lift for given motive conditions. In the work of Giacomelli et al. (2018), the HEM 122 approach described in the previous work (Giacom elli et al., 2016) was extended 123 into the mixture approach similar to that used by Yazdani et al. (2012). The 124 HEM approach was based on the enthalpy-based energy equation and real gas 125 properties in compressible flow as previously proposed in the work of Smolka 126 et al. (2013). However, the HEM approach studied by Giacomelli et al. (2016) 127 and by Giacomelli et al. (2018) was not validated in such a wide range of OCs as 128 in the case of Palacz et al. (2015). Moreover, the average accuracy in the mass 129 flow rate prediction was 15%, which was slightly higher than that obtained dur-130 ing validation processes presented in the papers of Smolka et al. (2013) and 131 Palacz et al. (2015). Hence, the mixture approach of Giacomelli et al. (2018) was 132 adjusted to improve the accuracy of the HEM method. Accuracy was improved 133 and equal to a level below 3%, proving the high potential of the mixture ap-134 proach. Nevertheless, in that investigation, only two sets of supercritical OCs 135 at the motive port were taken into account. Moreover, analysis of the coeffi-136 cients used in the vapour quality source terms led to inconsistent conclusions. 137 That is, during the sensitivity analysis of the coefficients, its influence was de-138 scribed as negligible. However, in further analysis, the values of the coefficients 139 were multiplied by 6 to match the experimental mass flow rate. Unfortunately, 140 this matter was not studied further. Hence, a more detailed investigation of the 141 applicability of the mixture model in the whole operational envelope of CO₂ 142 ejectors is required. 143

In this study, the non-equilibrium approach for the R744 ejector was proposed and validated in the subcritical region of the motive pressures, resulting in high accuracy of the predicted motive mass flow rates. The HEM approach was developed, described and extensively validated in previous works (Smolka et al., 2013; Palacz et al., 2015) and was extended by the transport equation

of the vapour mass fraction. On a basis of the source term in the aforemen-149 tioned equation, a boiling phenomenon in the phase-change process was mod-150 elled. Hence, homogeneous non-equilibrium model with boiling phenomenon 151 (HNB) is presented in this study. To validate the model, comprehensive map-152 ping of the coefficients used in the source terms was provided. Then, to im-153 prove practical use of the formulated model, the approximation functions were 154 developed for the R744 expansion process on the basis of the model coefficient 155 maps. Finally, the accuracy of m_{MN} prediction of the developed model was be-156 low 10% for the vast majority of examined cases. The results and discussion 157 included description of the field and mass flow rate differences between the 158 HNB and the HEM, noting the region where both models should be used with 159 regard to high accuracy. 160

161 2. Investigated envelope of the motive nozzle operation

According to the aforementioned literature, one of the main goals in ejec-162 tor modelling is to predict the motive and suction nozzle streams to meet the 163 application and properly fit this component into the system cycle. From the 164 fluid mechanics and thermodynamics points of view, the quality of the motive 165 nozzle and suction nozzle mass flow rate prediction is strongly related to the 166 two-phase flow and mixing models applied for the ejector modelling. In partic-167 ular, the fidelity of the m_{MN} prediction depends mostly on the two-phase flow 168 model applied, while the suction nozzle mass flow rate and entrainment rate 169 prediction are mostly related to turbulence model fidelity. In this study, the au-170 thors decided to focus on the motive mass flow rate, while future studies will 171 consider the suction stream analysis. Hence, the investigation is based on the 172 highly accurate modelling of the expansion process during two-phase flow in 173 the convergent-divergent motive nozzle of the R744 ejector. In this matter, one 174 of the key parameters is a proper prediction of the vapour quality distribution 175 along the ejector axis. A procedure for the quality evaluation of the model pre-176 dicting capabilities for the specific operating range is described in this section. 177

178 2.1. Performance factors of the ejector

The ejector operation can be described using the ratio between the mass
flow rate at the suction and motive port. This factor is called the mass entrainment ratio (MER):

$$\chi = \frac{m_{SN}}{m_{MN}} \tag{1}$$

where χ is the mass entrainment ratio and *m* is the mass flow rate of the motive nozzle (MN) and the suction nozzle (SN). The most common definition of ejector efficiency was proposed by Elbel and Hrnjak (2008). That formulation is a ratio of the amount of the recovered ejector expansion work rate (subscript rec) to the maximum possible expansion work rate recovery potential (subscript rec, max):

$$\eta_{ej} = \frac{W_{rec}}{W_{rec,max}} = \chi \cdot \frac{h(p_{OUT}, s_{SN}) - h(p_{SN}, s_{SN})}{h(p_{MN}, s_{MN}) - h(p_{OUT}, s_{MN})}$$
(2)

where η_{ej} is the ejector efficiency, *W* is the expansion work rate, *s* is the specific entropy and the subscript OUT denotes the ejector outlet.

190 2.2. Accuracy definition

With regard to the numerical approach utilised in this study (detailed description given in Section 4), one of the main model deliverable data set is that of the motive stream and the suction stream. Hence, a quantification of the model accuracy is mostly based on the relative error between the experimental data and the model predictions:

$$\delta m = \frac{m_{CFD} - m_{EXP}}{m_{EXP}} \cdot 100\% \tag{3}$$

where δm is the relative error of the selected flow parameter obtained by the CFD model (subscript CFD) compared to the experimental (subscript EXP) data.

¹⁹³ 2.3. Model accuracy regions in the R744 ejector envelope

Considering the literature review and the current state-of-the-art R744 ejec-194 tor numerical models, the applied model accuracy is strongly related to the 195 motive nozzle absolute pressure. Decreasing motive pressure and temperature 196 have a crucial impact on the accuracy deterioration when the mass flow rate of 197 the motive port is taken into consideration. An underestimation of the m_{MN} 198 is observed for both the HEM and HRM approaches (Palacz et al., 2015; Haida 199 et al., 2018c). Hence, with regard to motive pressure, the highest accuracy of 200 the HEM approach is obtained above the critical pressure of carbon dioxide, 201 while HRM provides high-quality predictions for the subcritical parameters at 202 the motive nozzle inlet. To the authors' best knowledge, the most extensive val-203 idation of the HEM approach was delivered in the works of Palacz et al. (2015), 204 including the region from 47 bar to 95 bar and from 6 °C to 36 °C at the mo-205 tive nozzle inlet. The aforementioned region corresponds to the area marked 206

by green and red frames in Fig. 1. According to those studies, the average HEM 207 accuracy in the high-pressure region (green frame) in Fig. 1 is on the level of 208 6.4%. Simultaneously, the HEM approach becomes substantially deteriorated, 209 with an average accuracy of 24.1% for the motive pressures below the critical 210 point marked by the red frame. Moreover, the maximum reported inaccuracy 211 was 52.0%. In this region of lower motive pressure, the HRM approach im-212 proved prediction accuracy to an average level of 20.2% and a maximum of 213 29.0% (Palacz et al., 2017a; Haida et al., 2018a). Nevertheless, as reported in 214 the work of Haida et al. (2018a), the largest underestimation of the m_{MN} was 215 located below 59 bar of the motive pressure, while in the operating range be-216 tween 59 bar and 70 bar, the average accuracy was on the level of 6.5%. Nev-217 ertheless, due to the relatively high maximum inaccuracies, the whole region 218 below 70 bar was taken into account in a calibration procedure presented in 219 Section 5.2 and finally considered for applicability of the approach developed 220 in this study. 221



Figure 1: Absolute pressure-specific enthalpy diagram of carbon dioxide with marked regions of the higher (green) and lower (red frame) motive pressure and the average accuracy of the HEM (in green frame) and HRM (in red frame) approaches.

222 3. Tested ejectors

223 3.1. Geometry

The ejector domains utilised in this study were investigated extensively in 224 previous experimental works on the multi-ejector module (Banasiak et al., 2015; 225 Haida et al., 2016) and numerical studies focused on validation of the HEM and 226 HRM simulations (Smolka et al., 2013; Palacz et al., 2015, 2017a; Haida et al., 227 2018a). The ejector motive nozzle is defined according to the geometry pre-228 sented in Fig. 2. The crucial dimensions of the two motive nozzles utilised in 229 this study were listed in Table 1. The remaining dimensions were established 230 on the basis of aforementioned studies where specific relations between the 231 utilised dimensions are investigated using more detailed approach. Namely, 232

the ejectors were designed for various capacities of the expanding fluid in binary manner. Therefore, as shown in Table 1, the motive nozzle throat crosssection area for motive nozzle B is two times larger than that for motive nozzle A. Moreover, each pair contains the ejector for the low and the high pressure lift applying the same approach for the capacity that is two times higher. Hence, four ejector configurations were investigated to establish the reliable calibration procedure of the model developed in this study.

The numerical domain was obtained on the basis of the commercial soft-240 ware Ansys ICEM CFD. With regard to the axis symmetry of the ejector geom-241 etry, the computational domain was generated for 2-D computations. A fully 242 hexahedral numerical mesh was generated according to the high requirements 243 of the transonic flow simulation. The domain was extended before the mo-244 tive nozzle inlet and after the diffuser outlet to ensure numerical stability of the 245 solution process. The number and distribution of the cells were finally deter-246 mined on the basis of the analysis in Section 5.1, where the mesh sensitivity 247 study was discussed. 248



Figure 2: General scheme for a single-ejector geometry: MN motive nozzle section, SN suction nozzle section, MIX mixing section, and DIFF diffuser section.

Deremotor name (symbol)	Unit	Value		
	OIIIt	Motive nozzle A	Motive nozzle B	
Motive nozzle inlet diameter (D_{MN1})	mm	3.80	3.80	
Motive nozzle throat diameter (D_{MN2})	mm	1.41	2.00	
Motive nozzle outlet diameter (D_{MN3})	mm	1.58	2.24	
Motive nozzle converging angle (γ_{MN1})	0	30.00	30.00	
Motive nozzle diverging angle (γ_{MN2})	0	2.00	2.00	

 Table 1: Geometrical parameters of the tested ejector motive nozzles

249 3.2. Operating regimes

The considered ejectors were tested in a laboratory test rig at the SINTEF 250 Energy Research (Trondheim, Norway), which resulted in experimental data 251 that included the mass flow rates at the ejector ports. The whole set of OCs used 252 in this study was reported by Haida et al. (2016). In that work, the experimental 253 procedure and accuracy of the measurements were described. In particular, the 254 measurement accuracy was in range from 0.05 K to 0.3 K for the temperature, 255 $\pm 0.3\%$ of reading for the pressure and $\pm 0.2\%$ of reading for the mass flow rate. 256 The presented ejectors were analysed for the motive nozzle operating regimes 257 marked by the red frame in Fig. 1. The complete set of OC utilised in the model 258 calibration and validation procedures is presented in Table 3 (Appendix A) for 250 motive nozzle A and in Table 5 (Appendix B) for motive nozzle B. Hence, the 260 motive inlet pressure conditions were in the range from 45 bar to 70 bar, and the 261 temperature was between 7 °C and 28 °C. These conditions correspond to the 262 refrigeration unit operation in medium- and high-temperature climates such 263 as the Mediterranean. A subcooling level varied from 0 K up to approximately 264 15 K. Moreover, in the group of the low pressure lift, the motive nozzle B was 265 simulated with three sets of the motive nozzle conditions very close to the satu-266 ration line. The suction port conditions could be assigned for chilling purposes 267 at -1 °C and air conditioning at 10 °C. Consequently, the aforementioned set 268 could be referred, e.g., to supermarket Heating Ventilation and Air Condition-269 ing (HVAC) applications. 270

To better illustrate the distribution of the operating points, the data con-271 tained in Table 3 (Appendix A) and Table 5 (Appendix B) are presented in graphs 272 in Figs. 3 and 4. The motive inlet conditions are marked in Fig. 3a and 3b for 273 motive nozzle geometries A and B, respectively. Moreover, points were grouped 274 into groups of a low (below 4 bar) and high (more than 4 bar) pressure lift de-275 fined as a pressure difference between the outlet and the suction port. Simi-276 larly, the suction and outlet pressure conditions are illustrated in Fig. 4a and 277 4b where pressure lift was correlated with the suction nozzle port pressure for 278 given OC. The types of mixing chambers are marked by red dots and green tri-279 angles for the high- and low-pressure lift conditions, respectively. 280



Figure 3: Absolute pressure-specific enthalpy diagram of carbon dioxide with marked inlet conditions for (a) motive nozzle A and (b) motive nozzle B.



Figure 4: OC of the suction nozzle port and the outlet presented on the basis of the pressure lift as a function of the suction nozzle pressure for (a) motive nozzle A and (b) motive nozzle B.

281 4. Computational procedure

The HNB considered in this study is presented in this Section. This approach was developed on the basis of the mathematical model for two-phase transcritical flow inside the ejector ducts proposed by Smolka et al. (2013). Hence, the HEM approach was extended by an additional transport equation of the vapour mass fraction with properly adjusted source terms for a phase change
regulation based on the boiling phenomenon. Moreover, formulation of the
R744 properties was reconsidered with regard to the full set of governing equations.

290 4.1. Governing equations of the mathematical model

The two-phase flow inside the ejector was formulated on the basis of the governing equations and assumption of the steady-state simulation (Chung, 2010; Anderson, 1995). The conservation equation of the mass is defined as follows:

$$\nabla \cdot \left(\bar{\rho} \tilde{\mathbf{u}} \right) = 0 \tag{4}$$

where the Reynolds and Favre-averaged quantities are indicated by (⁻) and (²⁹⁶ ⁻), respectively. Moreover, ρ is the fluid density, and **u** is the fluid velocity vector. ²⁹⁷ The momentum balance is defined by the following equation:

$$\nabla \cdot \left(\bar{\rho} \tilde{\mathbf{u}} \tilde{\mathbf{u}} \right) = -\nabla \bar{p} + \nabla \cdot \tilde{\tau} \tag{5}$$

where *p* is the pressure of fluid and τ is the stress tensor.

According to Smolka et al. (2013), the temperature-based form of the energy equation can be replaced by the enthalpy-based form. Hence, the energy balance of the R744 two-phase flow can be defined as follows:

$$\nabla \cdot \left(\bar{\rho} \,\tilde{\mathbf{u}} \tilde{E} \right) = \nabla \cdot \left[\left(\frac{\lambda}{\frac{\partial h}{\partial T}} \right)_p \nabla \tilde{h} - \left(\frac{\lambda}{\frac{\partial h}{\partial T}} \right)_p \left(\frac{\partial h}{\partial p} \right)_T \nabla \bar{p} + \tilde{\tau} \cdot \tilde{\mathbf{u}} \right] \tag{6}$$

where *T* is the mixture temperature, λ is the fluid thermal conductivity and *E* is the total specific enthalpy defined as a sum of the specific mixture enthalpy and the kinetic energy:

$$\tilde{E} = \tilde{h} + \frac{\tilde{u}^2}{2} \tag{7}$$

where *h* is the mixture specific enthalpy. Turbulence modelling was provided on the basis of the $k - \epsilon$ realizable turbulence model (Shih et al., 1995), as proposed by the base model developed by Smolka et al. (2013). Hence, two additional turbulence equations in the following forms were utilised:

$$\nabla \cdot \left(\bar{\rho}\tilde{\mathbf{u}}k\right) = \nabla \cdot \left[\left(\mu + \frac{\mu_T}{\sigma_k}\nabla k\right)\right] + G_k + G_b - \bar{\rho}\epsilon - Y_M \tag{8}$$

$$\nabla \cdot \left(\bar{\rho}\tilde{\mathbf{u}}\epsilon\right) = \nabla \cdot \left[\left(\mu + \frac{\mu_T}{\sigma_{\epsilon}}\nabla\epsilon\right)\right] + C_{1\epsilon}\frac{\epsilon}{k}\left(G_k + C_{3\epsilon}G_b\right) - C_{2\epsilon}\bar{\rho}\frac{\epsilon^2}{k} \tag{9}$$

where *k* is the turbulent kinetic energy, ϵ is the turbulent dissipation rate, μ and μ_T are the molecular and turbulent dynamic viscosity, σ_k and σ_ϵ are the turbulent Prandtl numbers for *k* and ϵ respectively, G_k and G_b denote the generation of the turbulence kinetic energy due to mean velocity gradients and buoyancy, respectively, and Y_M represents the contribution of the fluctuating dilatation in compressible turbulence to the overall dissipation rate. The constant *C* depends on the $k - \epsilon$ model variant.

The vapour quality field in the numerical simulation is tracked by the scalar transport equation including convective and source term. The additional conservation equation of the vapour mass fraction is given as (Singhal et al., 2002):

$$\nabla \cdot \left(\tilde{\rho} \, \tilde{X} \right) = R \tag{10}$$

where *R* is the vapour generation rate in and *X* is the vapour quality, which indicates the vapour mass in the mixture total. This approach is utilised due to requirements of the finite volume method which is used by the flow-dedicated solver. The equation is introduced to the Ansys Fluent solver using functionality of the User-Defined Scalar (Ansys, 2019). The prediction of the mass transfer is located in the source term *R* on the right-hand of the equation.

4.2. Source term in vapour mass fraction equation

In the state-of-the-art ejector cycles mentioned in Section 1, the satura-326 tion line is crossed during the expansion process in the motive nozzle. Hence, 327 the phenomenon of liquid evaporation must be taken into consideration. The 328 aforementioned literature review contains only a few studies in which the tran-320 sition into the two-phase regime is treated as a non-equilibrium process (Yaz-330 dani et al., 2012; Giacomelli et al., 2018). In this study, the evaporation and con-331 densation rate are modelled on the basis of the kinetic theory of phase change 332 (Carey, 2007). According to the kinetic theory (Carey, 2007), the boiling phase 333 change process can be described as the flux of given molecules between the 334 inter-facial surface: 335

$$j_{nw\pm} = \Gamma(\pm a) \left[\frac{M}{2\pi G_c T} \right]^{1/2} \cdot \frac{p}{f}$$
(11)

where $j_{nw\pm}$ is the flux of the molecules, Γ is the formulation correction factor and corresponds to the bulk motion effect, *M* is the molecular mass of the working fluid, G_c is the universal gas constant and f is the mass flux of molecules described by molecular mass M. This equation can be converted to the form that represents mass flux. Finally, on the basis of Carey (2007), the following relation for vapour mass generation rate was implemented to the vapour mass fraction equation:

$$R = \pm \left[\frac{\widehat{\sigma}}{2 - \widehat{\sigma}}\right] \left(\frac{M}{2\pi G_c T_{sat}}\right)^{1/2} \left[p - p_{sat}\right]$$
(12)

where T_{sat} is the local saturation temperature and p_{sat} is the saturation 343 pressure obtained for isentropic expansion from the motive nozzle inlet condi-344 tions. That approach was utilised in the study presented by Haida et al. (2018c). 345 The coefficient $\hat{\sigma}$ is the accommodation coefficient that represents the number 346 of molecules passing during the phase change process. The aforementioned $\hat{\sigma}$ 347 needs to be adjusted according to the experimental data. Moreover, the value 348 of that coefficient varies with the motive nozzle OC and the selected working 340 fluid. It is worth mentioning that the mapping of $\hat{\sigma}$ for various ejector designs 350 and working fluids may be beneficial from an ejector modelling point of view. 351 This procedure was performed in this study (Section 5.2) for carbon dioxide and 352 OC, where a non-equilibrium phase change is expected. 353

4.3. Computations of one-phase and mixture properties

The properties of the real fluid are obtained from the REFPROP ver. 9 libraries on the basis of the approach presented by Lemmon et al. (2010). In the one-phase regions, local state variables are a function of pressure and enthalpy (Smolka et al., 2013):

$$\{\rho, \mu, \lambda, c_p\} = f(p, h) \tag{13}$$

where μ is the dynamic viscosity and c_p is the specific heat. In the twophase region, where thermal and mechanical equilibrium exists between the phases, saturation variables are a function of pressure and enthalpy (Stadtke, 2006):

$$\{\rho_g, \rho_l, \mu_g, \mu_l, \lambda_g, \lambda_l, c_{p,g}, c_{p,l}\} = f(p)$$
(14)

where subscripts *g* and *l* denote saturated gas and saturated liquid conditions, respectively. The mixture quantities are obtained on the basis of an additional third independent parameter, i.e., the vapour mass fraction (Stadtke, 2006):

$$\{\rho, \mu, \lambda, c_p\} = f(p, X) \tag{15}$$

The final formulations for mixture state properties in the governing equations are defined as follows Stadtke (2006):

$$\rho = \frac{1}{X/\rho_g + (1-X)/\rho_l}$$
(16)

$$\mu = \frac{1}{X/\mu_g + (1-X)/\mu_l} \tag{17}$$

$$\lambda = \frac{1}{X/\lambda_g + (1 - X)/\lambda_l} \tag{18}$$

$$c_p = \frac{1}{X/c_{p,g} + (1-X)/c_{p,l}}$$
(19)

The described formulations were used for the R744 flow calculation in singleand two-phase flow conditions for subcritical, transcritical and near-critical point conditions (Smolka et al., 2013; Palacz et al., 2015).

362 4.4. Boundary conditions for numerical simulation

The pressure-based boundary conditions were used for the motive nozzle 363 and suction nozzle inlets and the outlet of the two-phase ejector. With regard to 364 the enthalpy-based energy equation, the specific enthalpy needed to be speci-365 fied at each port as well. The OC presented in Table 3 (Appendix A) and in Table 366 5 (Appendix B) were used to generate pressure-enthalpy sets for the boundary 367 conditions at each port. Next, the pressure-enthalpy conditions were used to 368 define the value for the quality transport equation at the motive and suction 369 nozzle inlet. Hence, the value at the motive port was 0 due to the subcooled 370 liquid region and the value at the suction port was 1 due to the superheated 371 vapour region. According to the previous studies, the turbulence intensity was 372 assumed to be 10% for both motive and suction inlet. Finally, the hydraulic 373 diameter was calculated separately for each inlet according to the geometrical 374 dimension of each nozzle. The walls of the ejector were simulated as an adi-375 abatic surface. The roughness of the wall surface was set to $2 \,\mu m$ as declared 376 by the ejector manufacturer. According to the turbulence model, the standard 377 wall treatment was used to model the boundary layer. 378

379 4.5. Implementation into ejectorPL platform

The model was implemented in the *ejectorPL* platform developed during 380 the HEM accuracy mapping presented in Palacz et al. (2015) and utilised for the 381 ejector shape optimisation study presented in Palacz et al. (2017b). The compu-382 tational platform was updated by the HRM model (Palacz et al., 2017a), the heat 383 transfer module of thermal analysis within the ejector wall (Haida et al., 2018a) 384 and the snapshot generator for reduced order models (Haida et al., 2018b). The 385 platform provides repeatable simulations of the ejectors for various working 386 fluids through the utilisation of commercial software Ansys ICEM CFD 18.2 and 387 Ansys Fluent 18.2. The structure of the platform was slightly modified accord-388 ing to the model developed in this study. The current structure of this tool is 380 presented in Fig. 5, where the implemented modification is marked in green. 390 Hence, the platform provides a full path from geometry preparation through 391 numerical discretisation, solving process and post-processing of the computa-392 tional results. The complete path from the geometry preparation to the final 393 results costs approximately 45 minutes when taking into account the mesh se-394 lected from the mesh independence study (Section 5.1). Differences in com-395 putational time between solutions obtained for various boundary conditions 396 are negligible. However, the coarser mesh generated directly from the ejectorPL 397 platform takes approximately 20 minutes less of computational time than the 398 case with the finer mesh. Moreover, due to the improved solver algorithms, the 399 time of coarser mesh simulation with the HNB approach is comparable to the 400 time of simulations with the HEM approach. The vast majority of the comput-401 ing cost is the solving process, which is realised on the 10 computing cores con-402 tained in a cluster located at the Institute of Thermal Technology of the Silesian 403 University of Technology, Gliwice, Poland. At the end of the solving process, 404 the levels of the residuals were below a value of 10^{-5} for all the governing equa-405 tions. Additionally, a mass imbalance was monitored until its level was reduced 406 to below 0.01% of the suction nozzle mass flow rate. 407



Figure 5: Flowchart of the *ejectorPL* platform with implemented path (green) for the HNB computations, modified and adapted from Palacz et al. (2015) Haida et al. (2018a)

408 **5. Model calibration**

409 5.1. Mesh independence study

As mentioned in Section 4.5, for both the HEM and HNB, the computational 410 procedure was carried out by the developed platform, including the automatic 411 generation of the fully structural numerical mesh for which the independence 412 study was provided in the previous studies. These studies considered mesh 413 independence study in transcritical states of the motive nozzle inlet. The ob-414 tained structural mesh was characterised by minimal orthogonal quality fac-415 tor (defined according to the utilised software documentation (Ansys, 2019)) at 416 the level of 0.85 and maximum aspect ratio of 2.5 in the flow direction. The 417 distribution and number of elements were on a satisfactory level regarding er-418 gonomic of the simulations characterised by the computational time. Never-419 theless, to ensure the reliability of the new model analysis, additional mesh re-420 finement was examined. Hence, the baseline numerical mesh generated by the 421 *ejectorPL* code was refined and simulated to compare the difference between 422

the aforementioned standard distribution. The results of the mesh indepen-423 dence study are listed in Table 2. The analysis contained two sets of boundary 424 conditions for the smaller motive nozzle geometries, #4 and #77 (see Table 3 in 425 Appendix A). These points were chosen as representatives of high and low mo-426 tive nozzle pressures, respectively. Both the HEM and HNB approaches were 427 analysed. $\hat{\sigma}$ for the high quality of the motive mass flow rate prediction (δm 428 below 0.5%) has already been chosen on the basis of further analysis given in 420 Section 5.2. 430

The baseline mesh of the ejectorPL was built on the basis of over 45,000 ele-431 ments. The final refined mesh contained over 80,000 elements. In each case, 432 the relative difference δm in the mass flow rate value was lower than 0.5%. 433 Moreover, a maximum difference between local absolute pressure and specific 434 enthalpy values along the motive nozzle profile was below 1%. The described 435 differences were evaluated as low enough, taking the previous validation of the 436 developed model into account (Palacz et al., 2015). Nevertheless, with regard to 437 the acceptable computational time of the refined mesh at the level of 45 min-438 utes and the high quality of the fields, the refined mesh was chosen for further 439 investigation. 440

		ejectorPL			
	C			base	refined
		#1	m, kg·s ⁻¹	0.0560	0.0558
HEM	HEM	<i>π</i> 4	δm ,%	-	-0.467
	#77	m, kg·s ⁻¹	0.0512	0.0510	
		$\delta m, \%$	-	-0.438	
		#1	m, kg·s ⁻¹	0.0570	0.0567
	UNR	<i>π</i> 4	δm ,%	-	-0.454
	#77	#77	m, kg·s ⁻¹	0.0777	0.0774
		π()	δm ,%	-	-0.489

Table 2: Mass flow rates at the motive nozzle inlet for the analysed mesh variants

441 5.2. Calibration of the model on the basis of the $\hat{\sigma}$ mapping

The model calibration was conducted with regard to the experimentally determined mass flow rates for the given OC. The values of the coefficients determine the intensity of the phase change. An increment in the coefficients results in more intensive evaporation and lower pressure in the motive nozzle throat. Consequently, the model prediction of the motive mass flow rate is adjusted.

In the calibration procedure, all 150 OCs for the two motive nozzles were taken 447 into account. The calibration procedure was performed with regard to the ac-448 curacy of the mass flow rate prediction δm below 0.5%. In that procedure, the 440 ejectorPL platform was utilised for serial computations with an in-house de-450 veloped script to search for the $\hat{\sigma}$. The obtained $\hat{\sigma}$ s are presented in Table 4 451 (Appendix A2) and Table 6 (Appendix B2) and were tuned based on the experi-452 mental data presented in Table 3 (Appendix A) and in Table 5 (Appendix B). The 453 graphical representation of Table 4 and Table 6 is available in Fig. 6, where the 454 values of the coefficients are marked on the pressure-enthalpy diagram. In this 455 figure, the chosen values of the coefficients are located in the corresponding 456 points as presented in Fig. 6. 457

The values of the coefficients are between 0.28 and 1.54. Moreover, there is 458 a correlation between the absolute pressure, the specific enthalpy and the co-459 efficient values. The coefficient values decrease with decreasing pressure and 460 enthalpy. From a physical point of view, the phase change is less instantaneous 461 in the lower-pressure region. Simultaneously, higher-pressure regions result in 462 more dynamic or even instantaneous evaporation processes. This behaviour 463 is expected with regard to HEM assumptions and its high accuracy only in the 464 region of the high motive pressures (see Fig. 1). 465



Figure 6: $\hat{\sigma}$ on the pressure-enthalpy diagram $\frac{22}{6}$ carbon dioxide for (a) motive nozzle A and (b) motive nozzle B.

466 5.3. Approximation function of the $\hat{\sigma}$

According to the model applicability, the necessity of manual coefficient ad-467 justment should be evaluated as a form of model limitation. Hence, the cal-468 ibration results were utilised for the development of the function $\hat{\sigma}_{map}$. The 469 paraboloid function was prepared for computations of the $\hat{\sigma}$ values. Statisti-470 cal tools available in the commercial software SigmaPlot v. 14.0 (Systat Soft-471 ware Inc.) were utilised for function determination. The resulting formulation 472 is presented in Eq. (20). The function utilises the absolute pressure and spe-473 cific enthalpy at the motive nozzle inlet. The function reflects the general trend 474 with regard to a negligible number of non-matching points. Global evaluation 475 of goodness of fit was prepared in the form of coefficient of determination, for 476 which a value of 0.9127 was obtained. 477

 $\hat{\sigma}_{map} = 3.16978 - 0.119943 \cdot P_{MN} - 0.0650588 \cdot h_{MN} - 0.000790122 \cdot P_{MN}^2 + 0.000153503 \cdot h_{MN}^2$ (20)

As mentioned, some of the obtained $\hat{\sigma}$ values did not fit into the general trend. However, the number of calibration points was large enough to minimise the influence of these points. A graphical illustration of the obtained $\hat{\sigma}$ distribution (red dots) is presented in Fig. 7. Moreover, the developed function $\hat{\sigma}_{map}$ is presented in the form of a surface (blue mesh). In Fig. 7, there are two views where local discrepancies are visible from the point of view of the specific enthalpy and absolute pressure.



Figure 7: The adjusted $\hat{\sigma}$ (red dots) on a pressure-specific enthalpy graph where the approximation function is presented as a blue surface for (a) the specific enthalpy view and (b) absolute pressure view.

485 5.4. HNB with the approximation function

Another computational campaign with the same set of boundary condi-486 tions was conducted using the approximation function $\hat{\sigma}_{map}$ for the reproduc-487 tion of the $\hat{\sigma}$ values. The results of this analysis are illustrated in Fig. 8a for 488 motive nozzle A and in Fig. 9a for motive nozzle B. Moreover, the resulting 489 dynamics of the evaporation process and the accuracy of the m_{MN} prediction 490 were correlated with the corresponding $\hat{\sigma}$. Additionally, the distribution of the 491 model accuracy is presented in Fig. 8b and in Fig. 9b for the smaller (A) and 492 larger (B) motive nozzles, respectively. 493

First, the developed function $\hat{\sigma}_{map}$ reproduces $\hat{\sigma}$ however the $\hat{\sigma}$ values from 494 the function are not identical with the values from mapping procedure. This 495 discrepancy is presented by the grey bars in Fig. 8a and Fig. 9a. The differences 496 between the 'in-point' calibrated coefficient and the approximated coefficient 497 are significant and in some cases exceed $\pm 30\%$. Nevertheless, in most cases, 498 the function computes the coefficient value with a difference lower than $\pm 15\%$. 499 The expected correlation between the accommodations coefficient values 500 and the obtained mass flow rate is clearly visible. That is, when the function 501 $\hat{\sigma}_{map}$ computes an excessively high coefficient value, the resulting mass flow 502 rate is too low, and vice versa, an excessively high mass flow rate is obtained 503 when the coefficient value is too low. Nevertheless, the difference between the 504

calibrated and computed $\hat{\sigma}$ does not result in the same difference in the mass 505 flow rate accuracy. Moreover, the relation is not linear and is not proportional 506 between the investigated cases. That is, the same difference between the cal-507 ibrated and computed $\hat{\sigma}$ can result in variation in the accuracies of the mass 508 flow rate prediction. For example, simulation of boundary conditions #53-54 509 of smaller motive nozzle A resulted in different mass flow rate accuracies de-510 spite the reproduction of the $\hat{\sigma}$ obtained with almost the same accuracy. This 511 behaviour might imply that the evaporation process is not completely con-512 strained by the coefficient value and that the influence of the flow parameters 513 is still visible. 514

As shown in Fig. 8 and Fig. 9 by the red dot bars and red dots, high accu-515 racy within $\pm 7.5\%$ was obtained for motive nozzle A with regard to the motive 516 nozzle type and resulting accuracy levels. The results of motive nozzle B are 517 more dispersed and could be characterised as more non-uniform than those 518 obtained from the smaller motive nozzle A Finally, in the vast majority of the 519 cases reaching 90%, the accuracy of the mass flow rate prediction was below 520 $\pm 12.5\%$. The group of the smaller motive nozzle contains three cases with an 521 inaccuracy on the level of $\pm 13.5\%$. 522

Motive nozzle B resulted in two cases that exceeded $\pm 12.5\%$ with 50.5% (OC 523 #52) and 15.1% (OC #3). The boundary condition related to the highest error is 524 characterised by motive conditions very similar to the saturation line of the liq-525 uid where the measured sub-cooling was lower than 1 K. This situation might 526 disturb the mass flow rate measurement due to the very sensitive characteristic 527 of the Coriolis mass flow-meter for which homogeneous flow without gas bub-528 bles should be ensured. Finally, with regard to the total number of simulated 529 cases, only one case was characterised by the m_{MN} prediction significantly ex-530 ceeding $\pm 15.0\%$. 531



Figure 8: Accuracy of (a) $\hat{\sigma}$ reproduction via the $\hat{\sigma}_{map}$ function (grey bars) and mass flow rate prediction (red bars) and (b) resulting accuracy dispersion of the motive mass flow rate prediction for motive nozzle A.



Figure 9: Accuracy of (a) $\hat{\sigma}$ reproduction via the $\hat{\sigma}_{map}$ function (grey bars) and mass flow rate prediction (red bars) and (b) resulting accuracy dispersion of the motive mass flow rate prediction for motive nozzle B.

The statistical analysis of the model accuracy distribution below $\pm 12.5\%$ is presented in Fig. 10 for motive nozzle A (black bars) and motive nozzle B (grey bars). First, the previously described accuracy of the simulation results in the case of the smaller motive nozzle is higher than that of larger motive nozzle ⁵³⁶ B. Satisfactory results of very low inaccuracy below $\pm 5.0\%$ were obtained for ⁵³⁷ 70% and 40% of the motive nozzle A and B simulations, respectively. How-⁵³⁸ ever, almost 80% of the latter is computed with inaccuracy below $\pm 10.0\%$. Fi-⁵³⁹ nally, more than 90% of the simulated OC was predicted with inaccuracy be-⁵⁴⁰ low $\pm 12.5\%$. However, the percentage of highly accurate predictions would be ⁵⁴¹ higher if the aforementioned maximum errors would not be included in the ⁵⁴² analysis presented in Fig. 10.



Figure 10: Distribution of the model accuracy in a given range.

The accuracy of the suction stream prediction is presented in Fig. 11a and 543 Fig. 11b for motive nozzles A and B, respectively. The motive nozzle mass flow 544 rate differences for the analysed $k-\epsilon$ and $k-\omega$ turbulence models were negligi-545 ble, namely below 1.0%. The quality of the suction nozzle mass flow rate predic-546 tion is definitely unsatisfactory. In the vast majority of the simulated cases, the 547 inaccuracy of the suction stream prediction was above $\pm 20.0\%$. Similar to the 548 motive nozzle computations, the accuracy is higher for the larger motive noz-549 zle. However, some proportionality could be indicated in both cases and is es-550 pecially visible for the smaller motive nozzle. That is, for high motive pressures 551 up to OC #40, the suction stream is overestimated at the level between approx. 552 20% and 40%. In cases where the pressure is higher than for #40, the motive 553 pressure is below approx. 65 bar, and the suction stream is under-predicted. 554 On the other hand, over 50 cases simulated with the $k - \omega$ turbulence model 555

are characterised by the accuracy higher than 20.0%.

With regard to suction stream and mixing processes, the mathematical model 557 should include physics such as inter-facial slip and cavitation in the pre-mixing 558 chamber. The influence of the turbulence model onto cavitation intensity should 559 be considered as relatively high. Hence, the aforementioned model should be 560 evaluated simultaneously in several aspects due to their mutual interaction. 561 Moreover, the phase change process inside the shock wave pattern in the pre-562 mixing area should be considered as a more instantaneous than constant evap-563 oration in the motive nozzle. Hence, in this study, the authors focused only 564 on the expansion process in the motive nozzle and the resulting accuracy of 565 the motive stream prediction. In future studies, the aforementioned additional 566 modelling of suction stream behaviour will be considered. 567



Figure 11: Accuracy of the suction stream prediction for (a) motive nozzle A and (b) motive nozzle B.

6. Results and discussion on the comparison of the HNB and HEM approaches

The developed HNB should be compared to the HEM approach, which was 569 described as the most inaccurate model in the region of low motive pressure, 570 i.e., below 70 bar. For this reason, two representative cases were chosen for 571 further analysis. The first case is OC #4, characterised by high accuracy of the 572 motive mass flow rate prediction equal to -5.0%. The second case considered 573 in this analysis was OC #77, which was much less accurate, i.e. the m_{MN} was 574 underestimated by 38.0%. The flow characteristic was discussed on the basis of 575 the vapour quality profile and fields of absolute pressure and velocity magni-576 tude. 577

578 6.1. Vapour quality profiles

The vapour quality distribution in the area of the ejector motive nozzle is presented in Fig. 12a for OC #4 and Fig. 12b for #77. Moreover, the throat and outlet of the motive nozzle are indicated by vertical dashed and dotted lines, respectively.

As expected, in both cases, the evaporation process of the HEM approach is realised in a dynamic manner. The vast majority of the vapour is generated in the throat region of the motive nozzle where vapour quality is on the level of 0.15-0.25. With regard to the HNB, the vapour generation rate is substantially lower. The first gas bubbles are generated in a slow process, providing less than 0.02 of the vapour mass fraction of the throat. Next, the vapour quality constantly increased along the divergent part of the motive nozzle.

Nevertheless, in the case of OC #4 (Fig. 12a), both approaches reach similar 590 vapour quality, equal to approximately 0.30 at the motive nozzle outlet. How-591 ever, in the very beginning of the pre-mixing chamber, the HNB predicts sig-592 nificantly higher evaporation than does HEM. According to the motive nozzle 593 outlet, similar vapour quality was obtained in both approaches. Consequently, 594 similarities are visible in the flow fields, such as velocity and pressure. Finally, 595 the mass flow rates at the motive port of the HEM and HNB simulations could 596 be characterised as comparable because they differ by 5.4%. 597

On the other hand, an analysis of the vapour quality distribution performed 598 for OC #77 (Fig. 12b) revealed some additional differences. In addition to global 599 differences in profile characteristics, the vapour quality for the HNB was sig-600 nificantly lower than that obtained by HEM. That is, the HNB vapour quality 601 and the HEM vapour quality at the motive nozzle outlet were equal to 0.1 and 602 0.25, respectively. The latter approach could be compared to the OC #4 results 603 where the aforementioned 0.30 level of vapour quality was obtained at the mo-604 tive nozzle outlet. Hence, the substantial difference in the evaporation process 605 behaviour between OC #4 and #77 is visible only for the HNB. Consequently, 606 simulation of the fluid flow within the HNB approach resulted in the increased 60 accuracy of the m_{MN} prediction ($\delta m = 0.5\%$) when compared to that obtained 608 for the HEM formulation ($\delta m = -38.0\%$). 609



Figure 12: Vapour quality profiles along the ejector axis for the HEM (blue dots) and HNB (red dots) in the area of motive nozzle and pre-mixing chamber for OC (a) #4 and (b) #77.

610 6.2. Velocity and absolute pressure fields

As discussed above, the crucial difference in the vapour quality profiles of 611 the HEM and those of the HNB were obtained in OC #77. Hence, that case 612 is utilised for further field result analysis. The absolute pressure fields of the 613 motive nozzle area obtained from the HEM and HNB are presented in Fig. 13. 614 Moreover, the corresponding absolute pressure profile is presented along the 615 presented field with the throat and motive nozzle outlet marked by vertical dot-616 ted lines. Compared to the HEM formulation, the HNB resulted in a low abso-617 lute pressure just before the motive nozzle throat as a consequence of the high 618 motive mass flow rate and resulting intensified pressure drop in the subcritical 619 region. Hence, the absolute pressure in the motive nozzle throat computed by 620 the HNB was lower than that obtained by HEM by approx. 2 bar. In the diver-621 gent section, the HEM approach predicted a nearly linear pressure drop from 622 approx. 45 bar (green/yellow colour in Fig. 13) to approx. 27 bar (blue/green in 623 Fig. 13). The HNB computations resulted in smooth pressure reduction at the 624 same distance where almost the entire divergent section corresponds to the 625 green colour, indicating a range between 43 bar and 30 bar. However, the latter 626 approach resulted in a higher intensity of the first pressure drop immediately 627 after the motive nozzle outlet, where approx. 21 bar of minimum absolute pres-628 sure was reached. The HEM solution predicted a minimum absolute pressure 629 equal to approx. 25 bar. Finally, a shock wave pattern in the pre-mixing cham-630 ber is more visible in the case of the HNB computations where a more uniform 631 pressure distribution was obtained from the HEM simulation. 632



Figure 13: Absolute pressure (Pa) profile and corresponding field distribution for the HEM and HNB approaches for OC #77 in the area of the motive nozzle and pre-mixing chamber.

The field distribution of the velocity magnitude obtained from the HEM and 633 HNB is presented in Fig. 14 with the corresponding profile and lines indicating 634 the throat and motive nozzle outlet. In the convergent part of the motive noz-635 zle, higher velocity was obtained using the HNB as a consequence of the higher 636 motive mass flow rate and constant pressure-specific enthalpy boundary con-637 dition. Considering the divergent part, the differences were more significant. 638 Moreover, reflection of the absolute pressure distribution can be found. The 639 HEM results are characterised by a substantial and rapid increase in the veloc-640 ity, while those of the HNB showed smooth growth of the velocity magnitude 641 along the divergent section of the motive nozzle. Consequently, the HNB deliv-642 ers approx. 90 $\text{m}\cdot\text{s}^{-1}$ (yellow colour in Fig. 14), and the HEM delivers nearly 120 643 $m \cdot s^{-1}$ (red colour in Fig. 14) at the motive nozzle outlet. The downstream be-644 haviour in the pre-mixing chamber maintains the described differences. More-645 over, the velocity in the wall vicinity is significantly higher for HEM as well. In 646 this case, the difference between the models reached almost $10 \text{ m} \cdot \text{s}^{-1}$. 647



Figure 14: Velocity magnitude $(m \cdot s^{-1})$ profile and corresponding field distribution for the HEM and HNB for OC #77 in the area of the motive nozzle and pre-mixing chamber.

648 7. Conclusions

In this study, an expansion model based on the HEM (Smolka et al., 2013) 649 and mixture approaches (Yazdani et al., 2012) was developed to simulate trans-650 sonic flow through the R744 ejector. The developed HNB approach was im-651 plemented into the *ejectorPL* platform, which allowed for comparison with the 652 previously developed (Smolka et al., 2013) HEM approach. The model struc-653 ture is suitable for various working fluids (preferable natural refrigerants) after 654 the proper calibration process of the $\hat{\sigma}$ responsible for the evaporation rate and 655 the resulting motive mass flow rate. In this study, the calibration of the $\hat{\sigma}$ was 656 performed for a CO₂ two-phase ejector. 65

- The calibration procedure included various ejector geometries and a wide
 range of motive nozzle OCs. The calibration range contained motive noz zle pressures from 50 bar to 70 bar, where the HEM model accuracy was
 unsatisfactory. The criterion of the successful calibration was an accu racy of below 0.5% for the motive mass flow rate prediction.
- The calibrated HNB was validated against experimental data composed of 150 operating points (Tables 3 and 4), which included the mass flow

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rate for validation purposes and pressure and specific enthalpy for the 665 model conditions. 666 The validation results were considered as acceptable regarding discrep-667 ancy between the experimental and numerical mass flow rates for the 668 whole range of the investigated OC. That is, the discrepancy between the 669 measured and computed mass flow rates was below 10.0% for the vast 670 majority of the cases. 671 • 70% of the simulated cases were simulated with a mass flow rate predic-672 tion below 7.5% of the relative error. The major advantage of the pre-673 sented model is the high accuracy of the motive mass flow rate predic-674 tions. The relative error of the m_{MN} prediction was below 5.0% for over 675 half of the investigated cases. 676 • The accuracy of the model differs between small and large motive noz-677 zles. Moreover, the fidelity of the presented model was unsatisfactory for 678 only 4 of 150 cases. 670 • Regarding applicability, the presented methodology introducing the uni-680 versal two-phase ejector designing tool that could be used for other flu-681 ids. An analysis of the vapour quality profiles showed the major differ-682 ence in evaporation for the HEM simulations and smooth and linear vapour 683 generation in the case of the HNB computations. 684 The reason for these differences was found in the absolute pressure and 685 the velocity magnitude fields in the motive nozzle. Consequently, a slower 686 evaporation process resulted in a higher pressure along the motive noz-687 zle in the HNB computations. Simultaneously, the increase in the velocity 688 magnitude was more rapid as a result of the HEM approach. 689

Further work will be more focused on the mixing process inside the mixer of the device and on the analysis of the suction stream prediction on the basis of the motive nozzle modelling presented in this study. The promising area of investigation should be the slip velocity between the phases, turbulence modelling and cavitation phenomenon in the pre-mixing chamber.

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Nomenclature

HFO Hydrofluoroolefin HNB Homogeneous non-equilibrium model with boiling phenomenon HRM Homogeneous relaxation model HVAC Heating Ventilation and Air Conditioning MER Mass entrainment ratio OC Operating condition Subscripts CFD Computational EXP Experimental Saturated gas g Saturated liquid 1 max Maximum Motive nozzle MN OUT Outlet Amount of the recovered ejector expansion work rate rec sat Saturation state SN Suction nozzle Superscripts Reynolds-averaged quantities Favre-averaged quantities Roman Symbols J·kg⁻¹·K⁻¹ Specific heat Cp D Diameter m E Total specific enthalpy J-kg⁻¹ kg·m⁻²·s⁻¹ Mass flux f kg·m⁻¹·s⁻³ Gb Generation of the turbulence kinetic energy due to buoyancy J·mol⁻¹·K⁻¹ Universal gas constant G_{c} Generation of the turbulence kinetic energy due to mean velocity gradients G_k kg·m⁻¹·s⁻³ J·kg⁻¹ Specific enthalpy h mol·m⁻²·s⁻¹ Flux of the molecules Jnw± $m^2 \cdot s^{-2}$ Turbulent kinetic energy k g·mol^{−1} Molecular weight М kg⋅s⁻¹ Mass flow rate т Absolute pressure р Pa kg·m⁻³·s⁻¹ R Vapour generation J⋅kg⁻¹⋅ K⁻¹ Specific entropy s Т Temperature $m \cdot s^{-1}$ Fluid velocity vector u Х Vapour quality kg·m⁻¹·s⁻³ Contribution of the fluctuating dilatation Y_M W Expansion work rate w Greek Symbols

χ Mass entrainment ratio³⁹

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δm	Relative error of the mass flow rate	%
ϵ	Turbulent dissipation rate	$m^2 \cdot s^{-3}$
η_{ej}	Ejector efficiency	
Г	Correction factor to the bulk motion effect	
γ	Angle	0
λ	Thermal conductivity	$W \cdot m^{-1} \cdot K^{-1}$
μ	Dynamic viscosity	$m^2 \cdot s^{-3}$
μ_T	Molecular dynamic viscosity	$m^2 \cdot s^{-3}$
ρ	Fluid density	kg·m ^{−3}
σ_k	Turbulent Prandtl number for k	
σ_{ϵ}	Turbulent Prandtl number for ϵ	2
τ	Stress tensor	N·m ^{−2}
σ	Accommodation coefficient	
σ_{map}	Approximation function	
Joil		

Declaration of interests

 \boxtimes The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

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The authors declare the following financial interests/personal relationships which may be considered as potential competing interests:

