

# 1    Effect of gear soak time on size selection in 2    the snow crab pot fishery

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## 8    Abstract

9    In the commercial pot fishery for snow crab (*Chionocetes opilio*), size selection by the pots is  
10   important for reducing catch sorting and unintended mortality. In addition to mesh size and  
11   shape, selection in the pots relies on every crab contacting the netting meshes, which makes  
12   the process complex because the odour of the bait tends to keep all sizes of crab in the pots.  
13   Thus, soak time may affect the extent of the use of the selective potential of the pots. This  
14   study was designed to assess the influence of soak time on size selectivity, and the  
15   methodology was applied to snow crab data collected in the Barents Sea. The results showed  
16   that a minimum soak time is required to reach the full size-selective potential of the pots.

17   Specifically, a fraction of the small crabs inside a pot will not attempt to escape through the  
18   pot meshes when the pots are soaked for short periods of time (under nine days). Further, with  
19   short soak time, some of the crabs inside a pot will not make selectivity contact with the  
20   netting. Therefore, some crabs will not utilize the escape options through the pot meshes. This  
21   finding confirms the need for using a selection model that explicitly accounts for such a  
22   process when assessing snow crab size selection. Lastly, this study outlines how the concept  
23   of selectivity contact can formally be applied to model the effect of soak time on the size  
24   selectivity of the snow crab pot fishery.

25    **1. Introduction**

26    Snow crab (*Chionoecetes opilio*) is distributed in the polar regions of the Northern  
27    Hemisphere and for decades has formed the basis of an important commercial fishery in  
28    countries such as the USA, Canada and Russia (Alvsvåg et al., 2009; Winger and Walsh,  
29    2007; Mathis et al., 2015). Although seines are successfully used to catch this species in  
30    countries such as South Korea (Yamasaki et al., 1990; Horie et al., 2001), in most fisheries  
31    snow crabs are harvested using pots. The design, size, and operation of the pots vary among  
32    regions, but the working principle of the gear is basically the same. Snow crabs are attracted  
33    to the pot area by the odour of the bait in the pot, and once they enter the pot they stay there  
34    until one or more mechanisms trigger their willingness to escape. These triggers vary from  
35    total or partial consumption of the bait to behavioural patterns such as competition with other  
36    snow crabs or other species (Chiasson et al., 1993; Vienneau et al., 1993; Broadhurst et al.,  
37    2017). However, a snow crab captured in a pot will not be able to escape unless it is able to  
38    pass through the netting covering the pot. This means that apart from the size distribution of  
39    snow crabs in the fishing area, the size selective properties of the pot's netting will affect the  
40    size distribution of the snow crabs ultimately recovered on board the fishing vessel.

41    Soak time (e.g., the amount of time a pot is fished in the water) is an important factor that can  
42    affect catch performance of pot gear (Boutillier and Sloan, 1987). For a snow crab to enter a  
43    pot, it must have enough time to sense the bait, approach the pot, and finally enter it. If the pot  
44    is hauled before this process is completed, the catch performance of the pot will be  
45    suboptimal. Furthermore, if soak time is too short and the pot is hauled before the snow crab  
46    attempts to escape, the selective properties of the pot's netting will not be fully utilized.

47    Several researchers have used the concept of "selectivity contact" to study size selectivity of  
48    active fishing gears (e.g. Sistiaga et al., 2010; Larsen et al., 2016), but to date this concept has

49 not been applied to pot gear. The concept of selectivity contact is that an animal must first  
50 physically contact the selectivity device (in this case the pot netting), but then be orientated in  
51 a manner to allow for a size-dependent escape to occur. For crabs, they cannot maneuver and  
52 change orientation as fast as fish and might therefore require more time to contact selectivity  
53 devices. Thus, while fish are likely to make selectivity contact with the pot netting several  
54 times in a short-time process (i.e., during haul back), the probability of crab to optimally  
55 orientate and escape through the pot meshes would be much lower. In this study, we tested  
56 whether an analytical approach that considers the probability of crab making selectivity  
57 contact with the pot netting could be used to study snow crab pot selectivity, including the  
58 effect of soak time. Off Canada, Winger and Walsh (2011) reported that increased soak time  
59 reduced the amount of undersized snow crab in pots. This suggests that selectivity contact  
60 with the netting and size selection increases over time.

61 Sorting crabs on deck can be a labour-intensive operation onboard a fishing vessel. If not  
62 performed with care and caution, it can result in illegal processing of undersized crabs or  
63 unnecessary mortality of undersized individuals. Snow crab fishing is often carried out in  
64 harsh weather conditions, and strong cold winds increase the mortality of snow crab as the  
65 risk for their internal organs to freeze increases with decreasing temperature (Grant, 2003).  
66 Thus, size selectivity at the seabed is optimal and would decrease the sorting labour on deck  
67 and decrease unnecessary snow crab mortality.

68 In this study, we evaluated the size selectivity of crab pots, including the effect of soak time,  
69 in the Barents Sea snow crab fishery. This fishery is relatively new, with the species not  
70 commercially exploited in the Barents Sea until the beginning of the present decade. The total  
71 landings in the Barents Sea increased from 2.5 tonnes in 2012 to 10,430 tonnes in 2016, of  
72 which approximately 5200 tonnes were landed by Norwegian vessels (Norwegian Sales

73 Organization (<https://www.rafisklaget.no>), 2016). The fleet consists of vessels between 40  
74 and 70 m long, and each vessel operates between 1000 and 2000 pots every day. Snow crab in  
75 the Barents Sea fishery are exclusively harvested using conical pots (ranging from 120 to 140  
76 mm mesh sizes) deployed in strings connected to the main line (e.g., longline). The minimum  
77 legal size for snow crab in the Barents Sea is 100 mm carapace width (CW), which means that  
78 primarily only male snow crabs can be harvested as females are rarely > 90 mm CW. All  
79 undersized snow crab must be returned to the sea. The management regulations in the  
80 Svalbard Fisheries Protection Zone (ICES area SXV) and Norwegian EEZ are as follows:  
81 minimum legal size of 100 mm CW; maximum of 12,000 pots deployed per vessel; maximum  
82 soak time for pots of three weeks; mandatory use of pot gear only; the fishery is closed and all  
83 pots must be removed from the seabed from 15 June to 15 September; and a maximum of  
84 20% post moult crab caught (Norwegian Fisheries Directorate ([www.fiskeridir.no](http://www.fiskeridir.no)), 2018).

85 The goals of the present study were to address the following research questions:

- 86 • Does soak time affect the selective performance of snow crab pots? If so, what is the  
87 minimum soak time required to exploit their full selective potential?
- 88 • Is the parameter "selectivity contact" a good indicator of the effect of soak time on the  
89 selective properties of snow crab pots?
- 90 • Are the selective properties of the conical pots used in the Norwegian snow crab  
91 fishery appropriate for the minimum legal CW regulation?

## 92 **2. Materials and methods**

### 93 *2.1. Collection of sea trial data*

94 Sea trials were conducted aboard the fishing vessel Northguider (55.2 m overall length and  
95 3750 HP) in the central Barents Sea (N76°28.9–E36°36.9 and N75°56.1–E37°33.8 (ICES area

96 SXV)) at depths of 280–310 m. The trials took place between 01 March and 09 April of 2018.  
97 The pots used in the trials were conical, with diameters of 70 and 130 cm at the top and the  
98 bottom, respectively and a height of 60 cm. The 53 cm diameter entrance to the pot was  
99 situated on top. The pots were fished in longlines of 200 pots attached to the mainline every  
100 30 m by a quick link system that allowed rapid attachment and release of the pots to/from the  
101 mainline (Fig. 1). During the experiments, we used size selective pots subjected to the  
102 investigation (test pots) and pots with small mesh size compared to in the test pots (control  
103 pots). All pots were identical except for the netting used to cover the frame. Test pots  
104 consisted of 140 mm (nominal) mesh size ( $\varnothing$ 4 mm polyethylene (PE) twine), whereas 52 mm  
105 (nominal) mesh size ( $\varnothing$ 2 mm PE twine) was used for the control pots (Fig. 1). Each third or  
106 fourth pot was a control pot. The large difference in mesh size between the test and control  
107 pots eliminated any overlap in potential size selection of snow crab between the two types of  
108 pots. Thus, this enabled an unbiased estimation of the size selectivity for the test pots based  
109 on comparing the catches in the test and control pots. Given the pots conical shape, the  
110 meshes opening angle on the netting will vary depending on their location on the pot.  
111 Therefore, both mesh size and opening angle are decisive for which sizes of crab can escape  
112 through the meshes. To get an estimation of the mesh size and opening angle on the test pots  
113 used during the sea trials, we digitized and modelled the contour of 12 meshes from a random  
114 pot used during the trials (Fig. 2). The average mesh size obtained was 136.7 mm (range  
115 130.4–139.7 mm) and the average mesh opening angle obtained 79.2° (range 67.2–88.8°)  
116 (Fig. 2).

117 FIG. 1

118 FIG. 2

119 Each pot was baited with 700 g of squid (*Ilex* spp.) in a mesh bag and perforated plastic  
120 container (Fig. 3a). When the pots were hauled onboard, they were emptied separately onto a  
121 sorting board and CW of each crab was measured to the nearest mm using callipers (Fig. 3b).

122 FIG. 3

123 *2.2. Analysis of sea trial data*

124 Analyses of the sea trial data were conducted separately for each group of deployments with  
125 the same soak time. The data were analysed using the method described below, which was  
126 implemented in the software tool SELNET (Herrmann et al., 2012). Based on the  
127 experimental design, the catch data from the test and control pots were collected in pairs on  
128 the same longline and can be regarded as paired. As each longline covered a long track  
129 (approximately 6500 m for a 200 pot line), the longline was segmented into local groups  
130 (sets) for analysis purposes. In this way, it was more realistic to assume that the control and  
131 test pots from a set were fishing a population of snow crab with the same size distribution  
132 than if each set was covering the complete longline. Consequently, a set consisted of between  
133 21 and 42 test pots and 7 and 21 control pots. The catch data from individual test and control  
134 sets with the same soak time were used to estimate the average size selectivity for the test pots  
135 for each specific soak time. The data for each soak time were pooled over sets, and the paired  
136 gear estimation method was applied (Wileman et al., 1996). Thus, the average size selectivity  
137 of the test pots was estimated based on the catch data summed over deployments by  
138 minimising the following equation, which is equivalent to maximising the likelihood for the  
139 observed experimental data:

140 
$$-\sum_l \sum_{i=1}^m \left\{ nT_{li} \times \ln \left( \frac{SP \times r(l, v)}{SP \times r(l, v) + 1 - SP} \right) + nC_{li} \times \ln \left( 1.0 - \frac{SP \times r(l, v)}{SP \times r(l, v) + 1 - SP} \right) \right\} \quad (1)$$

141 where  $nT_{li}$  and  $nC_{li}$  represent the number of snow crabs of each length class  $l$  retained in the  $i$ -  
 142 th set for the test and control pots, respectively.  $m$  represents the total number of sets for the  
 143 specific soak time group.  $SP$  is the split factor quantifying the sharing of the total catch  
 144 between the test and the control pots (Wileman et al., 1996), and  $\nu$  is a vector of parameters in  
 145 the size selection model  $r(l, \nu)$ . The potential for differences in entrance efficiency of snow  
 146 crab between test and control pots is reflected in the value of  $SP$ , and therefore will not bias  
 147 the estimation of the size selectivity  $r(l, \nu)$  for the test pots. Thereby, this eliminated potential  
 148 bias in estimation resulting from differences in netting twine thickness and colour between  
 149 test and control pots.

150 Because the test pots were constructed with a single mesh size and had the entrance on the  
 151 top, which prevented escape through this path, it would traditionally be assumed that the pot  
 152 size selection can be described by the standard *logit* model (Wileman et al. 1996). This model  
 153 has been applied by Xu and Millar (1993) and Winger and Walsh (2011) to model size  
 154 selection in snow crab pot fisheries using selection parameters  $\nu = (W50, SR)$ :

$$155 \quad r(l, \nu) = r_{Logit}(w, \nu) = \frac{\exp\left(\frac{\ln(9)}{SR} \times (w - W50)\right)}{1.0 + \exp\left(\frac{\ln(9)}{SR} \times (w - W50)\right)} \quad (2)$$

156  $W50$  is the CW of a snow crab with 50% probability of being retained given it has entered the  
 157 pot, whereas  $SR$  is the CW difference of a snow crab with 75% and 25% probability of being  
 158 retained, conditioned they entered it. The  $SR$  value can explicitly reflect the intra- and  
 159 between-test pot variation in mesh size and opening angle (Fig. 2) affecting the escape  
 160 probability for individual crab of same size. Model (2) assumes that every crab that enters a  
 161 test pot attempts to escape through the meshes before the pot is retrieved on board the fishing  
 162 vessel. However, a fraction of the crabs entering a test pot may not have had sufficient time to  
 163 attempt such an escape, especially for pots with short soak time. Therefore, instead of

164 modelling the size selection in the test pot based only on the *logit* model (2), we also  
165 considered the *CLogit* model (3), which can account for the possibility that only a fraction  $C$   
166 of the crabs entering the pot makes selectivity contact with the meshes and is subjected to a  
167 size selection process. This is the first time that the *CLogit* size selection model has been used  
168 to estimate size selection in a pot fishery.

169  $r(w, \mathbf{v}) = r_{CLogit}(w, C, W50_c, SR_c) = (1 - C) + C \times Logit(w, W50_c, SR_c) = 1.0 -$

170 
$$\frac{C}{1.0 + exp\left(\frac{ln(9)}{SR_c} \times (w - W50_c)\right)} \quad (3)$$

171 The parameter  $C$  holds a constant value that ranges between 0.0 (no crabs make selectivity  
172 contact with the pot meshes) and 1.0 (all crabs make selectivity contact with the pot meshes).  
173 When  $C = 1.0$ , the *CLogit* model simplifies to the traditional *Logit* model.

174 Estimation of the average test pot size selection with a *CLogit* size selection model requires  
175 finding the values for the parameters  $C$ ,  $W50_c$ ,  $SR_c$ , and  $SP$  that minimize (1) conditioned by  
176 the collected catch data. The ability of this size selection model to describe the experimental  
177 data was evaluated based on the p-value, which quantifies the probability of obtaining by  
178 coincidence at least as big a discrepancy between the experimental data and the model as  
179 observed, assuming that the model is correct. Therefore, the p-value calculated based on the  
180 model deviance and the degrees of freedom should not be  $< 0.05$  for the selection model to  
181 describe the experimental data sufficiently well (Wileman et al. 1996). We tested the ability  
182 of both the *Logit* and the *CLogit* models to describe the experimental data based on estimation  
183 in (1). Competing size-selection models were compared using the Akaike Information  
184 Criterion (AIC) (Akaike 1974), with the lowest-value model subsequently selected.

185 The confidence intervals (CIs) for each size selection curve and the associated selection  
186 parameters were estimated using a double bootstrap method for paired data. This method

187 accounted for between-set variation in the availability of snow crab and pot size selection by  
188 selecting  $m$  sets with replacement from the pool of sets for the specific soak time during each  
189 bootstrap repetition. Within-set uncertainty in the size structure of the catch data was  
190 accounted for by randomly selecting snow crabs with replacement from each of the selected  
191 sets separately. The number of crabs selected from each set was the same as the number of  
192 crabs caught with that longline segment. For each soak time case, we performed 1000  
193 bootstrap repetitions and calculated the Efron 95% (Efron, 1982) CIs for the size selection  
194 curve and the associated parameters. To examine differences between the selection curves,  
195 quantified as the difference (Delta) in retention probability, we used a method based on  
196 separately obtained bootstrap files. This method is described in Larsen et al. (2018) and  
197 Lomeli et al. 2018.

198 *2.3. Meta-analysis of the effect of soak time on size selectivity of the pots*

199 In this section, we describe a meta-analysis that links the point estimates obtained for each  
200 specific soak time to establish models that quantify the effect of soak time ( $t_{soak}$ ) on pot size  
201 selectivity for snow crab. The starting point for this modelling is the standard three-parameter  
202 logistic growth model (Gershenson, 1999):

$$203 \quad g(t_{soak}) = \frac{c_g}{1.0 + b_g \times \exp(-a_g \times t_{soak})} \quad (4)$$

204 Model (4) was applied separately and independently for  $g(t_{soak})$  to  $C$ ,  $W50_c$ , and  $SR_c$ , which  
205 resulted in independent estimates for the sets of parameters  $(a_C, b_C, c_C)$ ,  $(a_{W50_c}, b_{W50_c}, c_{W50_c})$ ,  
206 and  $(a_{SR_c}, b_{SR_c}, c_{SR_c})$ . The rationale for using model (4) as a starting point for the meta-analysis  
207 is that the three selection parameters ( $C$ ,  $W50_c$  and  $SR_c$ ) are all limited in their possible value  
208 ranges, which, contrary to the scenario for simple linear models, is a priori ensured with (4).  
209 Specifically, for the selectivity contact parameter  $C$  the value range should be 0.0 to 1.0,  
210 which in (4) is ensured by fixing the parameter  $c$  at 1.0. In addition to model (4), we also

211 considered the adjusted form (5). Similarly, for  $W50_c$ , we also considered a modified model  
 212 (5). In this case, the parameter  $c_g$  in (4) is fixed to a value  $W50_{cu}$  that is defined based on the  
 213 maximum size of snow crab that geometrically would be able to escape through the netting  
 214 meshes used in the experimental pots applied in the fishing trials. It was more complicated to  
 215 establish an alternative model For  $SR_c$ . As for  $W50_c$ ,  $SR_c$  has an upper boundary, but it is not  
 216 possible to quantify this value a priori. However, it may have a lower boundary value ( $SR_{cl}$ )  
 217 because individual snow crabs with the same CW are expected to differ in carapace  
 218 morphology, which for a specific pot mesh size/shape will lead to between-individual  
 219 variation in escape potential. The above considerations led to the following alternative model  
 220 for the effect of soak time on the pot size selection of snow crab:

$$\begin{aligned}
 C(t_{soak}) &= \frac{1.0}{1.0+b_C \times \exp(-a_C \times t_{soak})} \\
 221 \quad W50_c(t_{soak}) &= \frac{W50_{cu}}{1.0+b_{W50_c} \times \exp(-a_{W50_c} \times t_{soak})} \\
 SR_c(t_{soak}) &= SR_{cl} + \frac{c_{SR_c}}{1.0+b_{SR_c} \times \exp(-a_{SR_c} \times t_{soak})}
 \end{aligned} \tag{5}$$

222 Model (5) for  $SR_c$  is in the form of the common four-parameter logistic growth model  
 223 (Gershensonfeld, 1999).  
 224 Besides models (4) and (5), which explicitly assume a soak time dependency for the  
 225 parameters  $C$ ,  $W50_c$ , and  $SR_c$ , we also consider the possibility that they could be soak time  
 226 independent by investigating the null-hypothesis model (6) with only intercept parameters:

$$\begin{aligned}
 227 \quad C(t_{soak}) &= a_C \\
 W50_c(t_{soak}) &= a_{W50_c} \\
 SR_c(t_{soak}) &= a_{SR_c}
 \end{aligned} \tag{6}$$

228 Choice among models (4) to (6) was based on the lowest  $AIC$  value selecting the one with  
 229 lowest  $AIC$  for  $C$ ,  $W50_c$ , and  $SR_c$  individually. If model (6) results in the lowest  $AIC$ , we  
 230 would conclude that the selection parameters do not depend on soak time. Contrary, if model  
 231 (4) or (5) is the clear choice, we would interpret this as evidence that soak time affects the

232 selection parameter values. Furthermore, to support the conclusion, we estimate (based on  
233 Wagenmakers and Farrell, 2004) the relative likelihood  $L_i$  for each of the other models  $i$   
234 compared to the model with the lowest  $AIC$  value ( $AIC_{min}$ ) by:

235 
$$L_i = \exp\left(-\frac{AIC_i - AIC_{min}}{2}\right) \quad (7)$$

236 The *nls* function in the statistic software package R (version 3.5.0) was applied to estimate the  
237 parameter values in models (4) and (5). The estimations were made based on the data set  
238 consisting of the values for  $t_{soak}$  versus  $C$ ,  $W50_c$ , and  $SR_c$ . Subsequently, the R-functions  $AIC$   
239 and  $Rsq$  were used to obtain  $AIC$  and pseudo  $R^2$  values for the model fits.

240 *2.4. Estimation of optimal size selection*

241 The optimal size selection curve for the 137 mm test pot was assessed using a fall-through  
242 experiment (Herrmann et al., 2009). We tested whether crab (in a sample covering a wide  
243 range of CWs) were geometrically able to pass through a typical mesh of a test pot (Fig. 4).  
244 We selected a mesh near the bottom the pot as we found it most likely that most crabs make  
245 their escape attempts here. In all tests, crab were optimally orientated with respect to the  
246 mesh. A crab that could not pass through the mesh was regarded as retained, whereas a crab  
247 that could pass through was regarded as escaped. Treating these CW-dependent  
248 escape/retention data as size selectivity data and modelling them using the traditional logistic  
249 size selection model (2) with parameters  $W50_f$  and  $SR_f$  provided a fall-through size selection  
250 curve. The advantage of applying this method is that it automatically accounts for the cross-  
251 sectional shape and size of the animal when passing through partially opened meshes.  
252 Considering the cross-sectional shape of a snow crab and the shape of a partially opened  
253 mesh, simply comparing CW to the mesh size does not provide a reliable estimate of the  
254 largest sizes of snow crab that could pass through the pot meshes. Thus, the fall-through  
255 based method offers a simple and more reliable way to estimate optimal size selection. This

256 method has previously been applied to *Nephrops norvegicus* (Frandsen et al., 2010; Brčić et  
257 al., 2018).

258 FIG. 4

259 The obtained fall-through selectivity curves were used to compare the sea trial-obtained size  
260 selection curves to the full utilization of the selection potential of the 137 mm meshes of the  
261 pot netting. Furthermore, the parameter values obtained for  $W50_f$  and  $SR_f$  were used as  
262 estimates for  $W50_{cu}$  and  $SR_{cl}$ , respectively, in (5).

263 **3. Results**

264 *3.1. Optimal size selection*

265 In the fall-through experiment, we used a total of 200 snow crab with CWs between 70 and  
266 148 mm to estimate the optimal size selection (Table 1; Fig. 5) for the 137 mm mesh size  
267 experimental pots.

268 FIG. 5

269 TABLE 1

270 The fall-through results show that the 137 mm mesh size pots have a size selective potential  
271 that fits well with the minimum targeted snow crab size in the Norwegian fishery because  
272  $W50_f$  is close to 100 mm (Table 1). This is further supported by a small  $SR_f$  value (2.23 mm),  
273 which is reflected in the steepness of the size selection curve (Fig. 5).

274 *3.2. Experimental size selection from sea trials*

275 We fished a total of 18 sets of pots each containing between 21 and 42 test pots and between  
276 7 and 21 control pots (Table 2). During the sea trials, the number of crabs caught in the test

277 and control pots varied between 12 and 93 and between 20 and 573, respectively. Four sets  
278 were soaked for five days, four for six days, eight for nine days, and two for fourteen days.

279 TABLE 2

280 Based on the experimental data, the size selection in the pots was estimated for five, six, nine,  
281 and fourteen days of soak time (Fig. 6; Table 3). A comparison of the *AIC* values obtained for  
282 the *Logit* model (2) and the *CLogit* model (3) revealed that the latter better described the  
283 experimental size selectivity data when the soak time was short (five and six days). Thus, for  
284 short soak time it is necessary to use a size selection model that explicitly accounts for the  
285 fact that not all snow crabs make selectivity contact with the meshes in the pot and are not  
286 size selected by them. This finding was confirmed by the shape of the size selection curves,  
287 which show that a fraction of the crabs entering the pots is retained independent of their size  
288 (Fig. 6). When the soak time increased to fourteen days, the *AIC* value was lowest for the  
289 *Logit* model, which indicates that all snow crabs make selectivity contact with the meshes.  
290 This is also corroborated by that the estimated size selection curves reached zero retention for  
291 the smallest sizes of snow crab for these cases (Fig. 6).

292 As the *Logit* model is a special case of the *CLogit* model and because the sum of *AIC* values  
293 over soak time cases was lowest for the *CLogit* model, this model was applied for all cases.  
294 This choice enabled uncertainty estimation for the selectivity contact parameter *C* for nine and  
295 fourteen days of soak time, for which the average *C* was estimated to be 1.0. The p-values  
296 obtained for the *CLogit* model showed that this model could model the experimental data  
297 sufficiently well, as the estimated p-value were  $> 0.05$  (Table 3). Therefore, we were  
298 confident about applying this model to assess snow crab size selection in this study.

299 FIG. 6

## 300 TABLE 3

301 The size selection curve obtained with each soak time with the optimal size selection obtained  
302 based on the fall-through experiment (middle column and rightmost column) are compared in  
303 Figure 6. Results show that the size selection obtained was significantly lower than optimal  
304 when soak time was short. Significant difference was nearly absent only for the longest soak  
305 time (fourteen days). These results show that conical pots reach their full size-selective  
306 potential only when they have had sufficient soak time. A positive correlation was detected  
307 between soak time and  $C$ ,  $W50_c$ , and  $SR_c$ , as indicated by the meta-analysis that modelled the  
308 effect of soak time on these three selection parameters (Fig. 7; Table 4). After five and six  
309 days of soak time, respectively, 15% and 6% of the crabs were estimated to have not made  
310 selectivity contact with the meshes in the pot ( $C$  equal to 0.85 and 0.94). Only after nine–  
311 fourteen days of soak time were nearly 100% of the crabs in the pot been able to make  
312 selectivity contact with the meshes in the pot netting. However, Figure 7 shows that the  
313 quality of the selectivity contact with the meshes also depends on the soak time. The  
314 parameter  $W50_c$  increased with soak time, and even when 100% selectivity contact was  
315 achieved,  $W50_c$  was still below  $W50_f$ , which implies that not all crabs managed to make  
316 selectivity contact for mesh escape. The parameter  $SR_c$  also increased with soak time. The  
317 meta-analysis revealed that both the traditional model (4) and the alternative model (5)  
318 described the trends in the selection parameter values well, as the obtained pseudo  $R^2$  values  
319 were high in all cases. The alternative model (5) performed especially well, with pseudo  $R^2$   
320 values  $> 0.96$  for all parameters. This model also outperformed model (4) for  $AIC$  values, as  
321 they were always lower for model (5). Figure 7 reveals a nearly perfect fit for the trends in the  
322 experimental based point estimates versus soak time, and asymptotic values for all three  
323 parameters (1.0,  $W50_f$ , and  $SR_f$  for  $C$ ,  $W50_c$ , and  $SR_c$ , respectively) seem to make sense. Thus,  
324 model (5) provides a meaningful theoretical basis for understanding the effect of soak time on

325 gear size selection in the snow crab pot fishery. Regarding the null-hypothesis (model (6)), for  
326 each of the selection parameters the *AIC* value is much higher compared to both model (4)  
327 and (5), providing clear support for that soak time affects the snow crab size selection.  
328 Specifically, the null-hypothesis model has little support with a relative likelihood of only  
329  $8.38 \times 10^{-6}$ , 0.15 and 1.16 % for respectively  $C$ ,  $W50_c$ , and  $SR_c$  compared to for the model with  
330 most support (Table 4).

331 FIG. 7

332 TABLE 4

#### 333 4. Discussion

334 In a fishery in which the pots used have the sole purpose of trapping the target species  
335 independent of their size, soak time would only have implications for the catching  
336 performance of the pots and the time required for the target species to enter them. However,  
337 almost every pot fishery has an intended size selectivity process occurring in the pots, which  
338 can involve the netting covering the pots, an escape opening, or other devices (Krouse, 1989;  
339 Treble et al., 1998). Thus, fishing with such pots requires extra time to allow for selection to  
340 occur in addition to the time required for the catching process itself. In most cases, a species  
341 will first enter the pot; only when it attempts to leave the pot will the selection process begin.

342 The selectivity curves obtained for the pots tested during the trials differed significantly  
343 among the soak times tested, which clearly demonstrates that soak time can affect the  
344 selective performance of the pots (Bennett, 1974). In addition, if one considers that an  
345 inefficient selective process in the pots can lead to additional work for the crew onboard and  
346 to unnecessary mortality, one could argue that soak time directly affects the overall efficiency  
347 of crab pots as gear. The results showed that after five days at sea, on average 15% of the  
348 crabs in the pots had not achieved selectivity contact with the pot netting, and only after nine–

349 fourteen days of soak time was selectivity contact with the netting estimated to be 100%  
350 (Table 3). Thus, according to our results the minimum soak time required to exploit the full  
351 selective potential of the conical snow crab pots tested in this study is nine days. From an  
352 economic perspective, nine days of soak time with a corresponding 99.8 % selectivity contact  
353 is more viable than fourteen days of soak time. Moreover, replacing the bait every nine days  
354 over the course of a month of fishing would yield one more deployment with fresh bait.  
355 Despite the positive effect of soak time reported here, earlier studies on other crab species  
356 have shown that soak time can have negative effects on the damage levels of the crab  
357 harvested (Broadhurst et al., 2017). However, this potential effect was not assessed for snow  
358 crab in the present study.

359 Selectivity in pots has not been estimated using a model that considers the parameter  
360 "selectivity contact". We speculated that the parameter selectivity contact could be used as an  
361 indicator for the effect of soak time on the selective properties of pots, and the results in this  
362 study clearly show that this is a good approach. The fit statistics of the *CLogit* model  
363 demonstrated that this model was a good fit to the data. Furthermore, a comparison between  
364 the *AIC* values obtained with the *Logit* and *CLogit* models showed that the latter provided a  
365 better fit to the data, which demonstrated the importance of explicitly considering the  
366 parameter selectivity contact when measuring selectivity in pots. Our study outlines how the  
367 concept of selectivity contact can formally be applied to model and understand the effect of  
368 soak time on the size selectivity of snow crab pot gear. This new approach is not limited to  
369 the snow crab pot fishery, and it can be considered in future pot selectivity studies, especially  
370 in those in which soak time or other alternative variables can influence the ability of the  
371 catch/bycatch species in the pot to make selectivity contact with devices in the gear.

372 In the Barents Sea snow crab fishery, there is no minimum mesh size regulation for the  
373 netting used around the pots. However, the minimum CW for snow crab is 100 mm, and all

374 crabs below this size must be returned to the sea alive and in the best possible condition.

375 Based on experience and knowledge from other fisheries (e.g., the Canadian snow crab

376 fishery), fishermen use 137 mm mesh size single twine netting for snow crab pots, but this is

377 the first study designed to determine if this netting provides a satisfactory selectivity pattern

378 for the Barents Sea snow crab fishery. For the four different soak times tested, the average

379  $W50_c$  was between 89.9 and 94.8 mm, whereas the average  $SR_c$  was estimated to range from

380 3.0 to 8.8 mm. Using a slightly larger mesh size in the netting would increase  $W50_c$  and

381 consequently reduce the sorting work on deck. However, snow crab is a relatively high value

382 species (in Norway it can exceed 16 USD per kg for fishermen) and the  $W50_c$  and  $SR_c$

383 obtained here with 137 mm meshes were satisfactory, so the reduction of labour on deck

384 would not make up for the loss of an important fraction of commercial crabs. Therefore, we

385 conclude that 137 mm is an appropriate mesh size for the netting used in this fishery.

386 Winger and Walsh (2011) conducted a selectivity study in Canada using the same type of pots

387 used in the present study. They compared the selectivity for 140 mm meshes and 152 mm

388 meshes at three different fishing sites. Their average  $W50s$  for the 140 mm meshes ranged

389 from 95.1 to 106.8 mm, which means that at one of the sites their  $W50$  was more than 10 mm

390 bigger than the highest value in our study. Winger and Walsh (2011) noted that there are

391 "*alternative methods for reducing incidental capture of undersized crab, including switching*

392 *to larger mesh sizes and increasing soak time.*" However, the soak times tested in our study

393 were substantially longer than that used by Winger and Walsh, and probably this discrepancy

394 only made the differences in the estimated  $W50s$  between the two studies larger. The

395 differences in the results obtained between these two studies also could be due to potential

396 differences in mesh size/opening angle in the pots or differences in the analysis method used.

397 Winger and Walsh (2011) also estimated  $SR$  values of 16.8–34.5 mm, which are much higher

398 than the ones estimated in this study (Table 2). Sistiaga et al. (2010) demonstrated that by not

399 considering  $C$ ,  $SR$  could be significantly overestimated and  $W50$  could be biased. Thus, the  
400 differences in  $W50$  and  $SR$  values between the present study and that of Winger and Walsh  
401 (2011) also could be due to leaving  $C$  out of their model. If we compare the results obtained  
402 for six days of soak time in our study ( $W50_c$  89.9 mm;  $SR_c$  = 4.4 mm) with the results we  
403 would have obtained for the same data analyzed with the *Logit* model (without considering  $C$ )  
404 ( $W50_c$  = 177.9 mm;  $SR_c$  = 54.6 mm),  $W50$  would have been overestimated by 97% and  $SR$  by  
405 1244%. This example illustrates the importance of considering  $C$  in pot selectivity studies and  
406 provides a potential explanation for the difference between our results and the results from  
407 Winger and Walsh (2011).

408 This study presents a new framework for assessing/investigating size selectivity in pot  
409 fisheries, and it is applicable to other snow crab fisheries and pot fisheries targeting other  
410 species. Our results demonstrate that soak time and its relation to selectivity contact are  
411 important parameters to consider when investigating size selectivity in pots. Furthermore, the  
412 selective potential of the pots tested in this study were not fully utilized until the pots had  
413 soaked for nine days. Finally, our selectivity results show the 137 mm mesh size is adequate  
414 for use in conical pots in respect to the 100 mm minimum landing size of snow crab.

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## TABLES

### Table Legends

Table 1: Size selectivity parameters and fit statistics obtained from the fall-through experiment. Values in parentheses represent 95% confidence limits.

Table 2: For each set and its corresponding soak time, the table specifies the number of test and control pots used and the number of crabs captured in each type of pots.

Table 3: Selectivity parameters and fit statistics for each of the soak time cases presented in Fig. 5.

Table 4: Fit of models (4) and (5) to meta-data for soak time versus  $C$ ,  $W50_c$ , and  $SR_c$ . Values in parentheses represent standard errors for the parameter estimation. \*: not in model. NA: not applicable.

TABLE 1

$W50_f(mm)$	98.57 (98.00–99.27)
$SR_f(mm)$	2.23 (1.37–2.67)
p-value	>0.9999
Deviance	20.83
DOF	67

TABLE 2

Set	Soak time (days)	Number of test pots	Number of control pots	Number crabs in test pots	Number of crabs in control pots
1	14	21	11	13	261
2	14	21	10	13	182
3	6	31	15	61	61
4	6	31	12	90	342
5	6	32	15	19	203
6	6	31	15	20	20
7	9	35	17	19	92
8	9	34	14	19	133
9	9	42	16	93	268
10	9	35	11	40	281
11	9	32	14	15	258
12	9	33	13	14	154
13	9	29	17	12	381
14	9	34	12	25	573
15	5	37	7	30	53
16	5	30	14	41	162
17	5	31	13	55	131
18	5	34	12	79	124

TABLE 3

Soak time (days)	<i>SP</i>	Contact	<i>W50<sub>c</sub></i> (mm)	<i>SR<sub>c</sub></i> (mm)	p-value	Deviance	DOF	<i>CLogit</i> AIC	<i>Logit</i> AIC
5	0.4906 (0.4164–0.6096)	0.8504 (0.7548–1.0000)	89.91 (85.36–99.04)	3.03 (0.10–24.94)	0.3584	96.32	92	737.71	748.59
6	0.7114 (0.4505–0.9723)	0.9379 (0.8389–0.9988)	90.16 (68.35–102.00)	4.07 (0.10–14.25)	0.1937	102.45	91	731.1	786.3
9	0.4174 (0.3156–0.5008)	0.9978 (0.9880–1.0000)	93.05 (89.86–97.31)	8.81 (5.84–12.71)	0.8943	89.15	107	1053.58	1052.96
14	0.2813 (0.1503–0.5000)	1.0000 (0.9918–1.0000)	94.83 (85.08–103.30)	7.62 (0.10–11.98)	0.8783	60.11	74	146.61	144.61

TABLE 4

Selection parameter	Model equation	AIC	Relative likelihood (%)	Pseudo R <sup>2</sup>	Model parameter a	Model parameter b	Model parameter c
<i>C</i>	(4)	-37.66	36.79	0.9998	0.9823 (0.0339)	23.9264 (4.0820)	1.0000 (0.00125)
	(5)	-39.66	100.00	0.9998	0.9829 (0.0209)	23.9893 (2.6013)	*
	(6)	-7.07	8.38×10 <sup>-6</sup>	NA	0.9403 (0.0350)	*	*
<i>W50<sub>c</sub></i>	(4)	9.40	52.25	0.9803	0.1586 (0.1257)	0.1736 (0.0496)	96.6794 (3.0761)
	(5)	8.11	100.00	0.9772	0.1079 (0.0141)	0.1688 (0.01713)	*
	(6)	21.11	0.15	NA	91.988 (1.185)	*	*
<i>SR<sub>c</sub></i>	(4)	15.71	32.14	0.9369	0.9966 (0.8491)	320.5914 (1492.2784)	8.2903 (1.0870)
	(5)	13.44	100.00	0.9647	1.702 (2.094)	5.509e+04 (6.784e+05)	6.011 (0.7293)
	(6)	22.35	1.16	NA	5.883 (1.385)	*	*

## FIGURES

### Figure Legends

Fig. 1: Experimental setup used during the fishing trials.

Fig. 2: Photos showing the meshes used to estimate the size and opening angle of the of the pot meshes used during the trials (a), and the digitalization (b) and modelling (c) process of the netting meshes. The mesh size, opening angle and hanging ratio for each of the meshes measured are also provided.

Fig. 3: Photos showing the emptying of the pots (a), measurement of crab with a calliper (b) and hauling operation onboard (c).

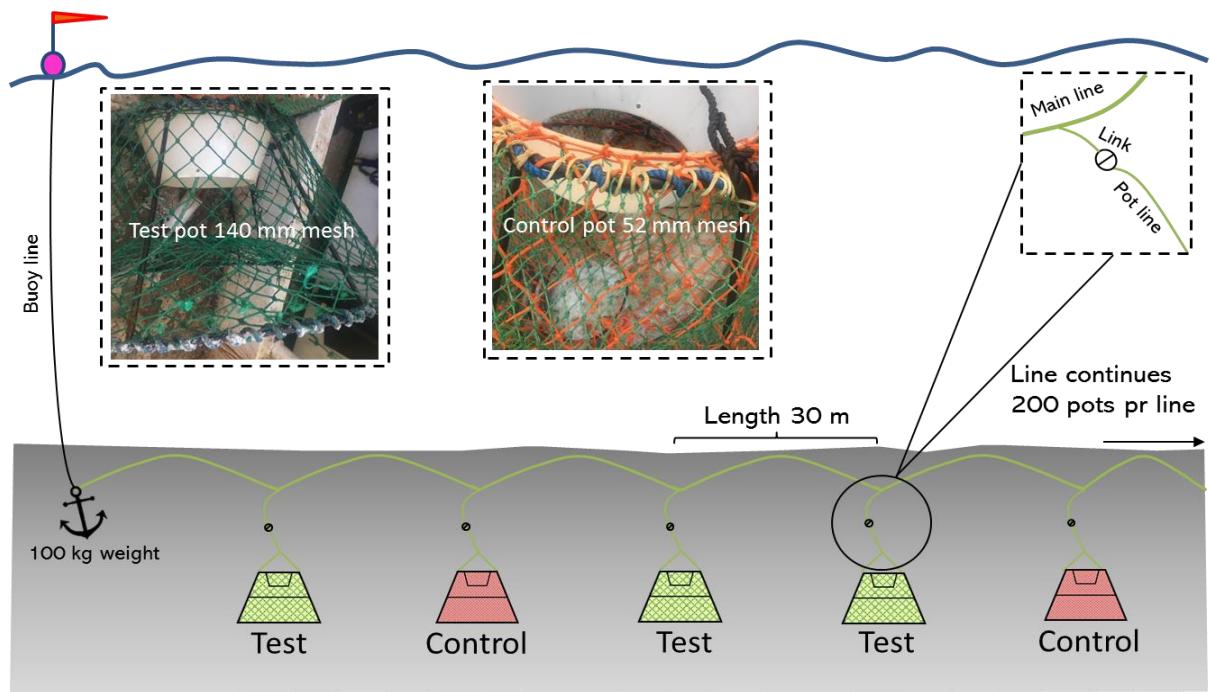
Fig. 4: Illustration of the fall-through experiments carried out to obtain optimal size selection.

Fig. 5: Optimal size selection curve (with confidence intervals) of a pot with 140 mm mesh obtained from the fall-through experiment. The grey stipple curve represents the sizes of crab used in the experiment. The vertical grey line represents the minimum legal target size for snow crab.

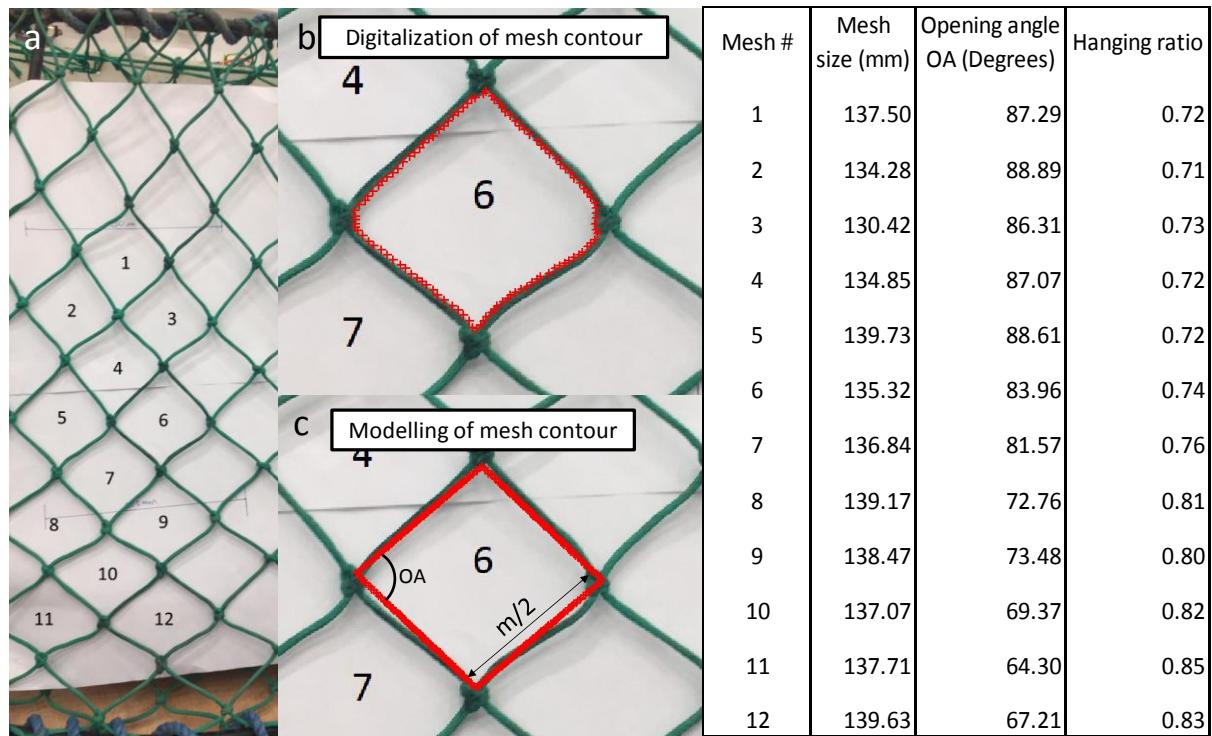
Fig. 6: For the different soak times, the left column shows the size distributions of the crab captured with the test (stippled grey) and control (full grey) pots together with the experimental retention data obtained (round marks) and the *CLogit* curve (black line). The plots in the middle column show the size selectivity curve (full line) with confidence intervals (stippled lines) for each of the different soak time cases (black) compared to the optimal size selectivity curve (grey). The plots in the rightmost column show the difference between the selectivity curve and the optimal selectivity curve for each of the soak time cases (delta plot).

Fig. 7: Effect of soak time on the selectivity parameters  $C$ ,  $W50$  and  $SR$ . Model (4) and (5) are represented by respectively the black and grey curve. Circle marks represent experimental based point estimates with 95% confidence bands. For  $W50_c$  the horizontal stipple line represents the upper band asymptotic value  $W50_{cu} = W50_f$ . For  $SR_c$  the horizontal stippled line represents the lower band asymptotic value  $SR_{cl} = SR_f$ .

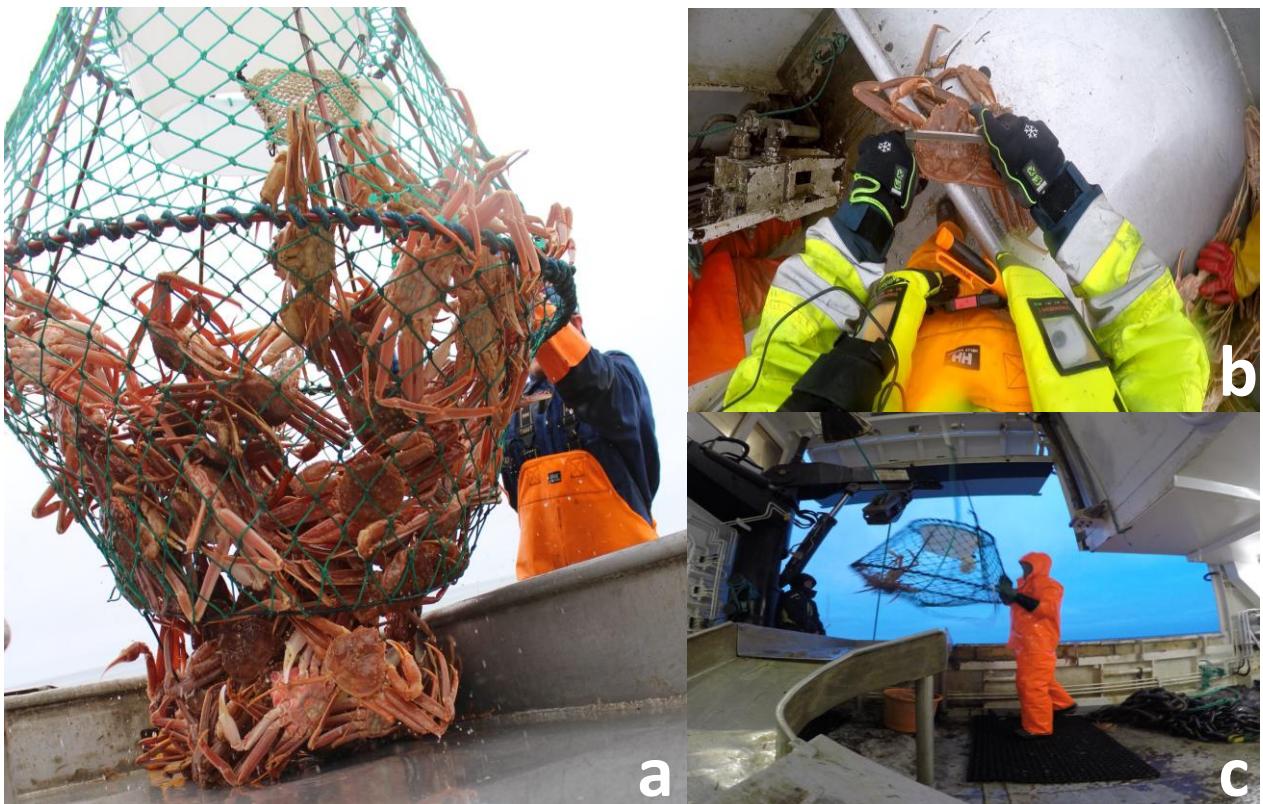
FIGURE 1



**FIGURE 2**



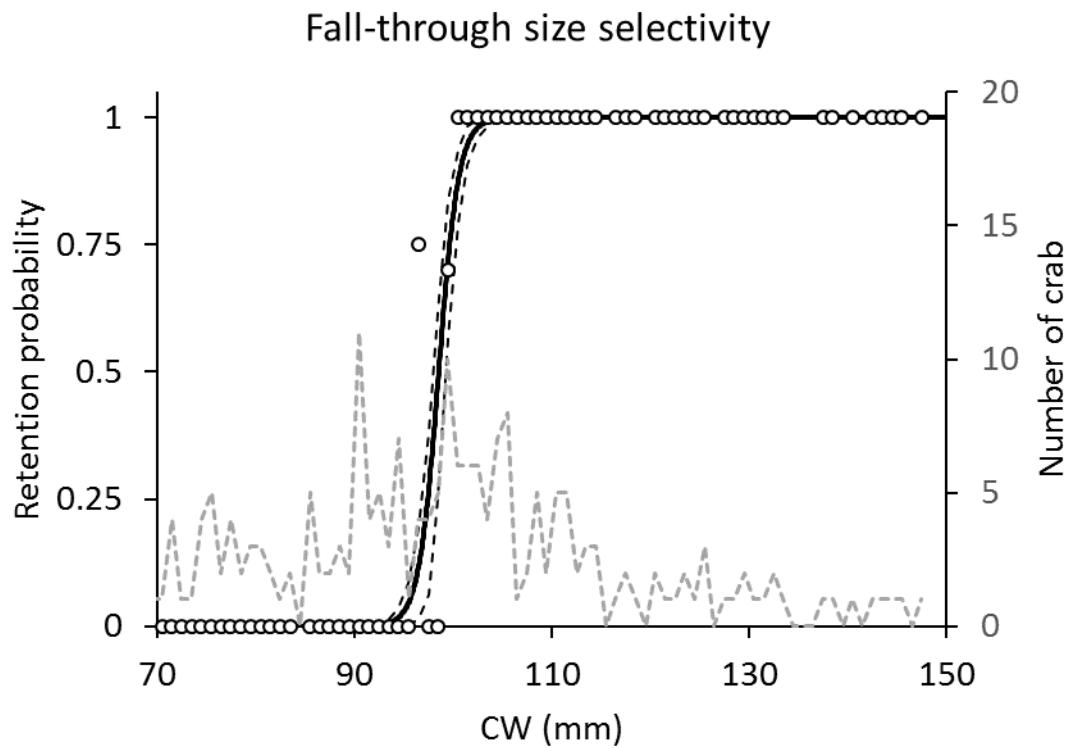
**FIGURE 3**



**FIGURE 4**



FIGURE 5



**FIGURE 6**

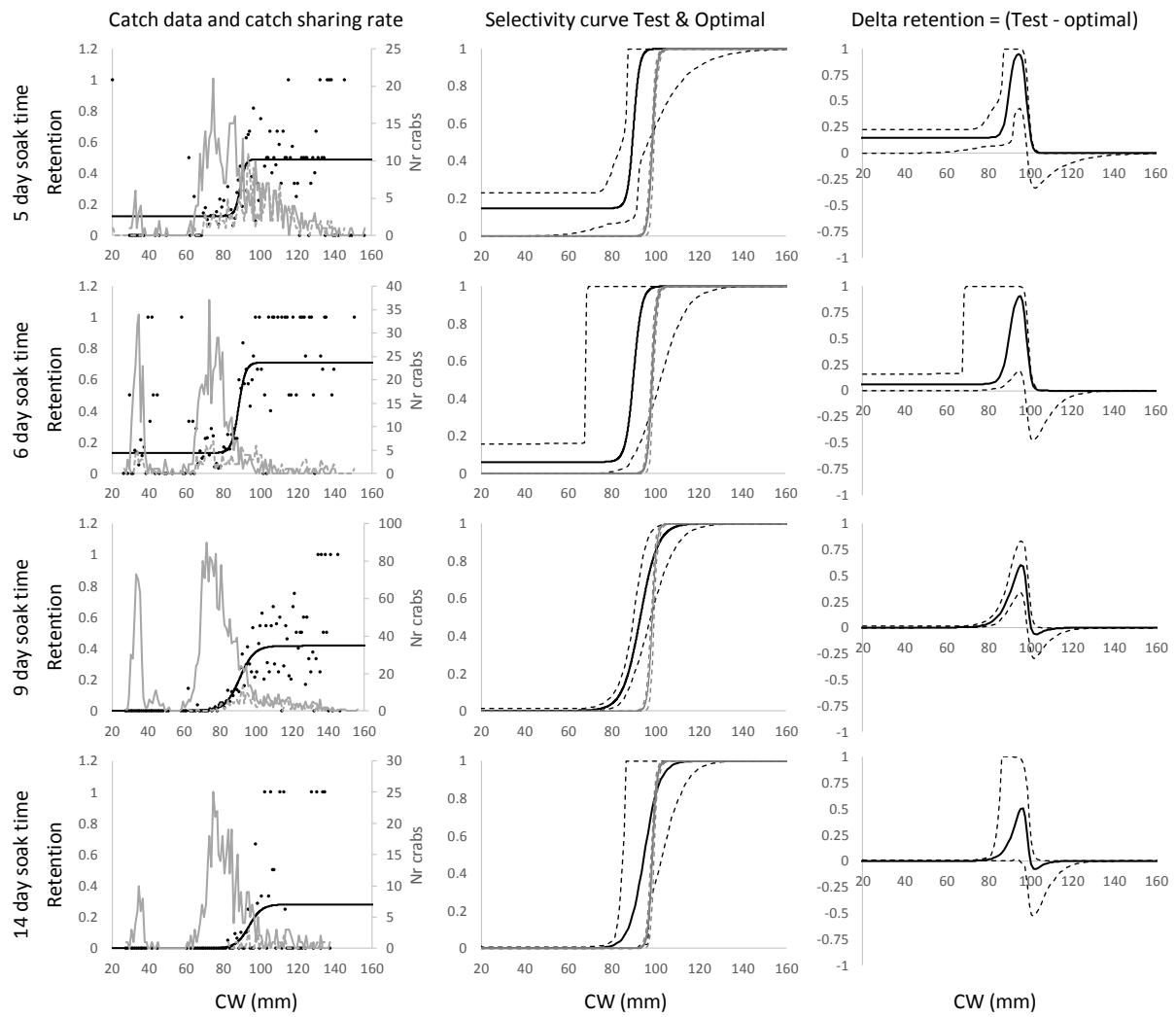


FIGURE 7

